

UseCase.0011 (1.0)

Positioning & Orientation of Elements

Keywords: positioning, orientation, element, component, angle, basal, isolated, input channel, output channel, coordinate system, origin, separate, tilt, shift, offset

Description

- The light path diagram (LPD) is used to define the radiation of sources, structures of optical elements and detectors.
- The user defines path of the light through optical systems.



 This use case explains how the positioning and orientation of the light path elements within the light path diagram has to be used.

Light Path Diagram vs Laboratory

- Optical devices in real laboratory:
 - Light sources
 - Optical components
 - Detectors or optical effect of light
- Elements of light path diagram:
 - Radiation source models (called light source in VirtualLab)
 - Real optical components
 - Ideal optical components
 - Detectors
 - Analyzers
- A component in laboratory does not necessarily be expressed by one component in light path diagram.

Light Path Elements



- Light path elements can have multiple input and output channels.
- Input and output channels define axes that correspond to the optical axes used for the system setup.

Light Path Elements



- Input channels correspond to different incident light distributions coming from different directions/components.
- Output channels correspond to different output light distributions propagating to different directions/components (for example reflected and transmitted light).

Light Path Elements



- Axes of channels are predefined or may change depending on parameters of a component.
- Each component 'knows' its orientation relative to the axes of the channels.

Definition of Element Position



- The axis of one output channel of a component is connected to an axis of an input channel of another component or detector
- All connected components and their corresponding channel axes define the optical axes of the system.

Definition of Element Position



- Light path elements have absolute positions.
- Origin of absolute coordinate system is defined by light source.
- Tilts of light source are not possible since it is the origin.
- For the positioning of elements relative and/or absolute distances/angles can be used.

Definition of Element Position



- Every component defines multiple reference points per channel.
- Relative positions of components are measured between reference points.

Positioning/Orientation Rules

- Distances away from an element are always positive.
- The position/orientation of an element can be done directly in the Edit Dialog of the element or with the help of Coordinate Break elements.
- For each element type there are defined reference points that can be selected. (Only the programmable component allows arbitrary reference points.)



CSs for Orientation/Positioning

Delta Z

The positioning and orientation of a consecutive element is done by setting x, y, z shifts of the origin of the input channel Coordinate System (CS) in relation to the CS of the output channel of the last element. Also the tilt angles are in relation to the output CS of the last element. (Different angle definitions can be used.)

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Used Directions of Output Channels

- The reflective output channel takes care of the reflected part of the input light; analogously for the transmitting output channel and the transmitted light.
- But there is no fixed relationship between the direction of the z-axis of the channel's coordinate system and the main direction of the propagating light.
- The direction of the reflection channel is calculated according the law of reflection regarding the xy plane of the coordinate system of the input channel. This is done in order to have a good first guess for the propagation direction of the reflected light in many cases.
- For standard systems these automatically considered directions are reasonable and ensure little computational effort. For special cases other directions might be more useful and have to be defined with the help of the Coordinate Break element.

Automatic Directions of Output Channels



It is also possible to handle position and orientation settings with the help of the so-called Coordinate Break element. It provides compatibility to Zemax setups using its Coordinate Break Elements.



Coordinate Break Element

Edit Identity Operator	×
Basal Positioning	Isolated Positioning Position Information (Absolute)
Position this Ele	ement's Input Axes with Respect to
Geometry / Reference Ele	ment 1: Spherical Lens There Absolute
Channels Reference Out	Positioning Data
The lefence Ou	
Relative Distan	ice on Axis
Position / Delta Z Orientation	15 mm
T Lateral Shift	
Delta X	0 m Delta Y 0 m
Function Inclination / Ro	tation
Orientation [Definition Type Spherical Angles
i -Z-	Axis Direction Definition
	Angle / Axis Value
	Theta (Spherical) 🔻 0°
Swap 🖈	Phi (Spherical)
Order	
Br	ntation About 7-Avis
₩ [™]	Z-Axis Botation Angle
	OK Cancel Help

- Coordinate Breaks allow the introduction of an offset or tilt independent of a real optical element.
- Position and direction of the optical axis can be changed between two optical elements.



- The following slides will show the possible settings for the positioning and orientation of elements using the example of a spherical lens component.
- All settings are comparable for ideal components and detectors.

