

#### Design and Rigorous Analysis of Non-Paraxial Diffractive Beam Splitter

#### Abstract



The direct design of non-paraxial diffractive beam splitters is still a challenge. Due to the quite large diffraction angle, the feature size of the element become similar to the wavelength of light. Hence, the typically used paraxial modeling approaches become inaccurate and rigorous techniques are required. Thus, in this example, the iterative Fourier transform algorithm (IFTA) and the thin element approximation (TEA) are used for the initial design of the diffractive optical element (DOE), and the Fourier modal method (FMM) also known as rigorous coupled wave analysis (RCWA) is applied afterwards for a rigorous performance evaluation, including the investigation of merit function changes in the case of height variations.

#### Task

- initial design of a diffractive 1:7x7 beam splitter using a paraxial approximation (TEA) for the structure design part
- performance analysis and further optimization of uniformity and influence of zeroth order by using rigorous analyses (FMM/RCWA)



#### Simulation & Setup: Introduction of Tools & General Process Overview

#### **Connected Modeling Techniques: Diffractive Beam Splitter**



#### Available modeling techniques for microstructures:

Methods	Preconditions	Accuracy	Speed	Comments	
Functional Approach	-	low	very high	diffraction angles acc. to grating equation; manual efficiencies	
Thin Element	smallest features > $\sim 10\lambda$	high	very high	inaccurate for larger NA and thick elements; x-domain	
(TEA)	smallest features < $\sim 2\lambda$	low	very high		
Fourier Modal Method (FMM)	period < ~ $(5\lambda \times 5\lambda)$	very high	high	rigorous solution; fast for structures and periods similar to	
	period > ~ ( $15\lambda \times 15\lambda$ )	very high	slow	the wavelength; more demanding for larger periods; k-domain	



In this example we want to investigate the difference between the **Thin Element Approximation (TEA)** and the **Fourier Modal Method (FMM)** for a real beam splitter.

## Via Configuration Assistant & IFTA to a Phase Design



## **Convert Transmission Function To Structure**

Structu

Structure

- The resulting transmission function can be converted into a structure profile by applying Structure Design from the Design ribbon.
- For this conversion, the thin element • approximation (TEA) is used. The resulting height profile is therefore proportional to the initial phase function.
- VirtualLab Fusion delivers the calculated • structure data in the form of already preset elements of an optical setup.
- To use the designed structure in different ٠ simulation scenarios either the sampled surface or the specified stack needs to be taken from within the component.

Structure Design	Diffractive Optical Element (DOE) (for Field Plane Surface Tracing) Edit Diffractive Optical Element (DOE) Component I Solid Channel Operator Operator Specified by O Complex Surface Response Stack Systems Grating Stack Sampled Grating Stack Sampled Grating O on Front Side of Base Surface On Back Side Of Base Surface Of Back Side Of	×
	Edit Stack × racy Factor 1 1 1 Index z-Distance z-Position Surface Subsequent Medium Com 1 0 mm 0 mm Sampled Surface Air in Homogeneous Enter your commer	
	Validity: Add Insert Delete Periodicity & Aperture OK Cancel Hel Stack Period is Dependent from the Period of Surface vitih Index Stack Period Tools IV OK Cancel Help OK Cancel Help	p

### **Diffractive Beam Splitter Surface**



For further evaluation, a *General Grating Optical Setup is used,* where the previously saved stack is loaded. The *Grating Optical Setup* offers unique tools, components and analyzers to further investigate the characteristics and performance of a given periodic structure.

