

SPIE PW 2018, Paper 10518-63

# Non-paraxial Diffractive and Refractive Laser Beam Shaping

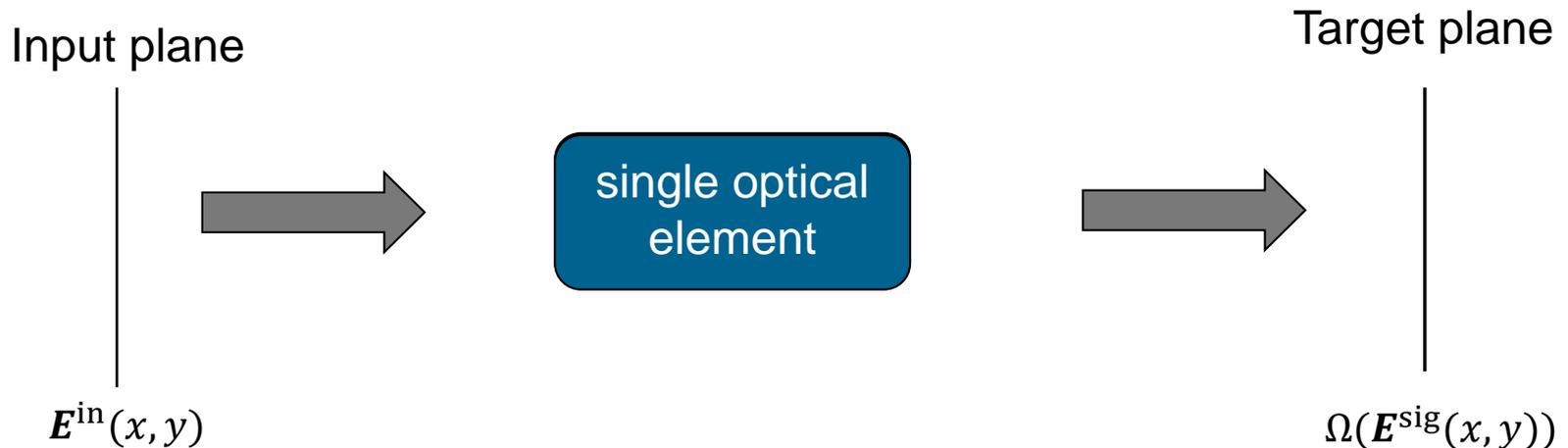
Liangxin Yang<sup>1</sup>, Roberto Knoth<sup>2</sup>, Christian Hellmann<sup>3</sup>, Frank Wyrowski<sup>1</sup>

1. Friedrich-Schiller-Univ. Jena (Germany);
2. LightTrans International UG (Germany);
3. Wyrowski Photonics UG (Germany)

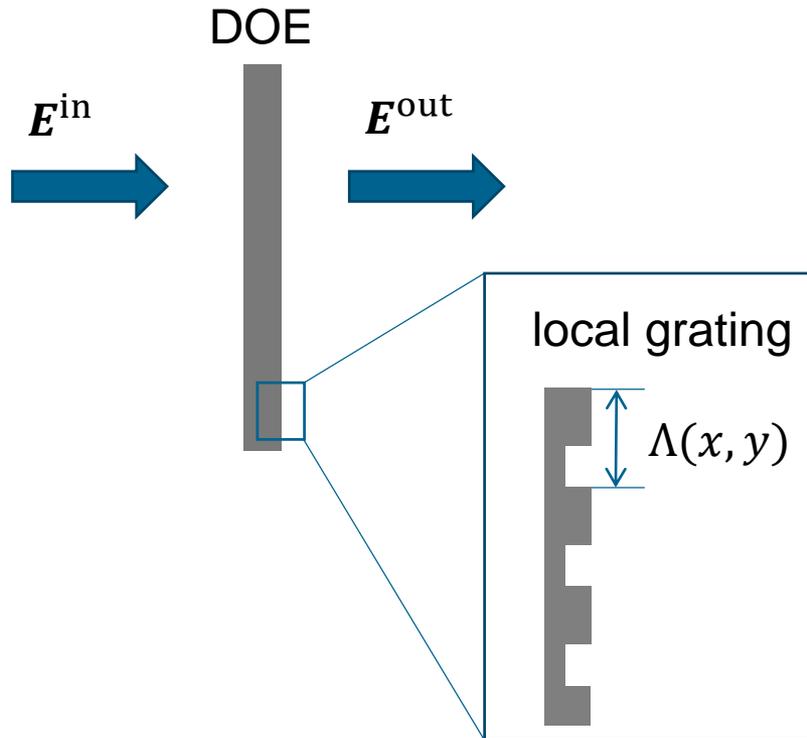
# Introduction

In general, an optical design problem can be described as followed:

- given input field  $\mathbf{E}^{\text{in}}(x, y)$
- design an optical system:  $\mathbf{E}^{\text{in}}(x, y) \rightarrow \mathbf{E}^{\text{sig}}(x, y)$
- obtain a detector function  $\Omega(\mathbf{E}^{\text{sig}}(x, y))$

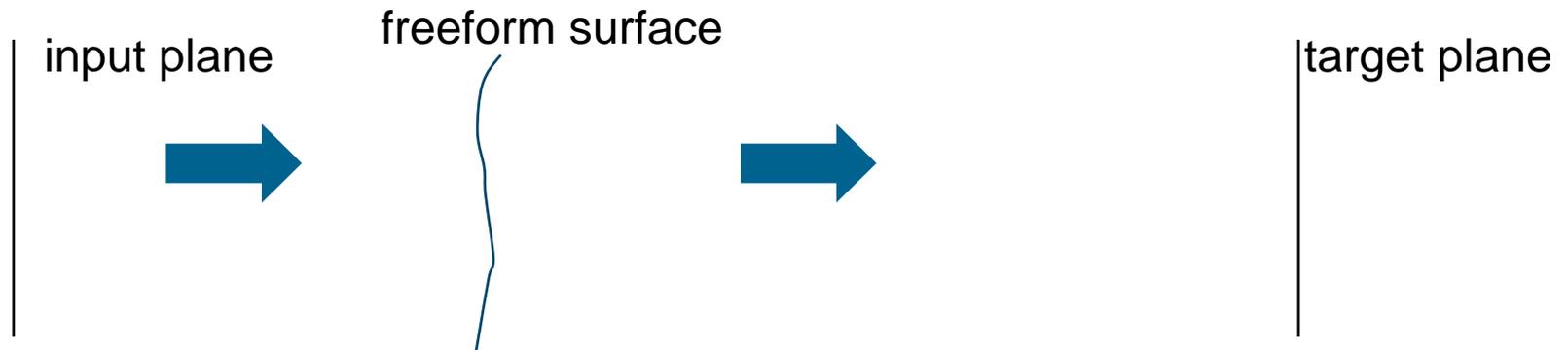


# Modelling of Diffractive Optical Element



The Fourier Modal Method (FMM) is a rigorous technique to model the electric field propagation through a grating.

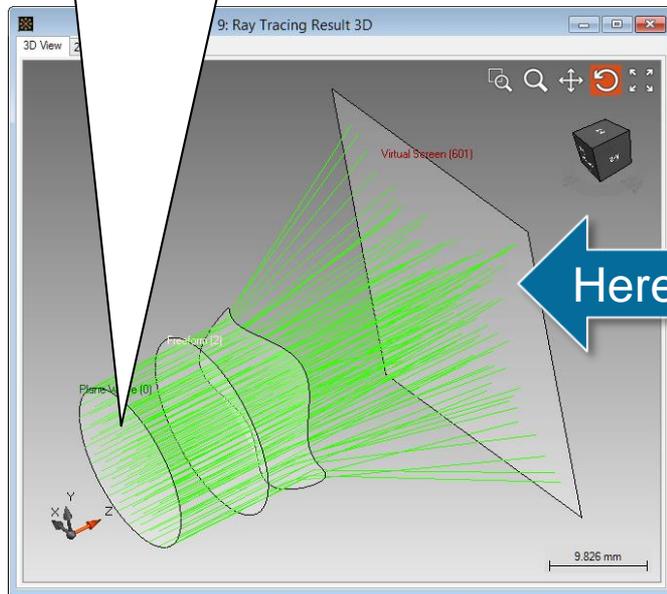
# Modelling of Refractive Optical Element



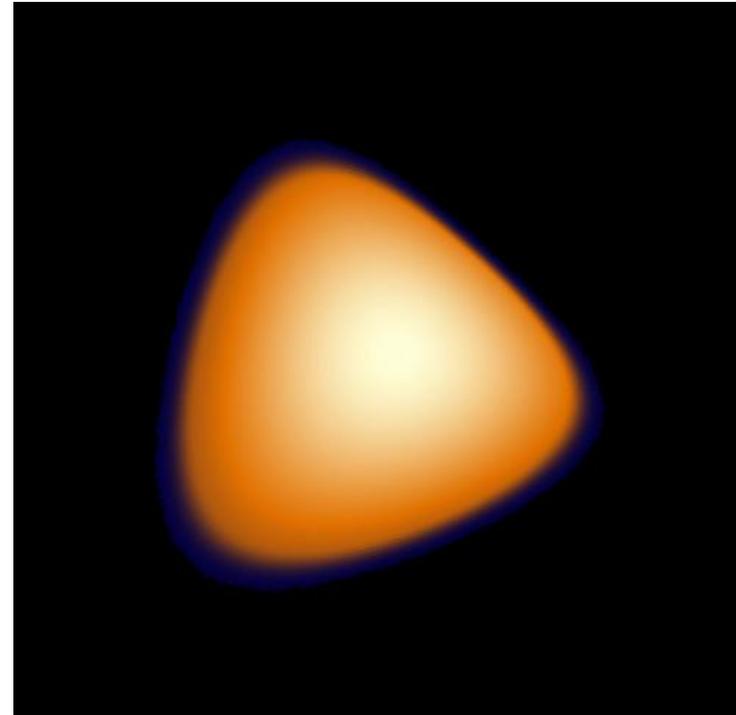
“Local plane-interface approximation“ a method for propagating electromagnetic fields through the smooth surface of an optical system.

