

EOS Topical Meeting on Diffractive Optics 2019

A K-Domain Method for Fast Calculation of Electromagnetic Fields Propagating through Graded-Index Media

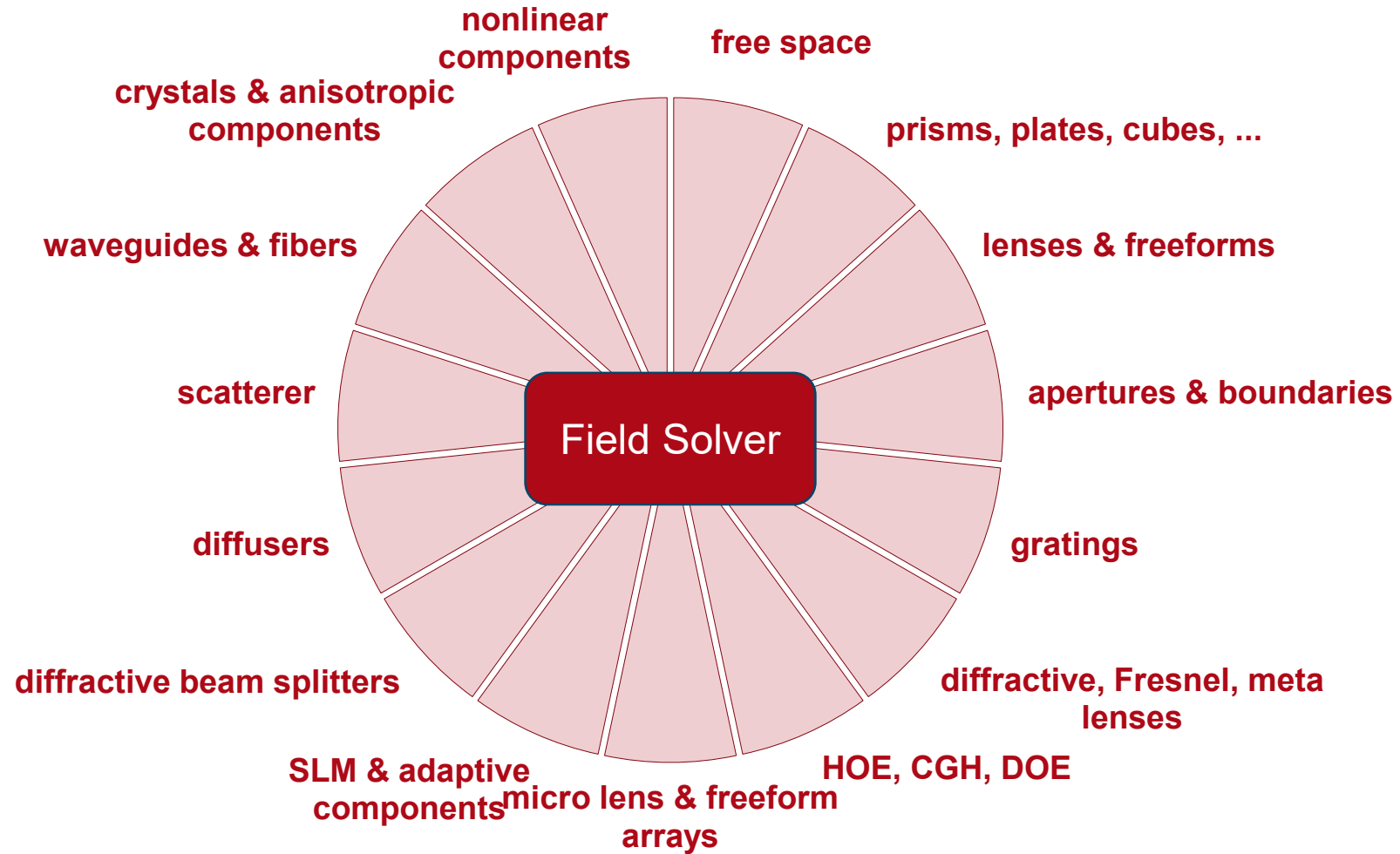