dit General Grating	g Component	×
Coordinate Systems	<ul> <li>1D-Periodic (Lamellar)</li> <li>Base Block</li> <li>Base Block Medium</li> <li>Fused Silica in Homogeneous Medium</li> <li>Load</li> </ul>	2D-Periodic      Edit
Position / Orientation	Thickness	10 mm
Structure Propagation	Stacks Use Stack on First Surface Catalog Entry DOE 2 Coad Catalog Edit No rotation about 22	Edit Stack × YOOR Seg z v Index z-Distance z-Position Surface Subsequent Medium Com
	Stack	E C C C C C C C C C C C C C C C C C C C
	Tools 🎁 🗸 Common Pe	Validity: Add Insert Delete
Validity: 🕑	Preview Wavelength 632.8 nm	• Periodic        Stack Period is        Dependent from the Period of Surface        with Index          Stack Period          7.2 μm           7.2 μm
		Tools 👔      OK Cancel Help

### **Diffractive Beam Solvers – TEA & FMM**



- The General Grating Component offers the Thin Element Approximation (TEA) and the Fourier Modal Method (FMM) as solvers to model the given grating.
- The *TEA* usually generates results faster but may have accuracy issues, if the structures are smaller than about 5 to 10 times the wavelength.
- The *FMM* allows for a rigorous simulation but requires a higher numerical effort.

Edit General Grating Component					
Coordinate	Con	nponent Propagation For For Thi	urier Modal Method urier Modal Method n Element Approximation	✓ ✓ Edit	
Systems		Interface	Stack	Medium	
2	1	Plane Interface Fourier Modal Met 🖂	7x7_BeamSplitter_#2 Fourier Modal Met ~	Fused Silica in Homogen Fourier Modal Met \vee	
Position / Orientation	2	Plane Interface Fourier Modal Met 🖂	Stack	Fused_Silica in Homogen	
Structure					
Propagation					

# **Grating Order & Programmable Grating Analyzer**



#### **Designs & Evaluation Results**

- Phase Function Designs
- Structure Designs
- TEA Evaluation
- FMM Evaluation
- Height Scaling Check (for Optimization/Tolerancing)

### **Phase-Only Transmission Design**

In this step, the iterative Fourier transform algorithm (IFTA) is applied for a binary phase-only transmission design.



VirtualLab Fusion offers the *Multiple Run* document, which allows the user to perform an arbitrary number of designs with an option to filter the results according to certain criteria.

The following three results were obtained this way; we will evaluate them further.



#### ...

#### **Element's Features**

- period size: 7.2nm (~11.4 $\lambda$ )
- smallest structure size (sampling distance): 400nm (~0.6λ)

#### **Structure Design**

Next, the thin element approximation (TEA) is used for the structure design of the height profile, i.e., under a paraxial assumption (the phase function and the resulting height profile are therefore proportional).



## **Performance Evaluation with TEA**

Now, the obtained microstructure is evaluated by applying TEA, which was also used for the structure design and is accurate under paraxial conditions.





Merit Function	Design #1	Design #2	Design #3
Total Efficiency	66.1%	65.7%	69.5%
Average Efficiency (of use orders)	1.4%	1.3%	1.4%
Zeroth Order Efficiency	1.4%	1.4%	1.5%
Zeroth Order Error*	4.3%	5.7%	6.4%
Uniformity Error**	28.7%	41.3%	27.1%
Uniformity Error without 0th Order	28.7%	41.3%	27.1%

\* Zeroth Order Error =  $\frac{\text{Zeroth Efficiency} - \text{Average Efficiency}}{\text{Zeroth Order Error}}$ 

**Average Efficiency** 

Max. Efficiency – Min.Efficiency \*\* Uniformity Error = Max. Efficiency + Min.Efficiency

From the results obtained by TEA, system #1 and #3 look roughly similar. Design #2 shows significantly larger uniformity errors. Furthermore:

- For all three design the 0<sup>th</sup> order never stands out.
- Design #1 has the lowest zeroth order error.
- Design #3 has the lowest uniformity error.

But these values are not expected to be accurate, since the assumptions of the paraxial model do not hold.

 $\rightarrow$  A rigorous analysis is urgently required.

### **Performance Evaluation with FMM**

After the investigation with TEA, a rigorous analysis by using FMM is performed.