# Modelling of Refractive Optical Element

Input: Gaussian beam  
Diameter 10 mm

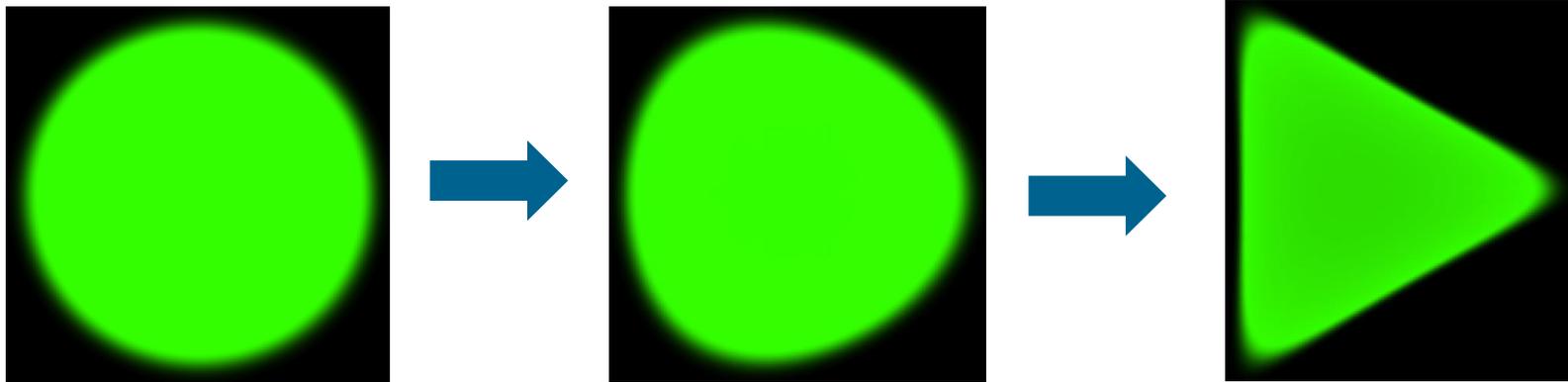
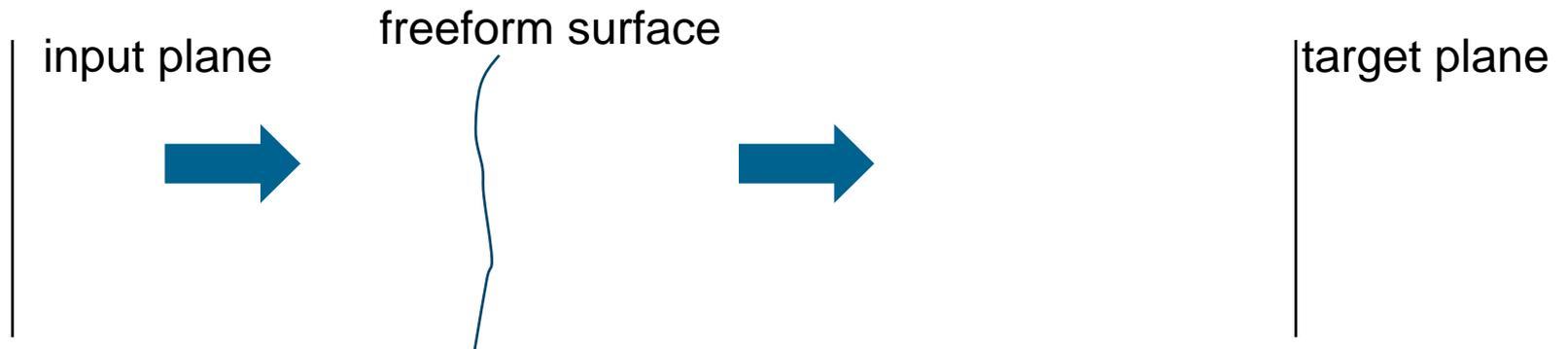


Amplitude  $E_x(x,y)$



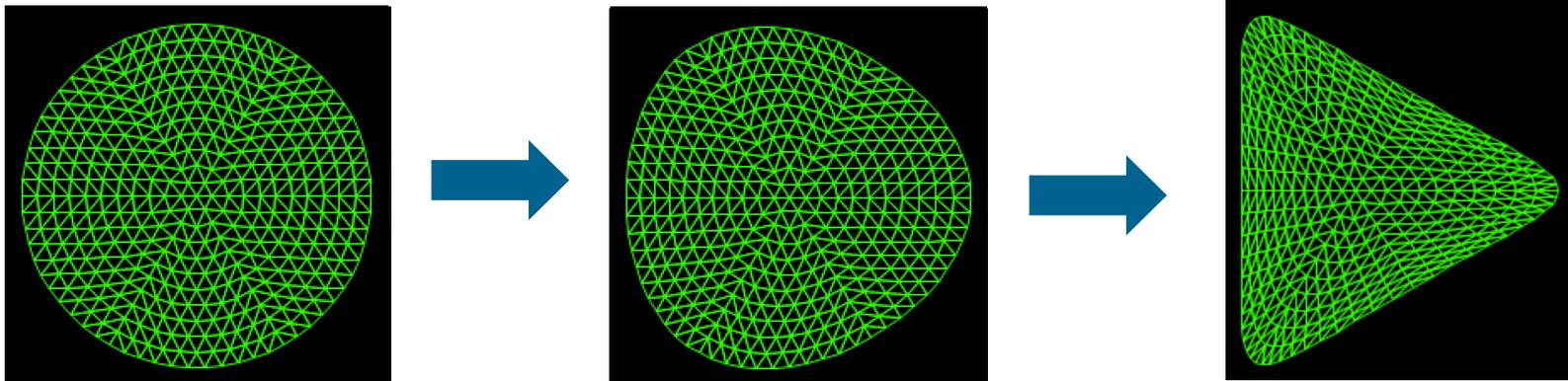
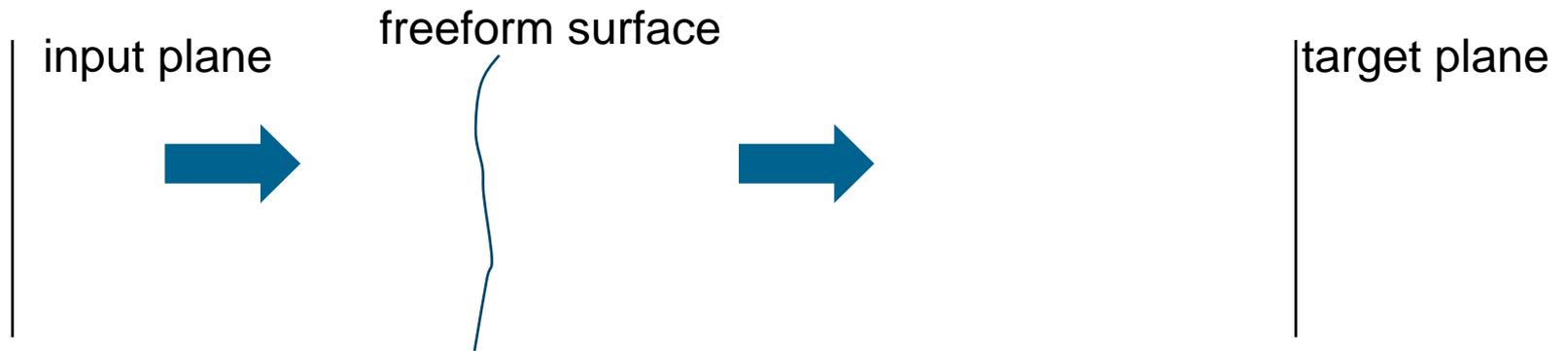
simulation time < 1 sec

# Modelling of Refractive Optical Element



Irradiance pattern is morphing while propagation

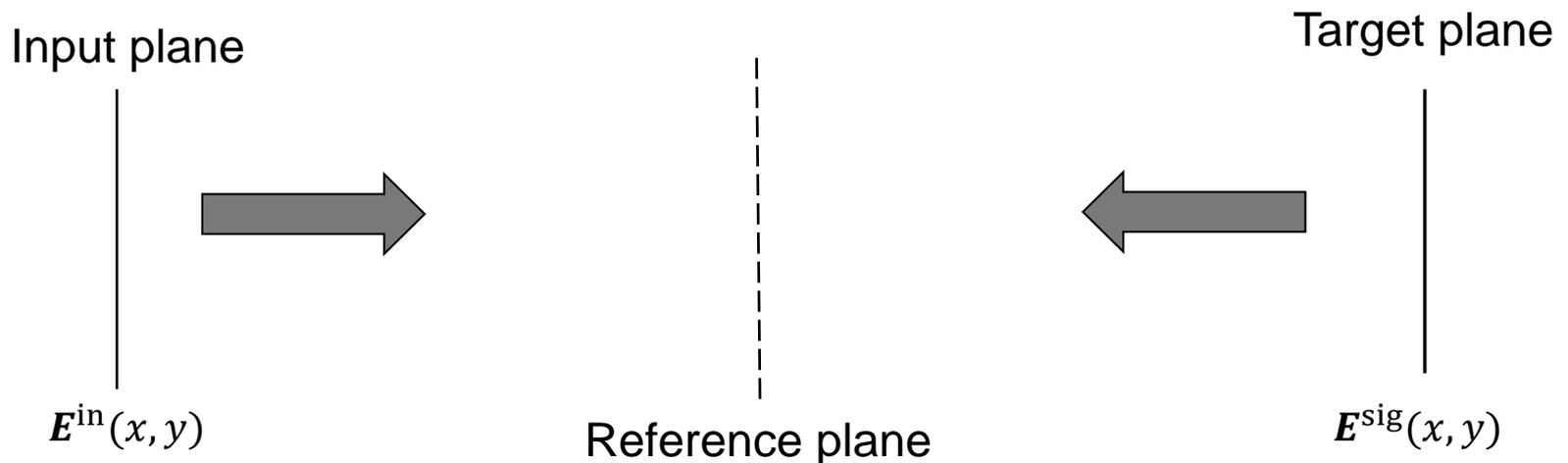
# Modelling of Refractive Optical Element



# Introduction

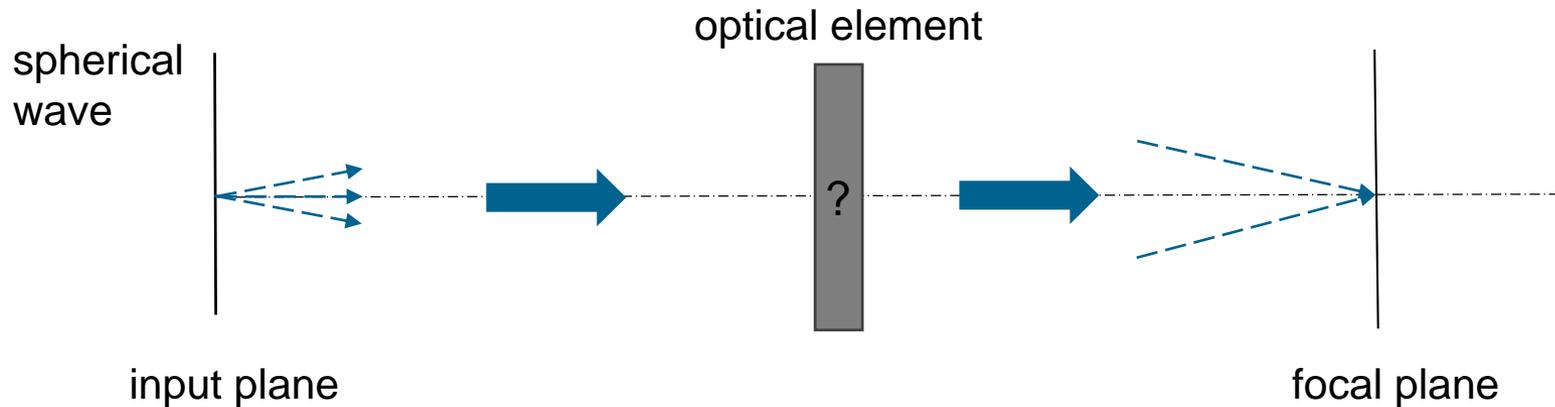
Inverse approach

1. functional embodiment: an ideal component function is introduced to realize the transmission between the two fields;
2. structure embodiment: suitable structure is developed to realize the functionality of the component.



