

Complex Lightguide System with a 2D Eye Pupil Expansion and Human Eye Model

Abstract



In order to push the limits in the field of augmented and mixed reality (AR/MR), the need for more complex lightguide systems is constantly increasing. VirtualLab Fusion provides a set of tools which enable the design and modeling of such complex systems. To demonstrate the capabilities of VirtualLab Fusion, an exemplary lightguide system with a 2D exit pupil expander in combination with a slanted grating in the outcoupler is presented. In addition, the point spread function (PSF) and modulation transfer function (MTF) are evaluated by applying a model of the human eye. Finally, an assessment of the lateral uniformity in the eyebox is demonstrated.

Task Description



Light Guide Component



With the *Light Guide Component*, systems with regions with complex shapes can easily be defined. Further, these regions can be equipped with idealized or real grating structures to act as incoupler, outcoupler or exit pupil expanders. More information under:





Eye-Pupil-Expander (EPE) Region



Outcoupling Region



Edit Surface Layout # Name of Region 🥖 Edit Region Region Type Period Polygon Pegion Simple Polygon Regi __E Add Region Outcouple Grating Rectangular Region 453.1 nn X Remove Region Gridded Segmentation < Co Periodic Stack; Stack Period 453.1 nm Cancel Apply Absorption Outside of Region on Surface OK rourie Transforms How to Set Up a Lightguide with Real Grating Structures 🛃 🔞 Validity: 🗸 OK Cancel

Edit Light Guide Component

Coordinate

Systems

Solid

Surface Layouts

Surface Name Edit

1 Plane Surface

2 Plane Surface

Х

Info

Surface layout containing 1 regions.

Surface layout containing 2 regions.

Edit Surface

Edit Surface

Layout

Layout

×

Help

Help

Preview for Outcouple Grating Human Eye Model

Index z-Distance z-Position

0 mm

500 nm

0 mm

2 500 nm

Surface

Plane Interface

Plane Interface

Human Eye Model



In order to evaluate the PSF and MTF accurately, one possible model of the complex optical system that is the human eye is used, represented by a sequence of surfaces and materials. For the configuration, these surfaces and materials can be loaded from VirtualLab's inbuilt catalogs.



Summary – Components...



of Optical System	in VirtualLab Fusion	Model/Solver/Detected Value
1. Source	Plane Wave source	Truncated Ideal Plane Wave
2. Incoupler	Idealized grating in Rectangular Region	Idealized Rayleigh Matrices
3. Eye Pupil Expansion	Idealized grating in Polygonal Region	Idealized Rayleigh Matrices
4. Outcoupler	Slanted grating in Rectangular Region	Fourier Modal Method (FMM)/RCWA
5. Eye	Lens System Component, PSF&MTF Detector, Camera Detector, Uniformity Detector	Local Plane Interface Approximation & energy density measurement

Field at Different Positions/Planes in the System

and in the focal spot. 2 19: After Lightguide 20: Focal Spot Chromatic Fields Set Chromatic Fields Set 30 4 3 20 \sim 10 -۲ [mm] Y [Jum] 0 0 Full propagation through the lightguide, 5 -10 including complex 2 -20 grating configurations 'n and diffraction -30 efficiency calculations at real gratings by FMM 2 3 4 -1 -4 -3 -2 0 1 -40 -30 -20 -10 0 10 20 30 is performed in a few X [µm] X [mm] seconds! 1 field after lightguide 2 field in focal plane

VirtualLab Fusion can calculate the electromagnetic field after the lightguide

MTF & PSF – Calculation

here Depending on the user's choice, the MTF & PSF can be calculated either coherently or incoherently, according to the coherence properties of the actual light source.





Lateral Uniformity Evaluation after the Lightguide

Uniformity Det	Detector Window and Resolution Detector Function
Coordinate Systems	Coherence Parameters Summation Type Coherent Summation V
Position / Orientation	Pupil Parameters Shape Elliptical Rectangular Size 1.2 mm X 1.2 mm Pupil Positions from Central Rays Pupil Positions on Grid
Fr CO	Shape, size and number of pupils nsidered for evaluation can be defined. More information under: Uniformity Detector for Lightguide

Note: The dashed circles are just for illustration of the pupils, these are not shown in the simulation result.

result of Uniformity Detector		Value for Pu				
			Value for Pu			
						Value for Pu
						Value for Po
						Value for Pu
						Value for Pu
						Value for Po
		result	of Can	nera Dete	ector	Value for Pr
fter	Lightguide	:				Value for Po
	-		Chromatic Fields S	et		Value for Po
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	ω -					Value for P
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		-4 -3	-2 -1 0 X [m	1 2 m]	3 4	
			-			

Value for Pupil around (-3.97 mm; -4.15 mm)	0.0122 (V/m) ²
Value for Pupil around (-3.97 mm; -1.45 mm)	0.000566 (V/m) ²
Value for Pupil around (-1.27 mm; -4.15 mm)	0.0109 (V/m) ²
Value for Pupil around (-3.97 mm; 1.25 mm)	0.000533 (V/m) ²
Value for Pupil around (-1.27 mm; -1.45 mm)	0.00038 (V/m) ²
Value for Pupil around (1.43 mm; -4.15 mm)	0.00943 (V/m) ²
Value for Pupil around (-3.97 mm; 3.94 mm)	0.000282 (V/m) ²
Value for Pupil around (-1.27 mm; 1.25 mm)	0.000375 (V/m) ²
Value for Pupil around (1.43 mm; -1.45 mm)	0.000317 (V/m) ²
Value for Pupil around (4.12 mm; -4.15 mm)	0.00797 (V/m) ²
Value for Pupil around (-1.27 mm; 3.94 mm)	0.000227 (V/m) ²
Value for Pupil around (1.43 mm; 1.25 mm)	0.000312 (V/m) ²
Value for Pupil around (4.12 mm; -1.45 mm)	0.000264 (V/m) ²
Value for Pupil around (1.43 mm; 3.94 mm)	0.000189 (V/m) ²
Value for Pupil around (4.12 mm; 1.25 mm)	0.00026 (V/m) ²
Value for Pupil around (4.12 mm; 3.94 mm)	0.000158 (V/m) ²
Minimum	0.000158 (V/m) ²
Maximum	0.0122 (V/m) ²
Uniformity Error	97.4 %
Arithmetic Mean	0.00277 (V/m) ²
Standard Deviation	0.0172 (V/m) ²

VirtualLab Fusion Technologies





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