Merit Function	Design #1	Design #2	Design #3
Total Efficiency	70.5%	70.2%	73.8%
Average Efficiency (of use orders)	1.4%	1.4%	1.5%
Zeroth Order Efficiency	8.0%	2.9%	2.3%
Zeroth Order Error*	453.3%	100.4%	55.6%
Uniformity Error**	82.8%	56.8%	42.4%
Uniformity Error without 0 <sup>th</sup> Order	44.1%	46.3%	42.4%

\* Zeroth Order Error = Zeroth Efficiency – Average Efficiency

Average Efficiency

Max. Efficiency – Min.Efficiency \*\* Uniformity Error = Max. Efficiency + Min.Efficiency

- Rigorously evaluated (FMM), it turns out that design #1 actually produces the strongest 0<sup>th</sup> diffraction order, resulting in a very poor uniformity.
- The designs seem to have a comparable Uniformity Error without 0<sup>th</sup> Order.
- Therefore, an optimization to minimize the *Oth Order Error* may improve the performance distincly.

## **Further Analyses (Post-Optimization, Tolerancing)**

- A scaling of the height profile has a strong influence on the 0<sup>th</sup> order's efficiency.
- This can be used to correct an undesired efficiency of the zeroth order and thus also to improve the uniformity.
- The *Parameter Run* document is the best suited tool to perform such investigations.
- At the same time, such simulations with varied heights may serve as tolerance investigation.



#### **Further Optimization – Zeroth Order Tuning Design #1**



- It turns out that simple height scaling does not sufficiently reduce the high value of the *Zeroth Order Error* of design #1.
- It should be noted, that while the goal of height scaling is the reduction of the 0<sup>th</sup> order, the uniformity error and other merit functions are also affected, albeit to a lesser extent.

Comparison between initial vs post-optimized design aiming at low Uniformity Error

Merit Function	Design #1	with scaling factor 1.08
Total Efficiency	70.5%	67.87%
Average Efficiency (of use orders)	1.4%	1.4%
Zeroth Order Efficiency	8.0%	6.4%
Zeroth Order Error	453.3%	362.6%
Uniformity Error	82.8%	80.6%
Uniformity Error without 0th Order	44.1%	47.4%

### **Further Optimization – Zeroth Order Tuning Design #2**



- The 0<sup>th</sup> order of design #2 is also distinctly higher but not as dominant as for design #1. Here a scaling might show more promising results.
- On the other hand, the height scaling won't optimize the merit function *Uniformity Error without 0<sup>th</sup> Order*. Hence in general, the best that can be expected, is a similar overall uniformity of all working orders including the 0<sup>th</sup> order.
- Usually, the other merit function values get worse, but not always. In any case, it is up to the optical engineer to decide which compromise is best.

Comparison between initial vs post-optimized design aiming at low Uniformity Error

Merit Function	Design #2	with scaling factor 1.02
Total Efficiency	70.2%	69.4%
Average Efficiency (of use orders)	1.4%	1.4%
Zeroth Order Efficiency	2.9%	2.1%
Zeroth Order Error	100.4%	45.2%
Uniformity Error	56.8%	47.0%
Uniformity Error without 0th Order	46.3%	47.0%

#### Further Optimization – Zeroth Order Tuning Design #3



- For this design, the height scaling shows no further improvement of the uniformity error.
- Nevertheless, a variation of the height scaling is still advisable, as it provides information on how sensitive the design is with respect to possible tolerances of the etching depth. In particular, we see that a larger structure height will slightly decrease the overall uniformity but allows much more stable results.

Comparison between initial vs post-optimized design aiming at low Uniformity Error

Merit Function	Design #3	with scaling factor 1.025
Total Efficiency	73.8%	72.9%
Average Efficiency (of use orders)	1.5%	1.5%
Zeroth Order Efficiency	2.3%	1.4%
Zeroth Order Error	55.6%	1.7%
Uniformity Error	42.4%	42.9%
Uniformity Error without 0th Order	42.4%	42.9%

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