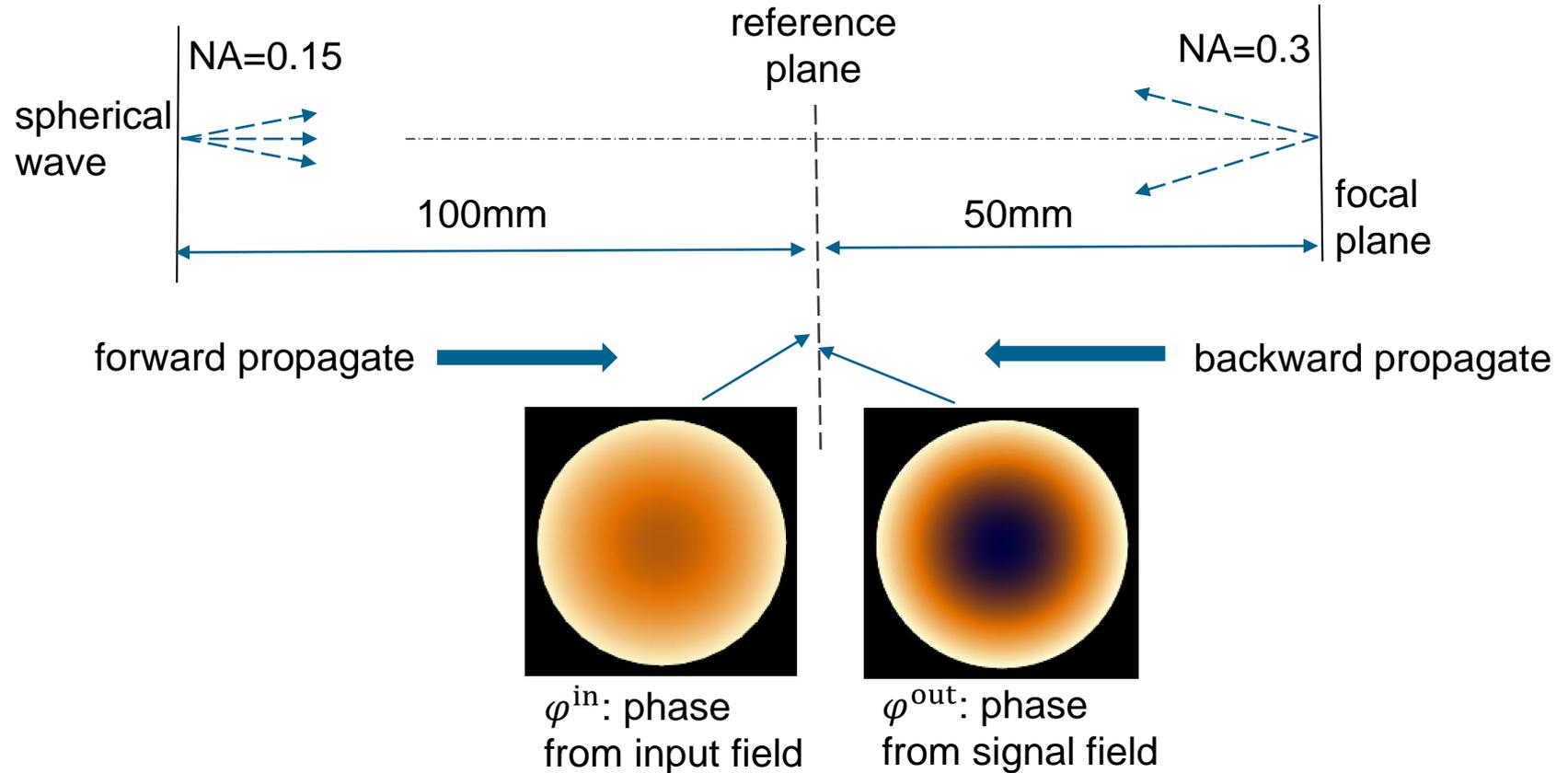
# Design Task: Focusing System

Task description: for an given spherical wave, to design an optical element to focus it with a specific NA



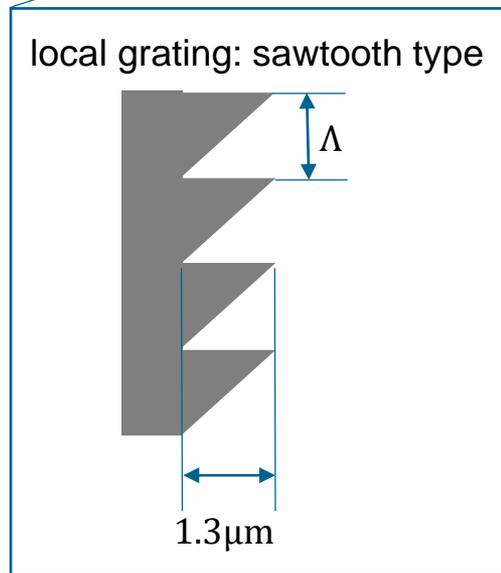
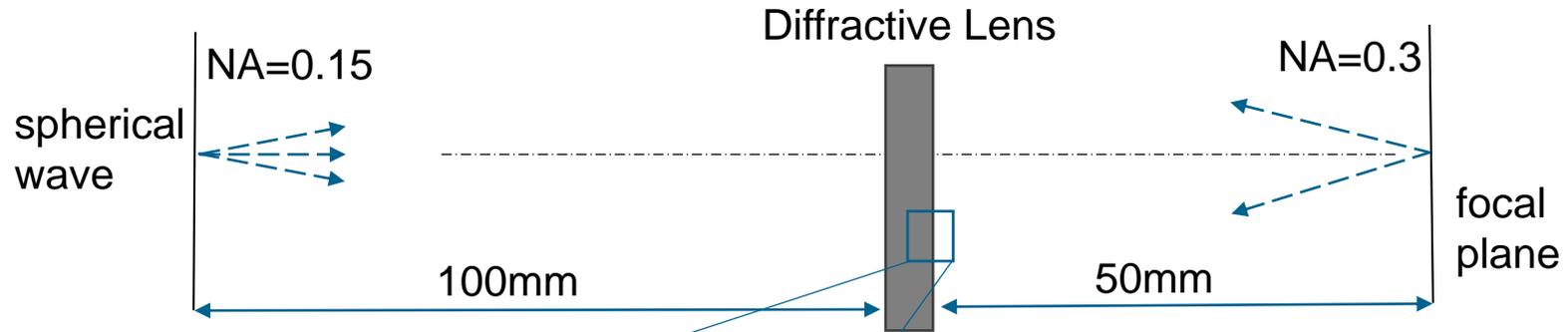
The signal field is considered as a spherical wave.

# Design Process: Functional Embodiment



The element is considered as a phase only function, which is the subtraction of the phase from input and output field:  $\varphi(x, y) = \varphi^{\text{out}}(x, y) - \varphi^{\text{in}}(x, y)$

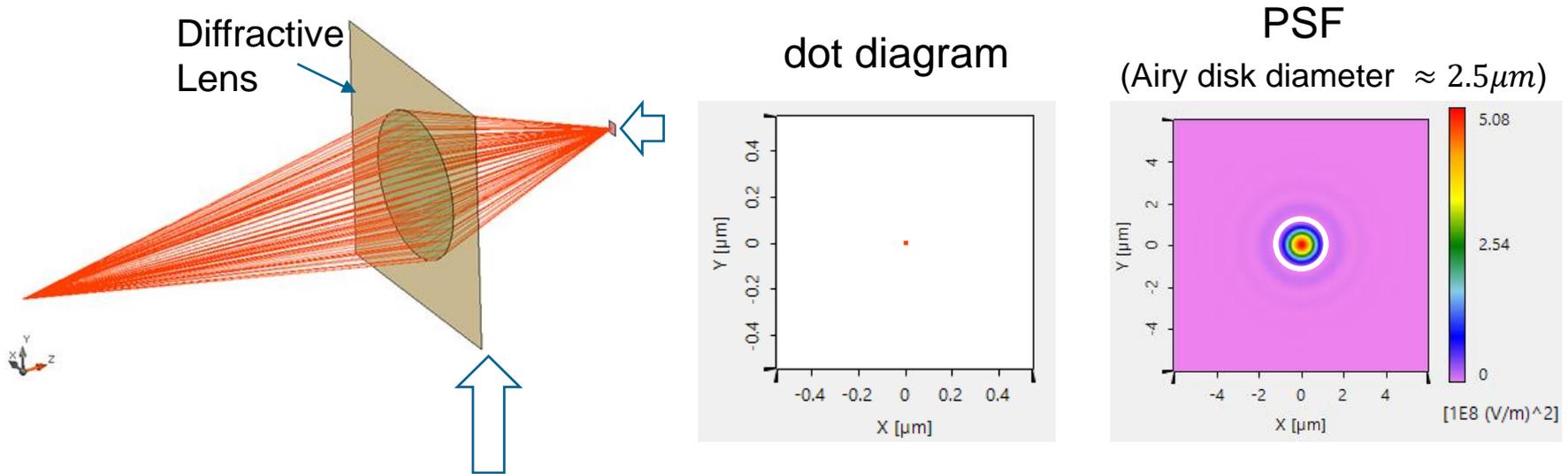
# Design Process: Structure Embodiment



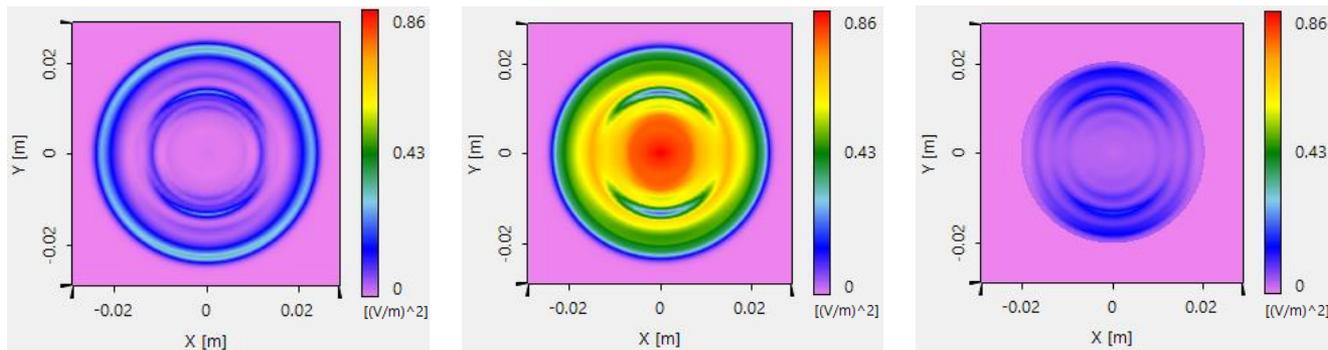
- The local grating of the diffractive lens is chosen as sawtooth type.
- The 1st order is selected as working order.
- Local grating period  $\Lambda(x, y)$  of the diffractive lens is obtained with the phase function.