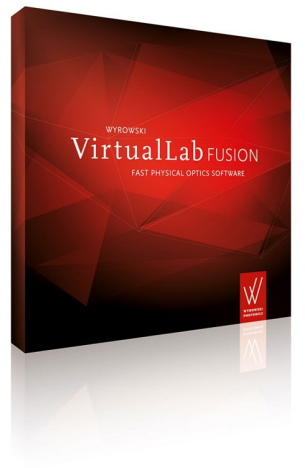
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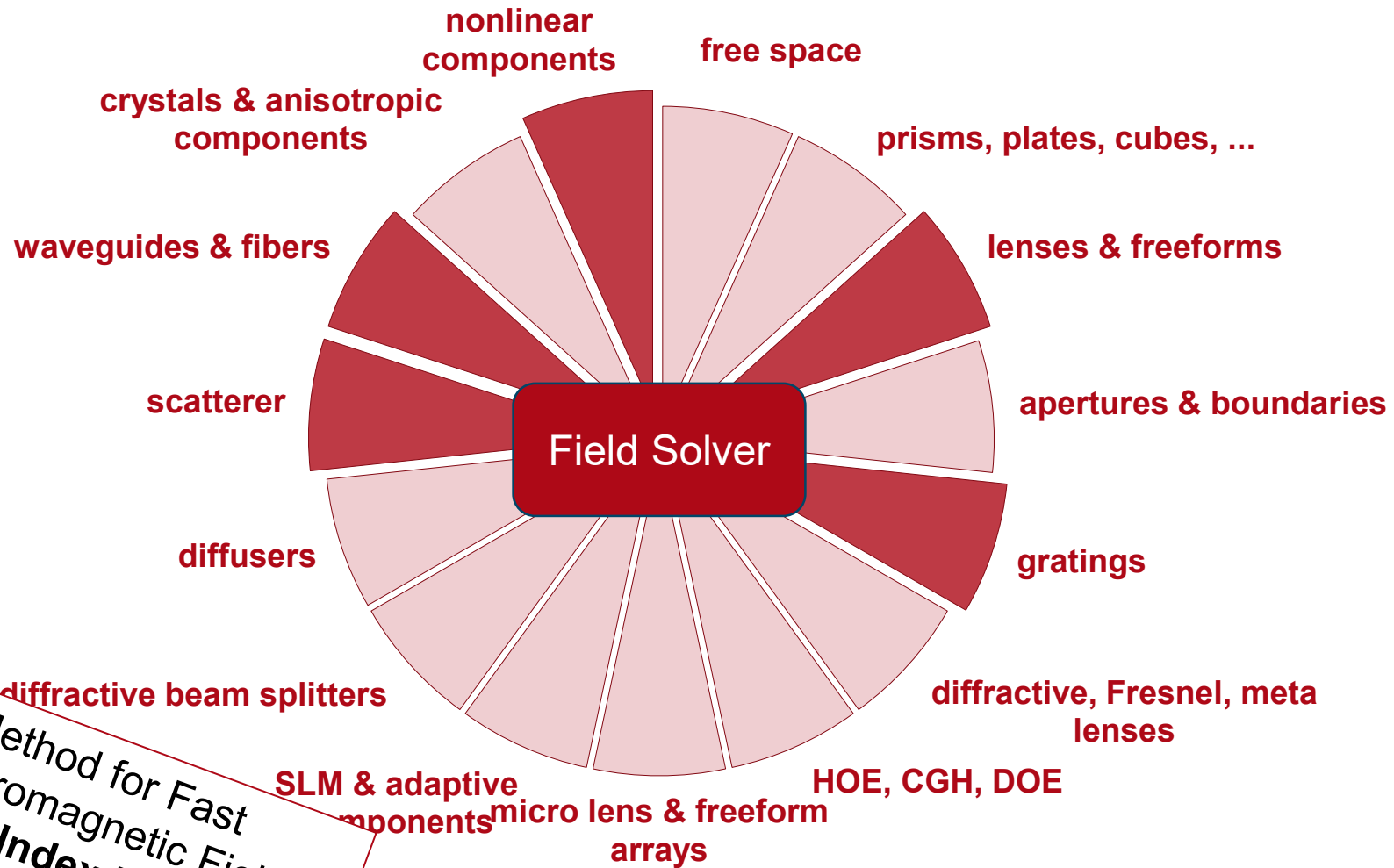
²LightTrans International UG, Jena, Germany, 07745