Edit Spherical Lens	×
Residue (Construction) Position / Orientation Structure / Function Propagation	Internal Coordinate System Reference Points Optical Channels
	OK Cancel Help

Definition of reference points for distance definition

Edit Spherical Lens	
Geometry / Channels Channels Position / Orientation Structure / Function	Internal Coordinate System Reference Points Optical Channels Channel to Show Axis Direction and Orientation Default Position of Channel's Coordinate System The Transmission Output Axis is identical to the axis of symmetry. The associated coordinate system is not rotated to the Internal Coordinate System. Initially, its origin is located at the second plane of maximum extension.
	Origin (Reference Point) Back Vertex
	Homogeneous Channel Medium Standard Air in Homogeneous Medium Contemporation of the term of term
	OK Cancel Help

Selection of reference point and medium for each channel

- Selection of channel
 - Selection of reference point
 - Homogeneous medium containing the channel

Edit Spherical Lens		
1	Basal Positioning Isolated Positioning Position Information (Absolute)	
	Position this Element's Input Axes with Respect to	
Geometry / Channels	Caussian Wave Enter Absolute	
	Reference Output Channel	
	Relative Distance on Axis	
Position / Orientation	Delta Z 0 m	
	Lateral Shift	Ι
	Delta X 0 m Delta Y 0 m	
Structure / Function		
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	Z-Avis Direction Definition	
	Angle / Axis Value	
	Swan	
	Order	
	Potetion About 7 Avia	
	Z-Axis Rotation Angle 0°	
I		
	OK Cancel Help	
[L		

- Basal and isolated positioning as well as information about the absolute position in optical system
 - Button opens edit dialog for position settings in absolute coordinate system.
 - Distance along z-axis (optical axis) and lateral offset relative to previous component

Light Path View (Positioning)





Edit Spherical Lens	
Basal Positioning Isolated Positioning Position Information (Absolute)	
Position this Element's Input Axes with Respect to	
Geometry / Reference Element 0: Gaussian Wave Enter Absolute	
Channels Reference Output Channel -	
Relative Distance on Axis	
Position / Delta Z 0 m	
Lateral Shift	
Delta X 0 m Delta Y 0 m	
Structure / Function	
Inclination / Rotation	
Orientation Definition Type Spherical Angles	
Propagation	
Angle / Axis Value	
Theta (Soherical)	
Swap Phi (Spherical) 0°	
Botation About Z-Axis	
Z-Axis Rotation Angle 0°	
Cancel Help	

Component tilt with angle definitions:

- Spherical angles
- Cartesian angles
- Direction angles
- Eulers angles
- Arbitrary sequence of axis rotations.

Spherical Angles



Spherical angles are typically used in grating theory.

Cartesian Angles



Cartesian angles are rotations around the x- and y- axis.

Direction Angles



Direction angles expresses a tilt by direction cosines.



Euler angles



Arbitrary Sequence of Axis Rotations



Arbitrary sequence of rotations around the coordinate axis

Edit Spherical Lens		×
	Basal Positioning Isolated Position	ning Position Information (Absolute)
Geometry / Channels	Position and Orientation Use Isolated Translation	☑ Use Isolated Orientation
Į,	Order of Steps Translation Parameters Orient	1: Translation -> 2: Orientation
Position / Orientation	Translation Directions Axes Selection	Axes of the Internal Coordinate System
Structure /	Translation Values Delta X	0 m
	Delta Y Delta Z	0 m
Propagation		
	×	OK Cancel Help

 Introduction of an additional offset relative to the basal position of the element.

Edit Spherical Lens	×
Geometry / Channels Position / Orientation Structure / Function Propagation	Basal Positioning Isolated Positioning Position Information (Absolute) Position and Orientation Isolated Translation Isolated Orientation Order of Steps 1: Translation > 2: Orientation Image: Content of Rotations Reference Point to be Erront Vertex Isolated Orientation Angles Orientation Definition Type Spherical Angles Image: Content of Point Isolated Orientation Definition Angle / Axis Value Image: Content of Content of Content of Content of Point Image: Content of
	OK Cancel Help

- Introduction of an additional tilt relative to the basal position of the element.
- This requires also the determination of an reference point for the rotation (pivot point).

Basal vs Isolated Position/Orientation: Shift



Original System

Shift in y-direction

System with Shifted Lens via Basal Positioning Settings

System with Shifted Lens via Isolated Settings

Basal vs Isolated Position/Orientation: Tilt



Reference Points for Isolated Tilt



Order of Isolated Positioning Steps





- VirtualLab allows the specification of tilts and offsets of optical components and detectors.
- Basal and isolated positioning can be used.
- Coordinate Break element allows change of direction and position of the optical axis.