$$\Lambda(x, y) = \frac{2\pi}{|\nabla\varphi(x, y)|}$$

# Simulation with Designed Result



Intensity After the Diffractive Lens

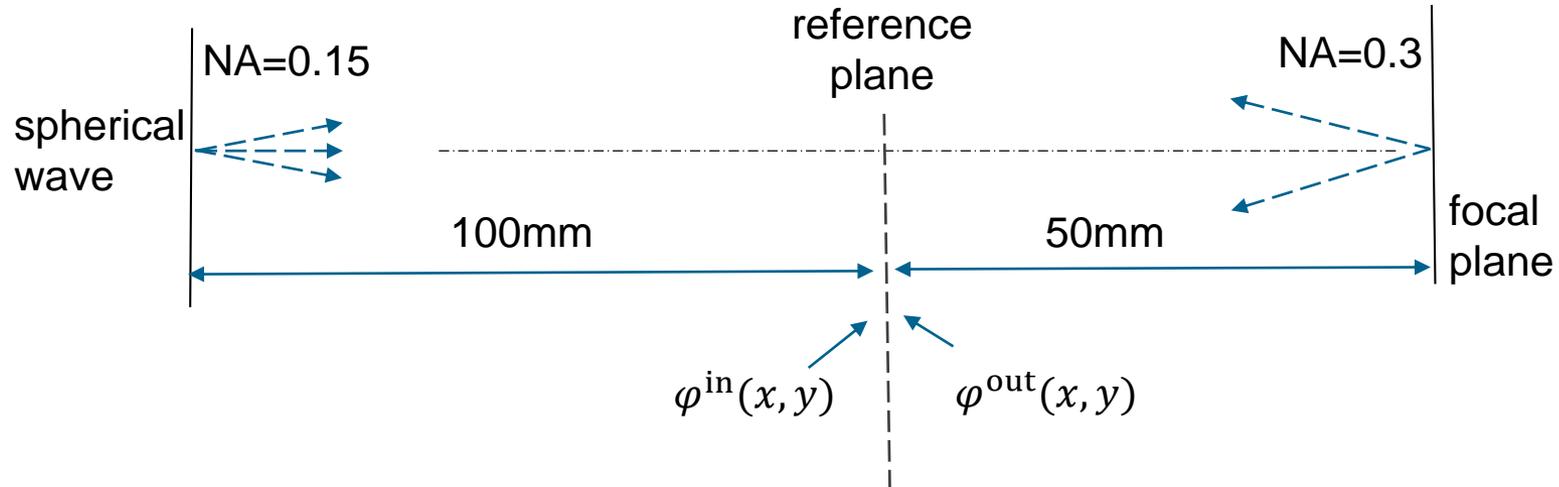


0th order

1st order

2nd order

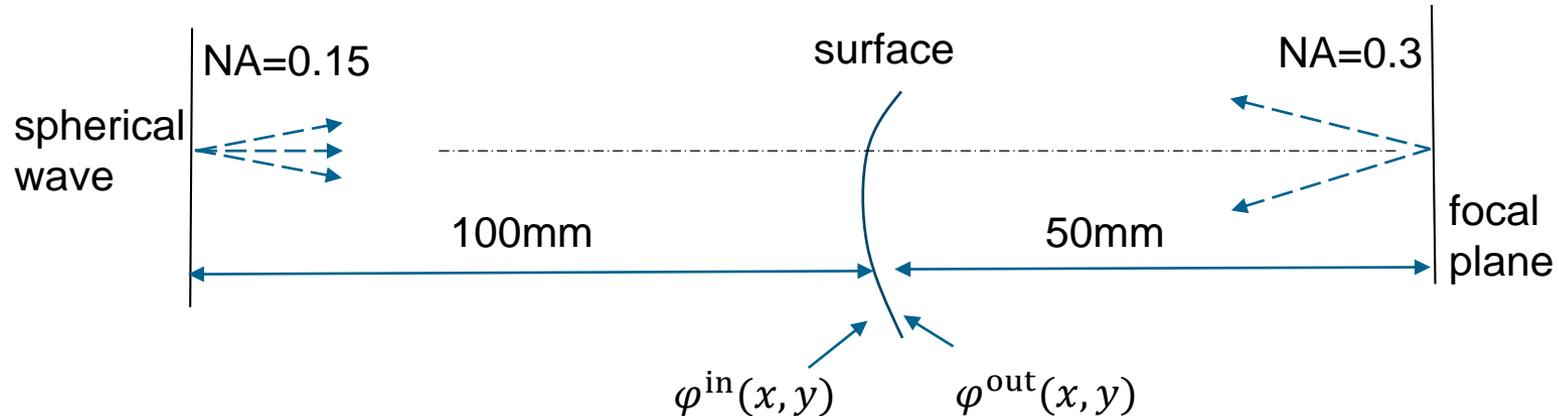
# Design Process: Structure Embodiment



Algorithm in brief:

1. propagate  $\rightarrow$  phase on reference plane  $\varphi^{\text{in}}(x, y)$  ,  $\varphi^{\text{out}}(x, y)$
2.  $\varphi^{\text{in}}(x, y)$  ,  $\varphi^{\text{out}}(x, y)$   $\rightarrow$  local wave vectors  $\mathbf{k}^{\text{in}}(x, y)$  ,  $\mathbf{k}^{\text{out}}(x, y)$ ;
3.  $\mathbf{k}^{\text{in}}(x, y)$  ,  $\mathbf{k}^{\text{out}}(x, y)$   $\rightarrow$  gradient of the surface  $\nabla H(x, y)$ ;

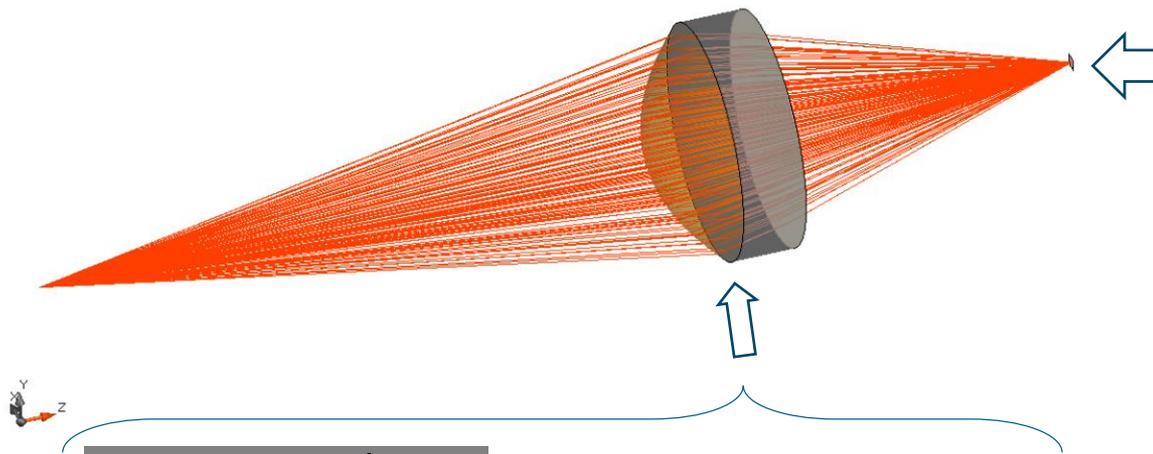
# Design Process: Structure Embodiment



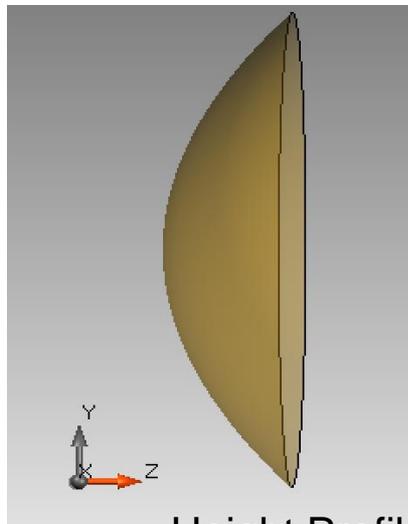
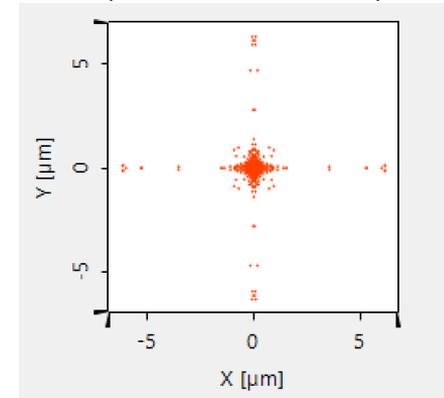
Algorithm in brief:

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3.  $\mathbf{k}^{\text{in}}(x, y)$  ,  $\mathbf{k}^{\text{out}}(x, y)$   $\rightarrow$  gradient of the surface  $\nabla H(x, y)$ ;
4. fit the gradient by B-spline to obtain a surface;
5. update the reference plane with the surface, and iteratively perform step 1 to 4 until a proper surface is obtained.

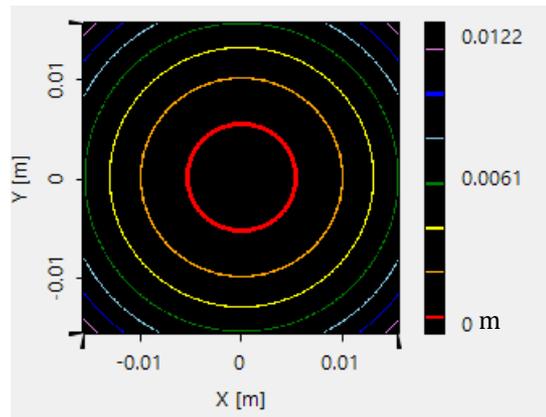
# Designed Result and Simulation



dot diagram  
( $RMS \approx 4110nm$ )

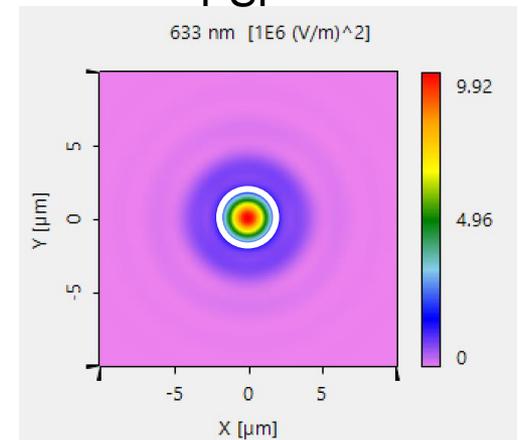


Height Profile  
(3D view)



Height Profile  
(2D Contour line)

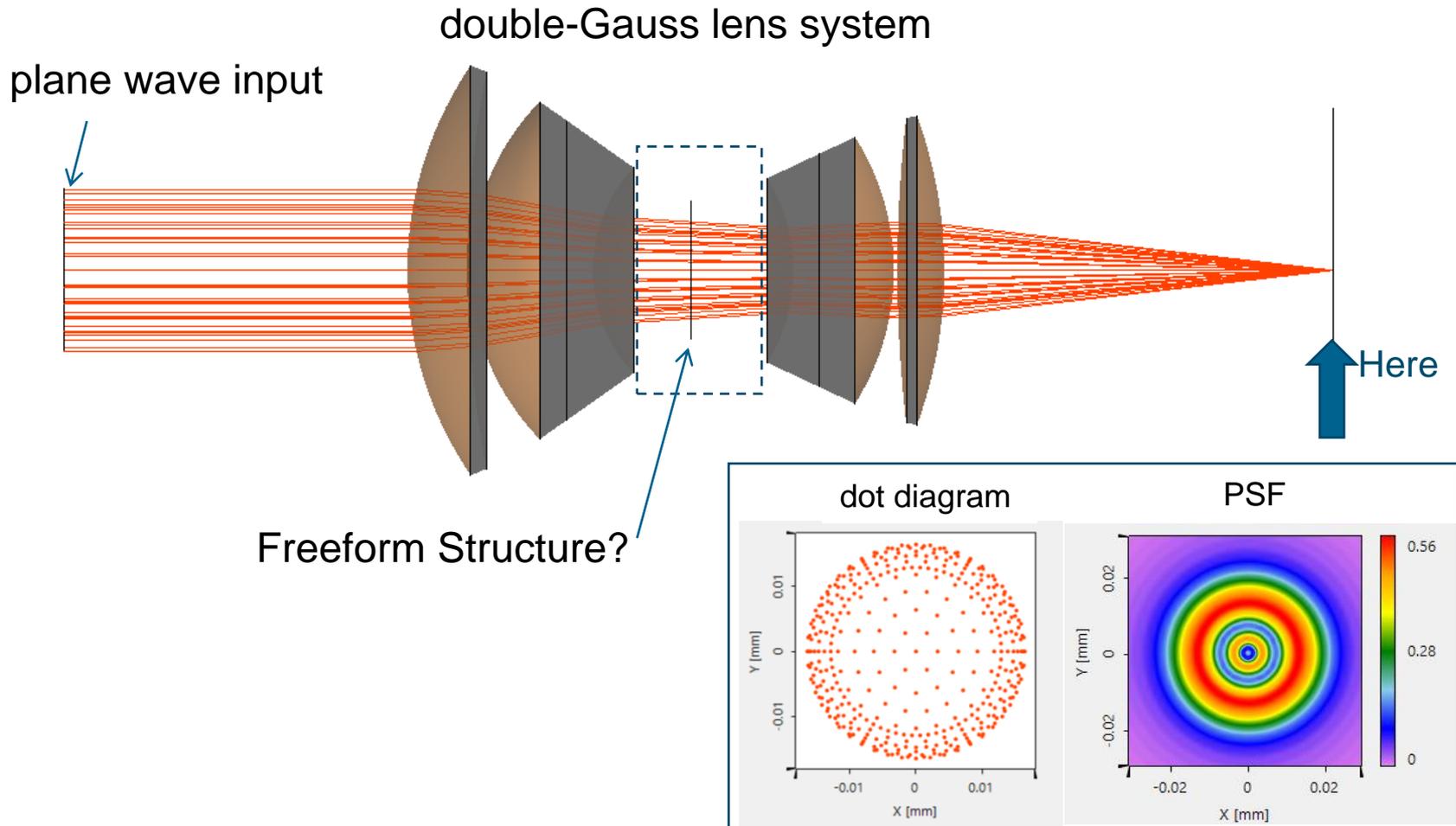
PSF



(Airy disk diameter  $\approx 2.5\mu m$ )

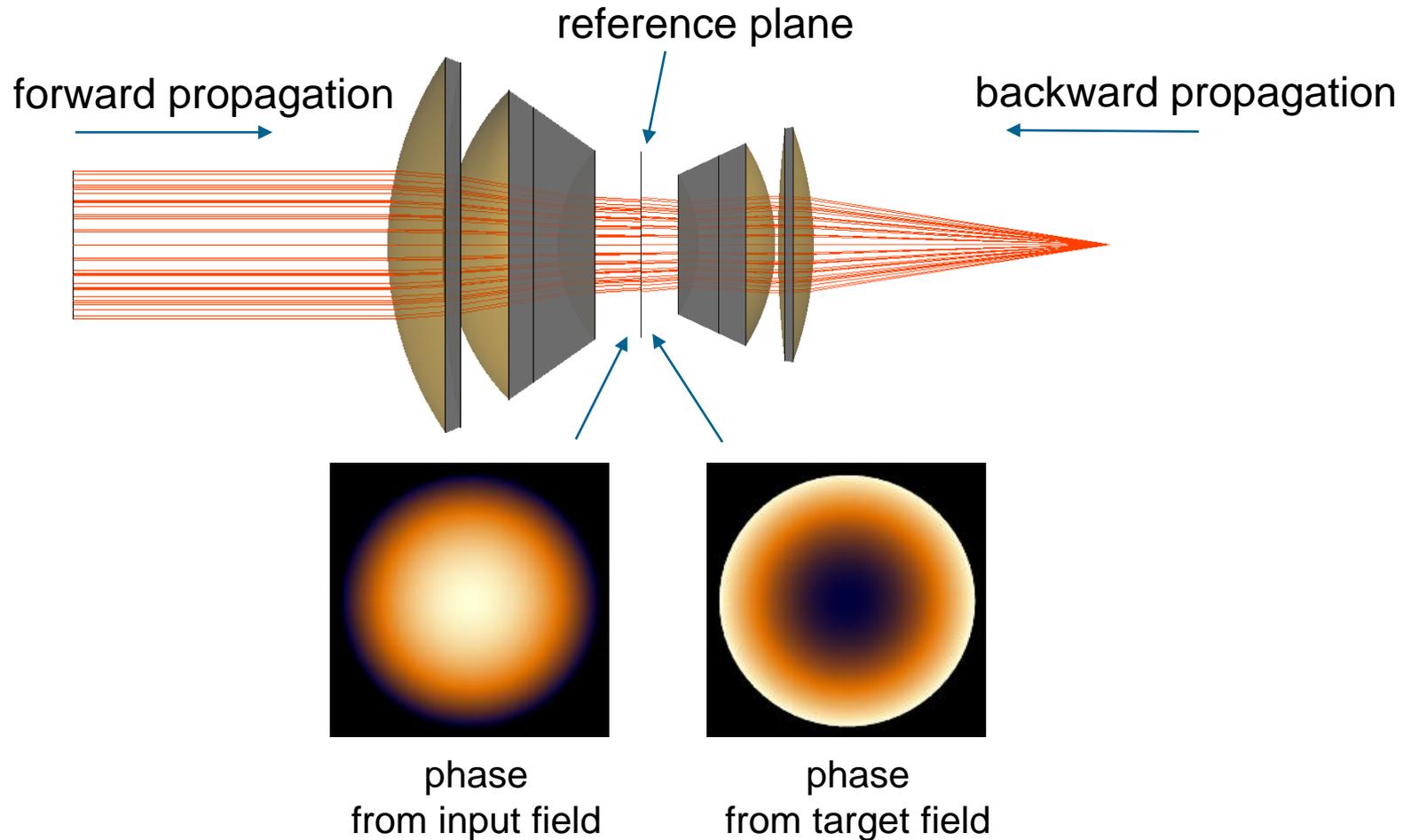
# Application: Aberration Control in Image System

## 1. Spherical Aberration

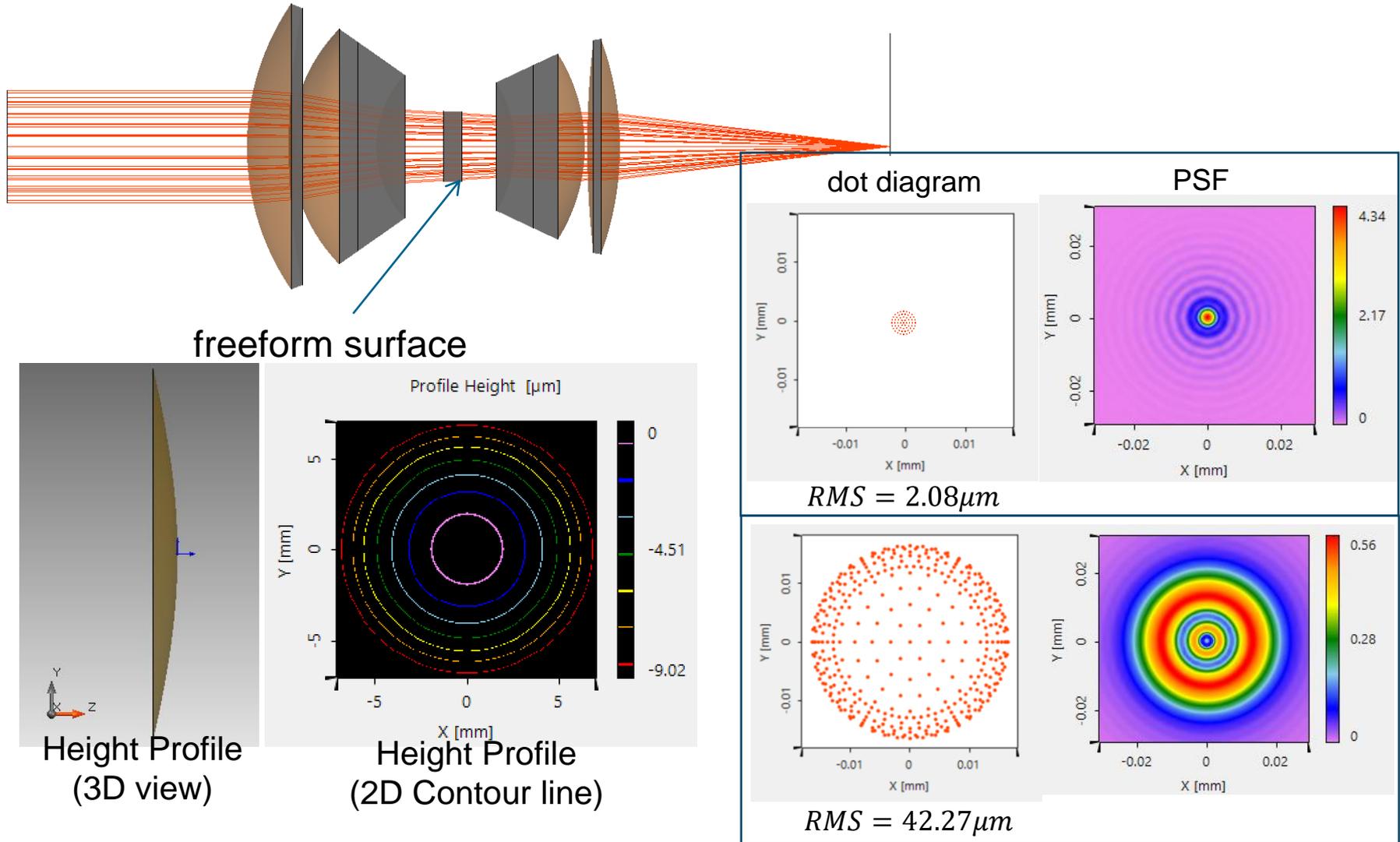


# Application: Aberration Control in Image System

## Design Process

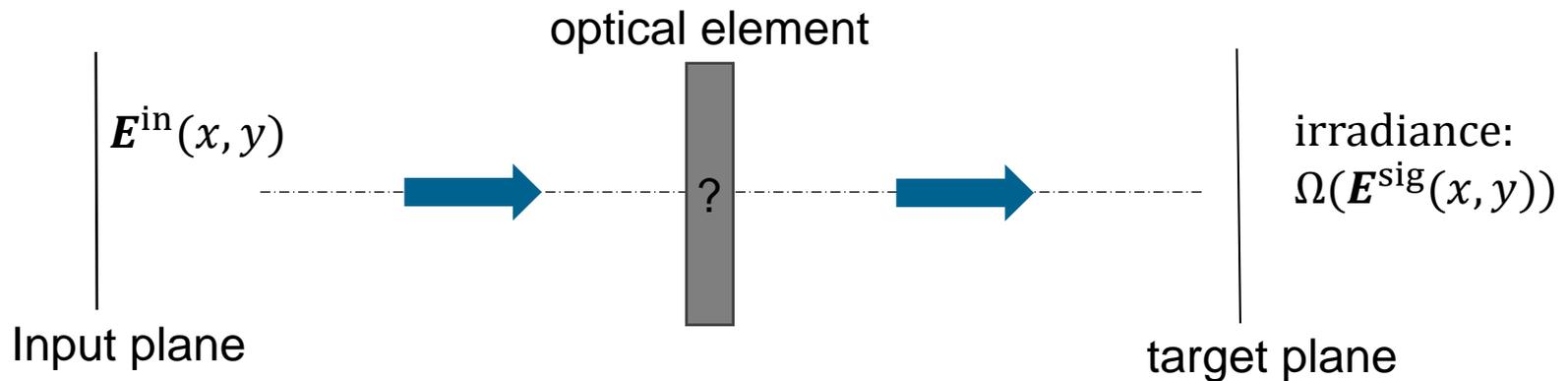


# Design and Simulation Result



# Design Task: Irradiance Redistribution

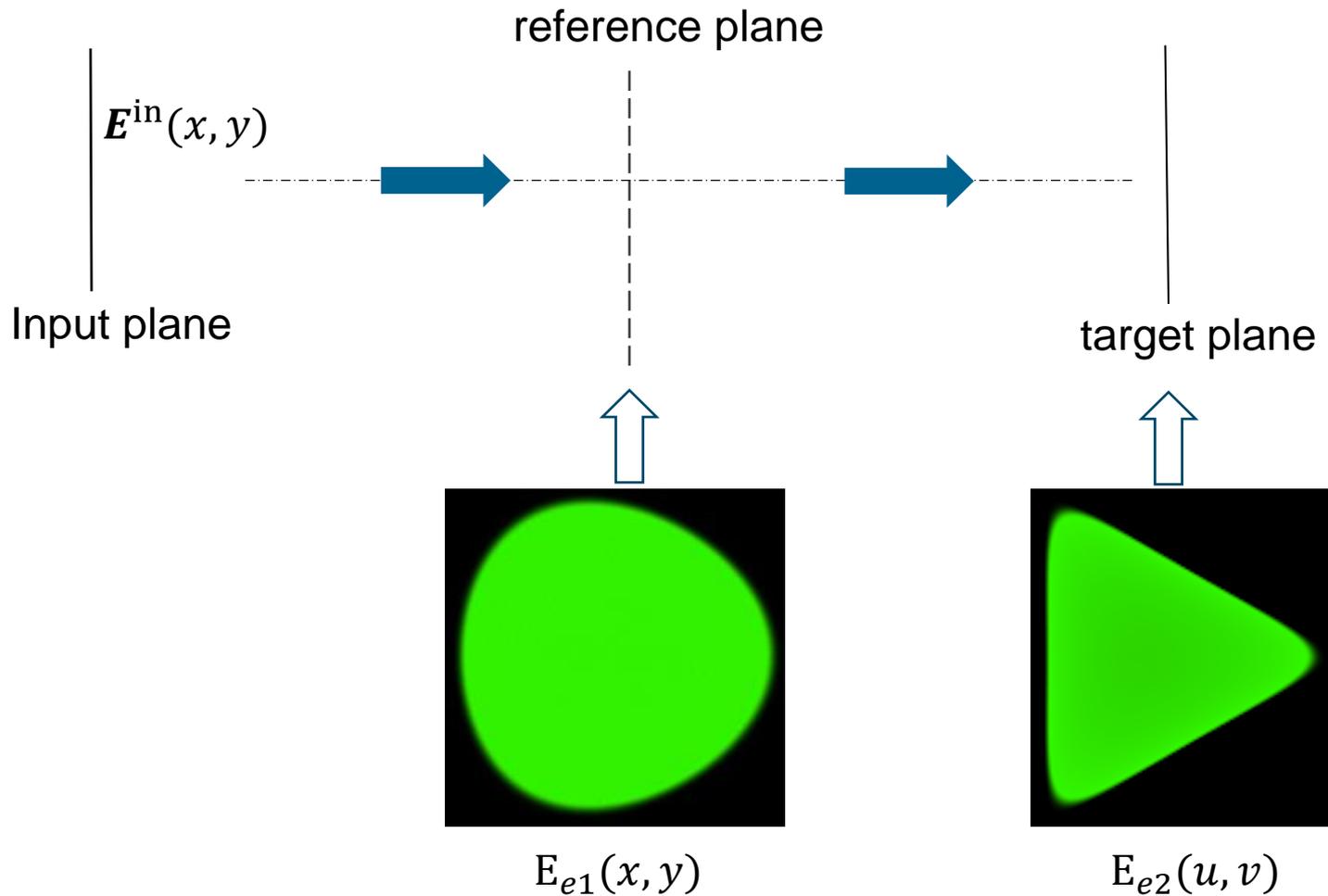
Task description: for a given input field, design an optical element to achieve required irradiance on target plane



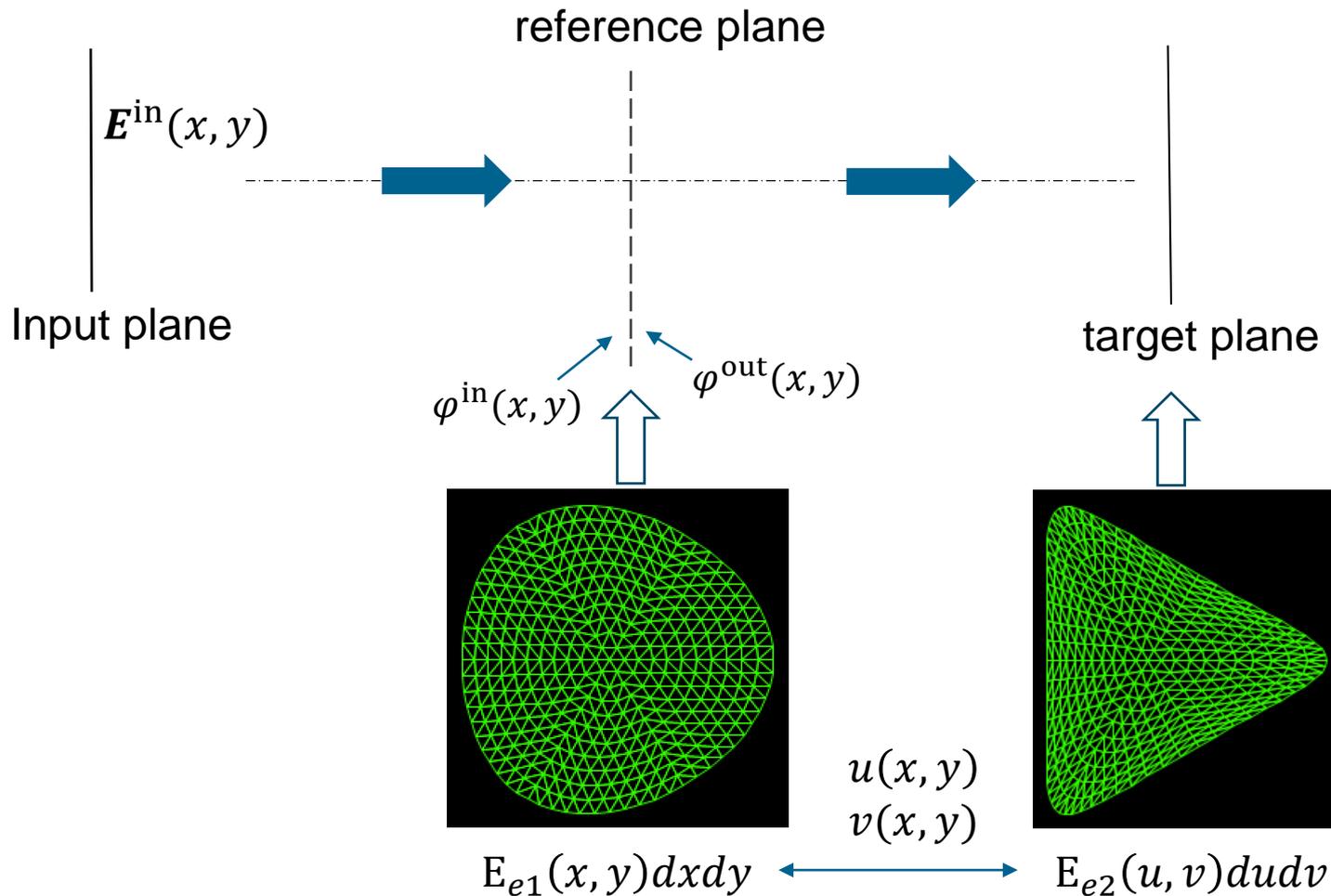
The input field is given.

The signal field is a freedom for the design.

# Design Process: Functional Embodiment

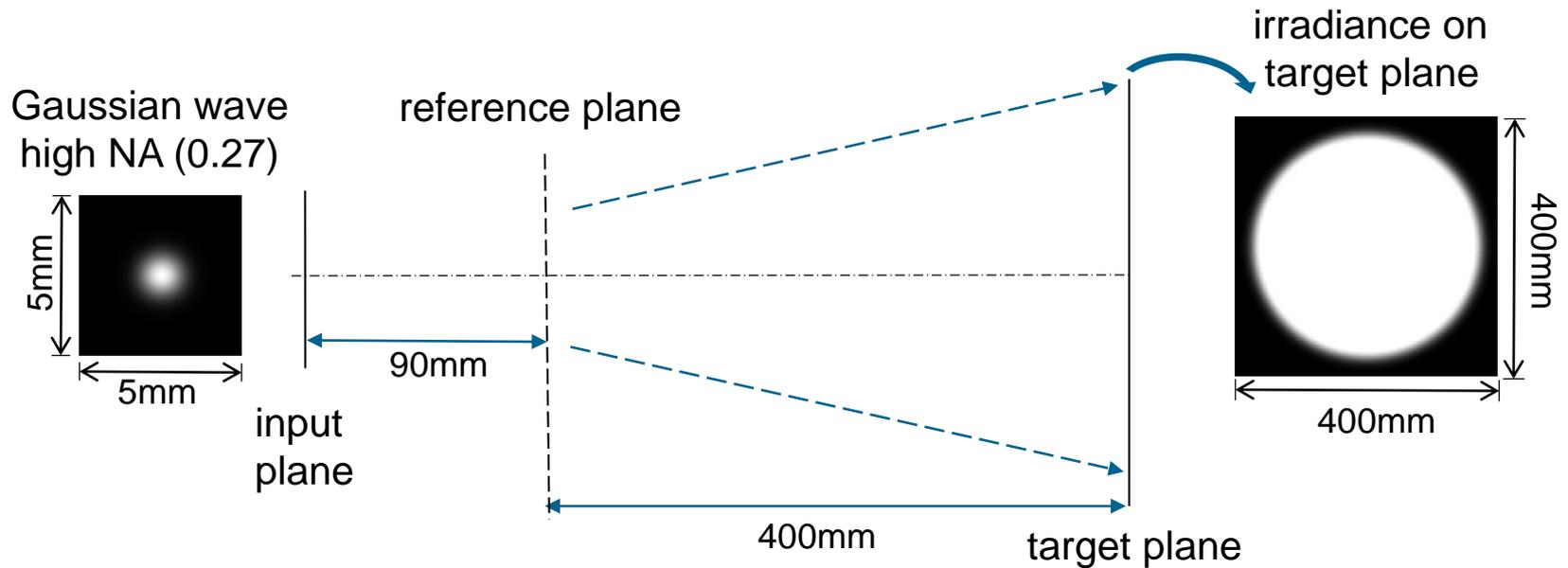


# Design Process: Functional Embodiment

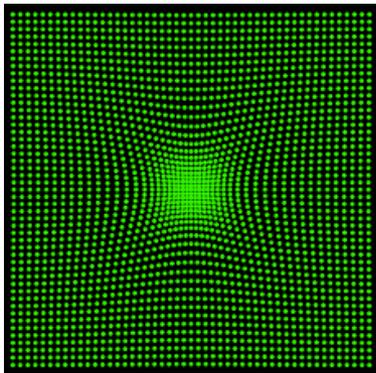
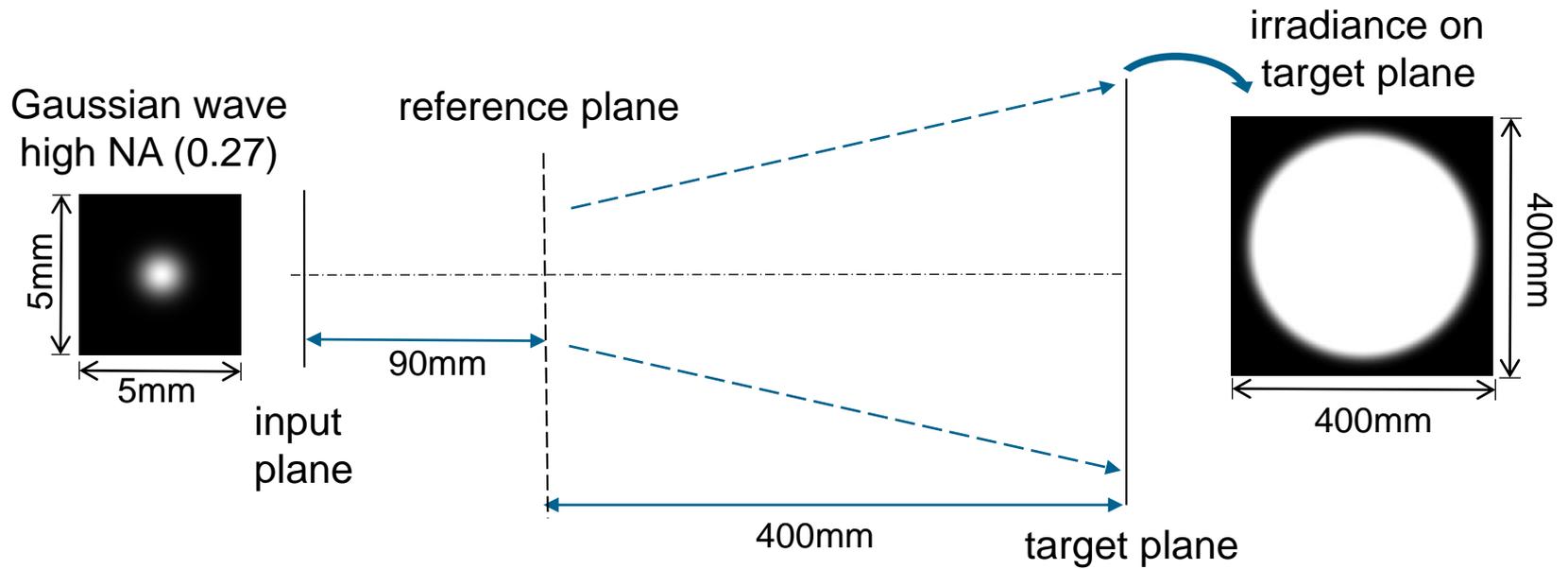


# Example: Homogeneous Irradiance

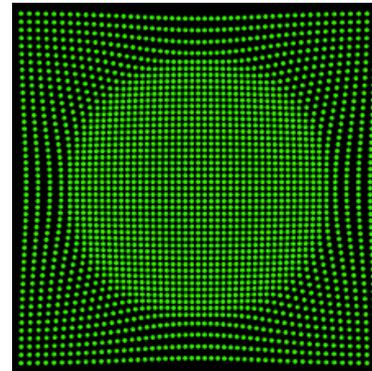
Task description: for an input Gaussian wave, design an optical element to achieve homogeneous irradiance on target plane



# Example: Homogeneous Irradiance



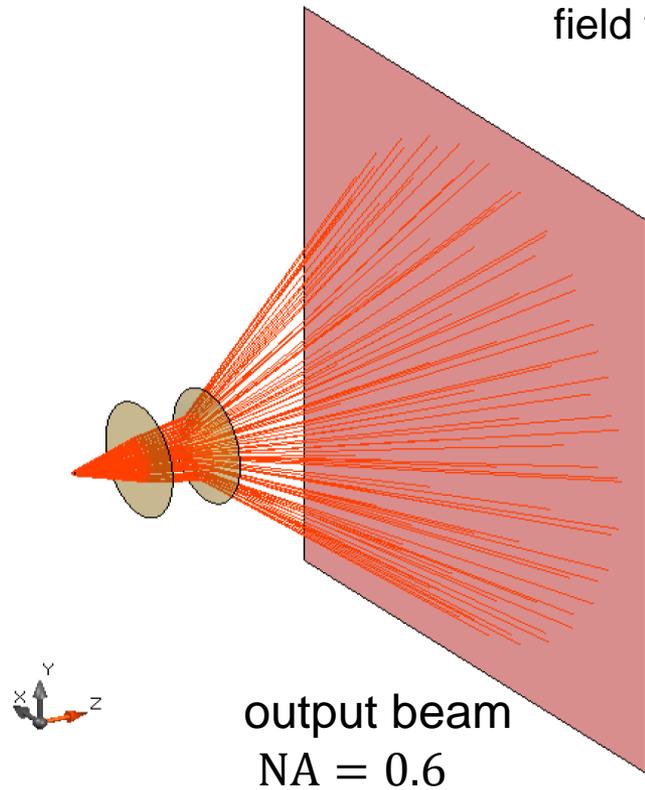
mesh nodes for input irradiance



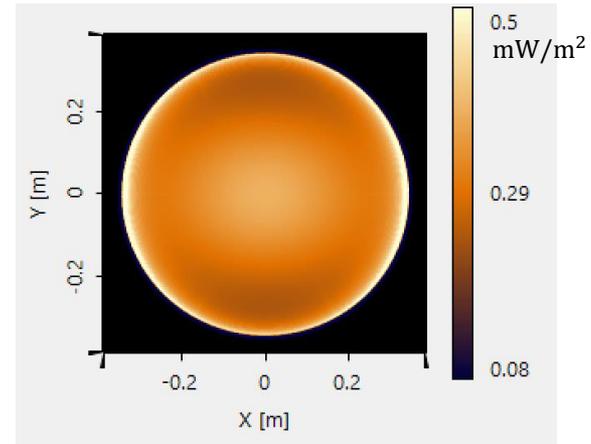
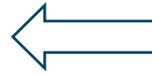
mesh nodes for target irradiance



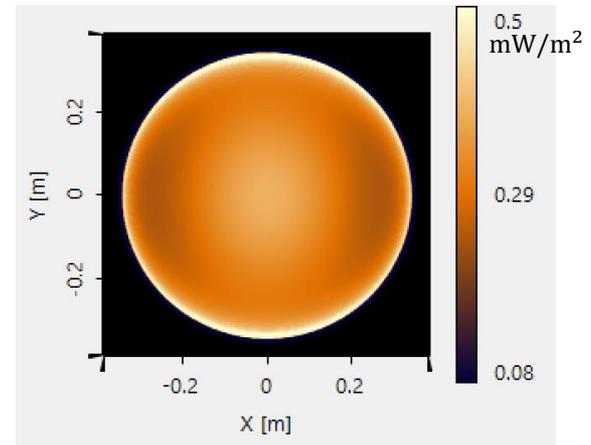
# Designed Result and Simulation



field tracing result: irradiance with different polarization input field

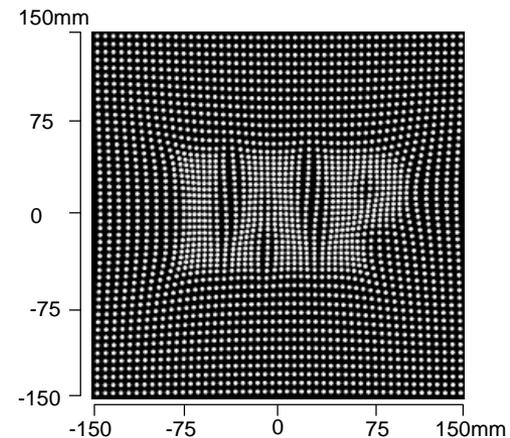
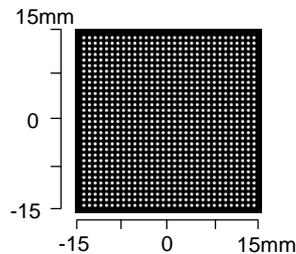
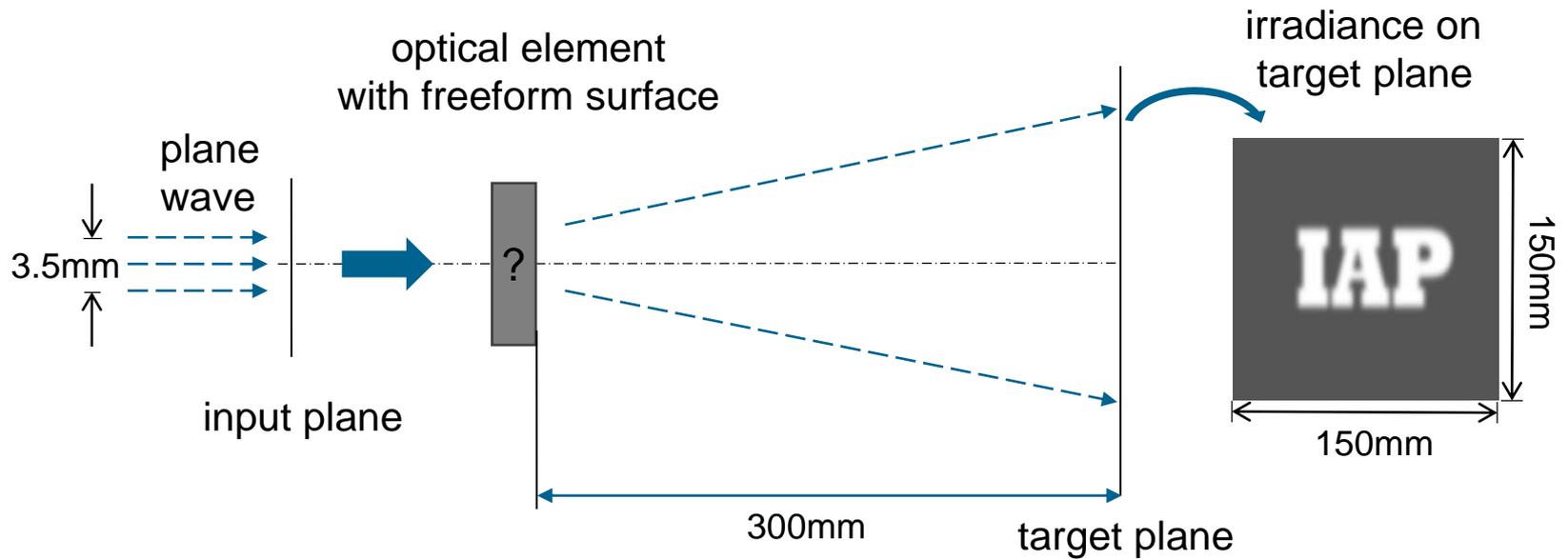


x-polarized

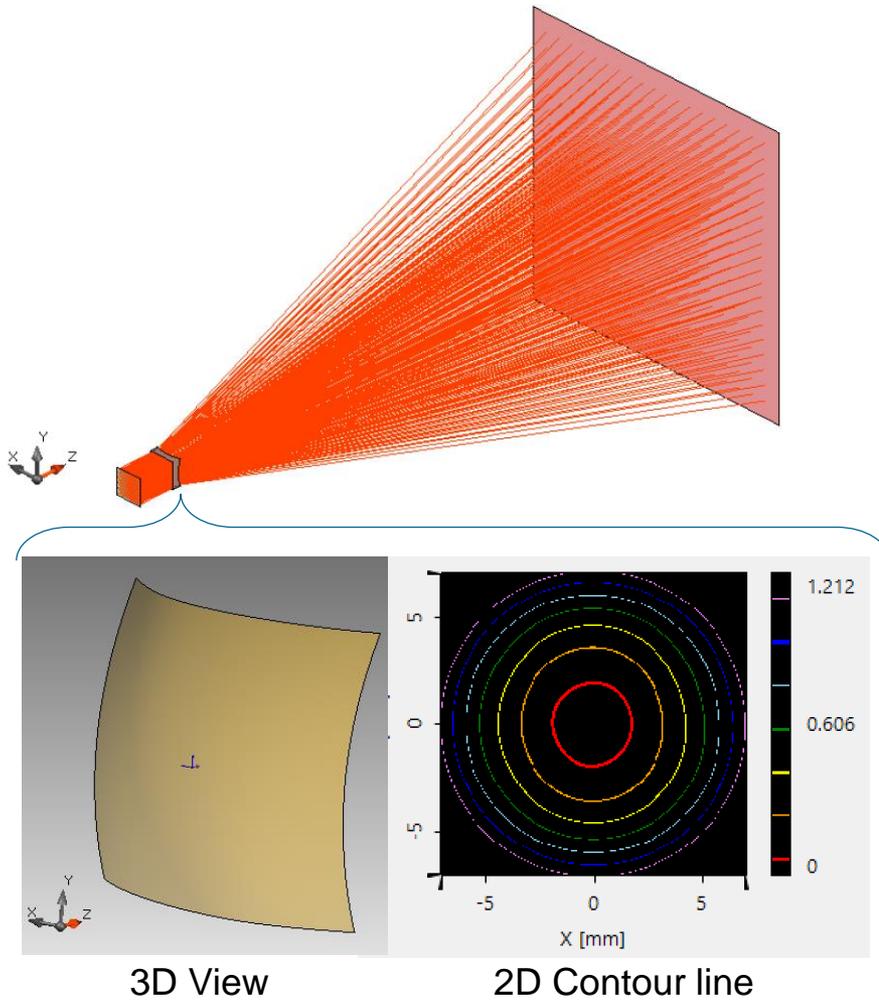


y-polarized

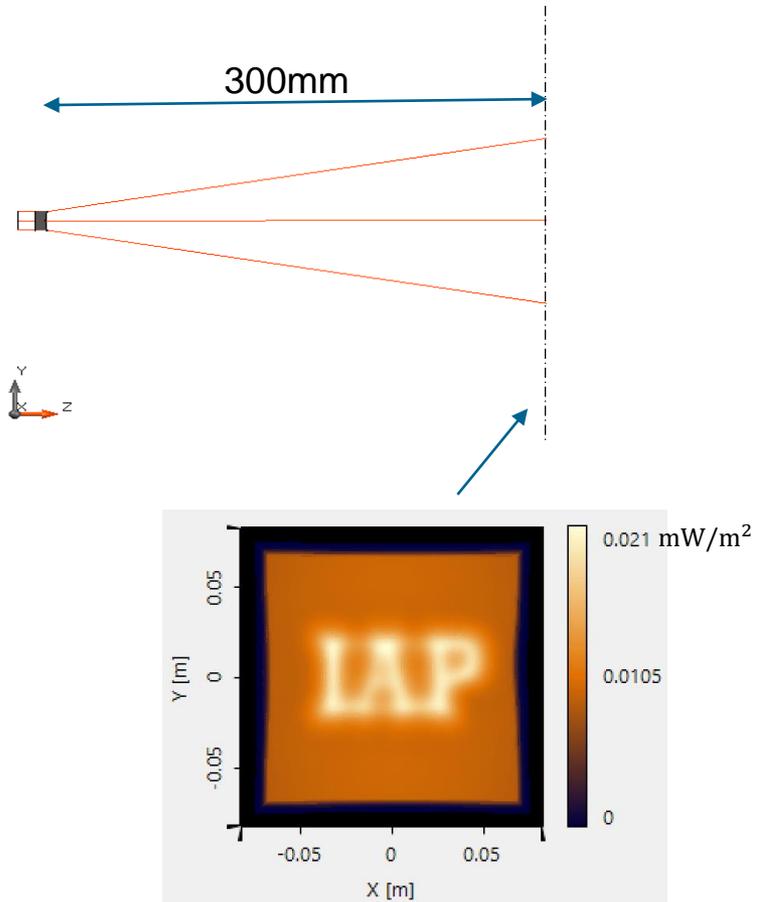
# Example: Specific Irradiance



# Designed Result and Simulation

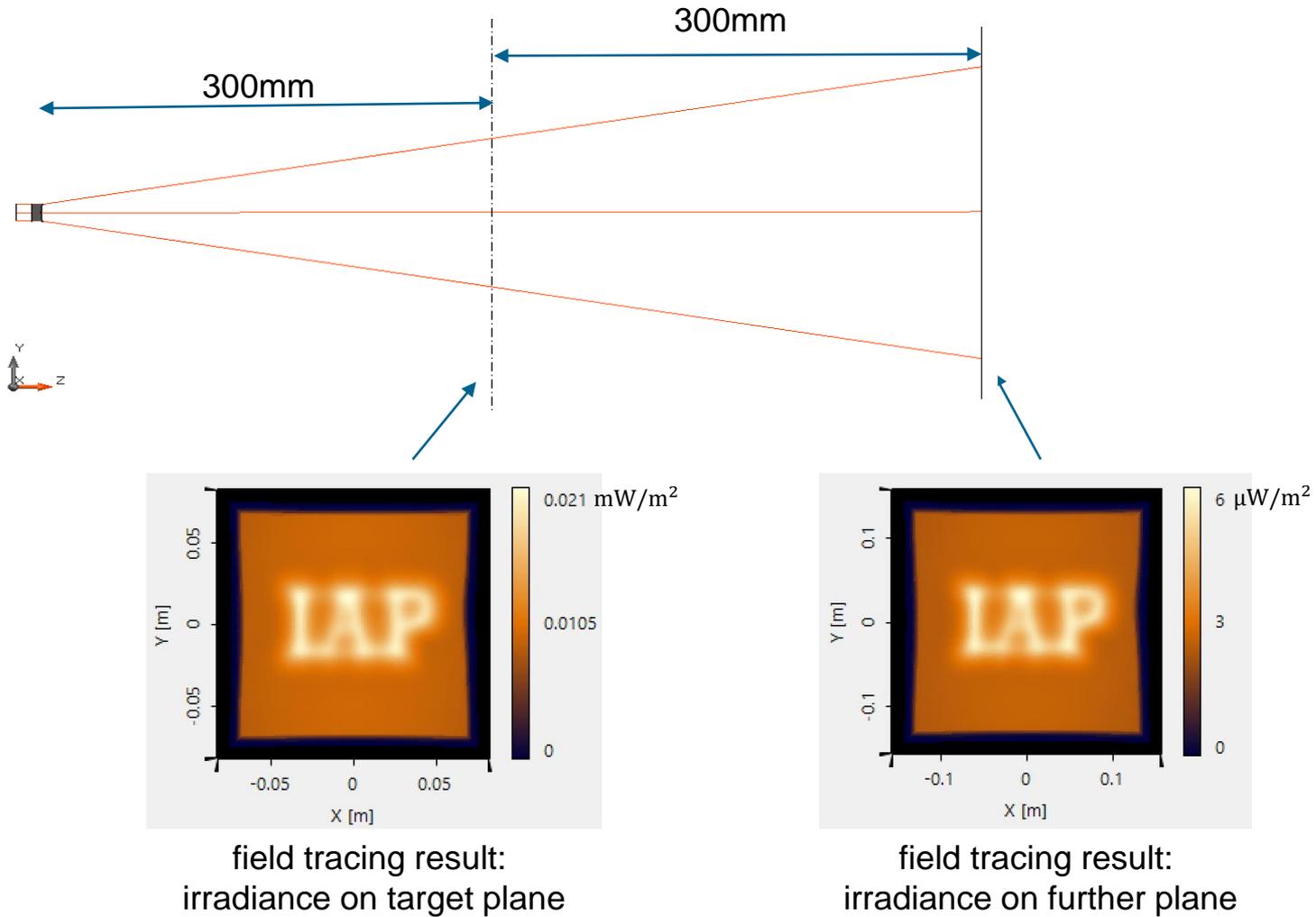


# Designed Result and Simulation



field tracing result:  
irradiance on target plane

# Designed Result and Simulation



# Conclusion

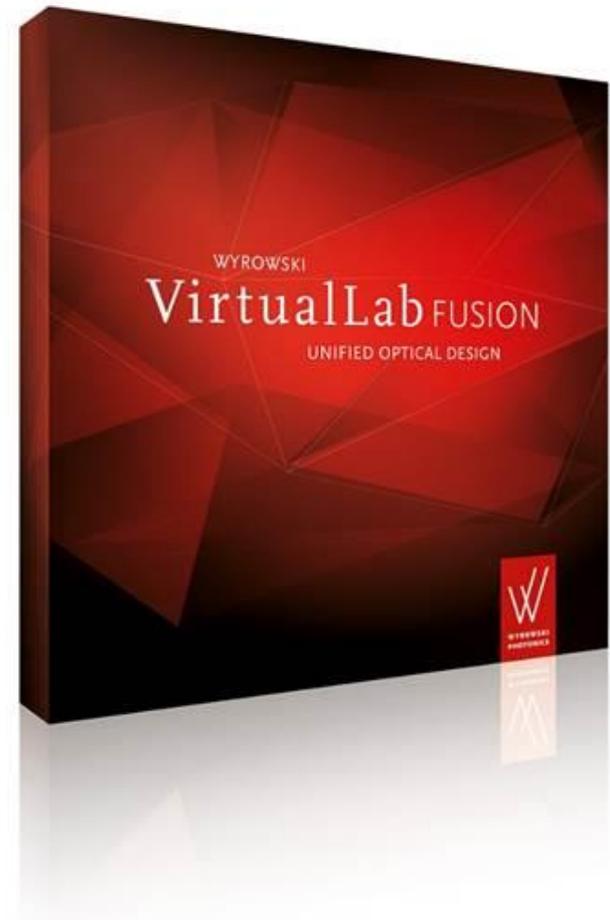
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In summary:

- Modelling method is the basic for optical design;
- Base on the inverse approach, the directly design for the element structure is done in a fast way;
- The designed results can be used as the initial structure for further optimization.

# Implementation

- All algorithms are implemented in the physical optics simulation and design software **VirtualLab Fusion**
- VirtualLab Fusion is developed, following the field tracing concept, by Wyrowski Photonics UG, Jena, Germany



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**Thank you**