³Wyrowski Photonics GmbH, Jena, Germany, 07745

Connecting Field Solvers

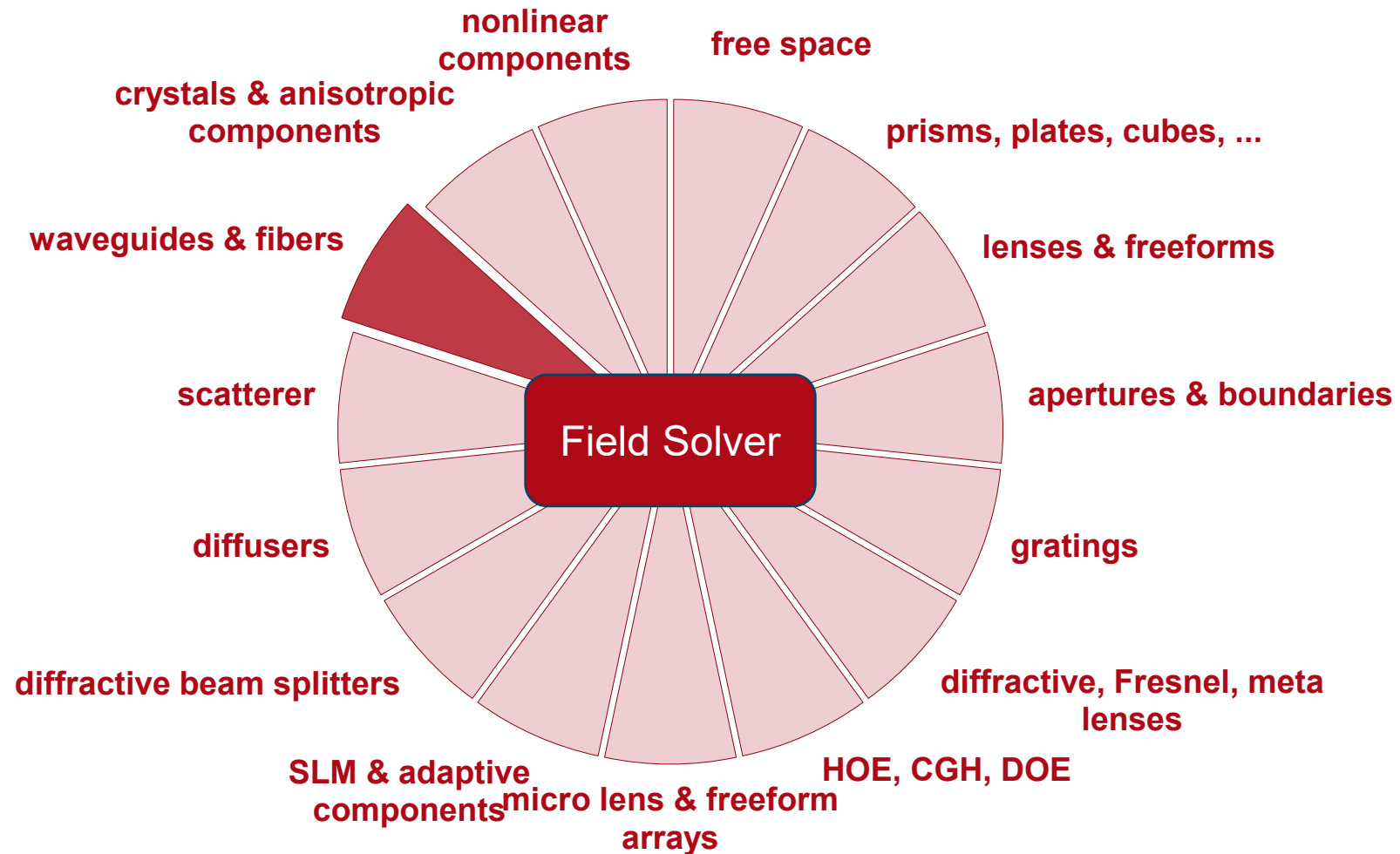


Regional Field Solver for Graded-Index Medium



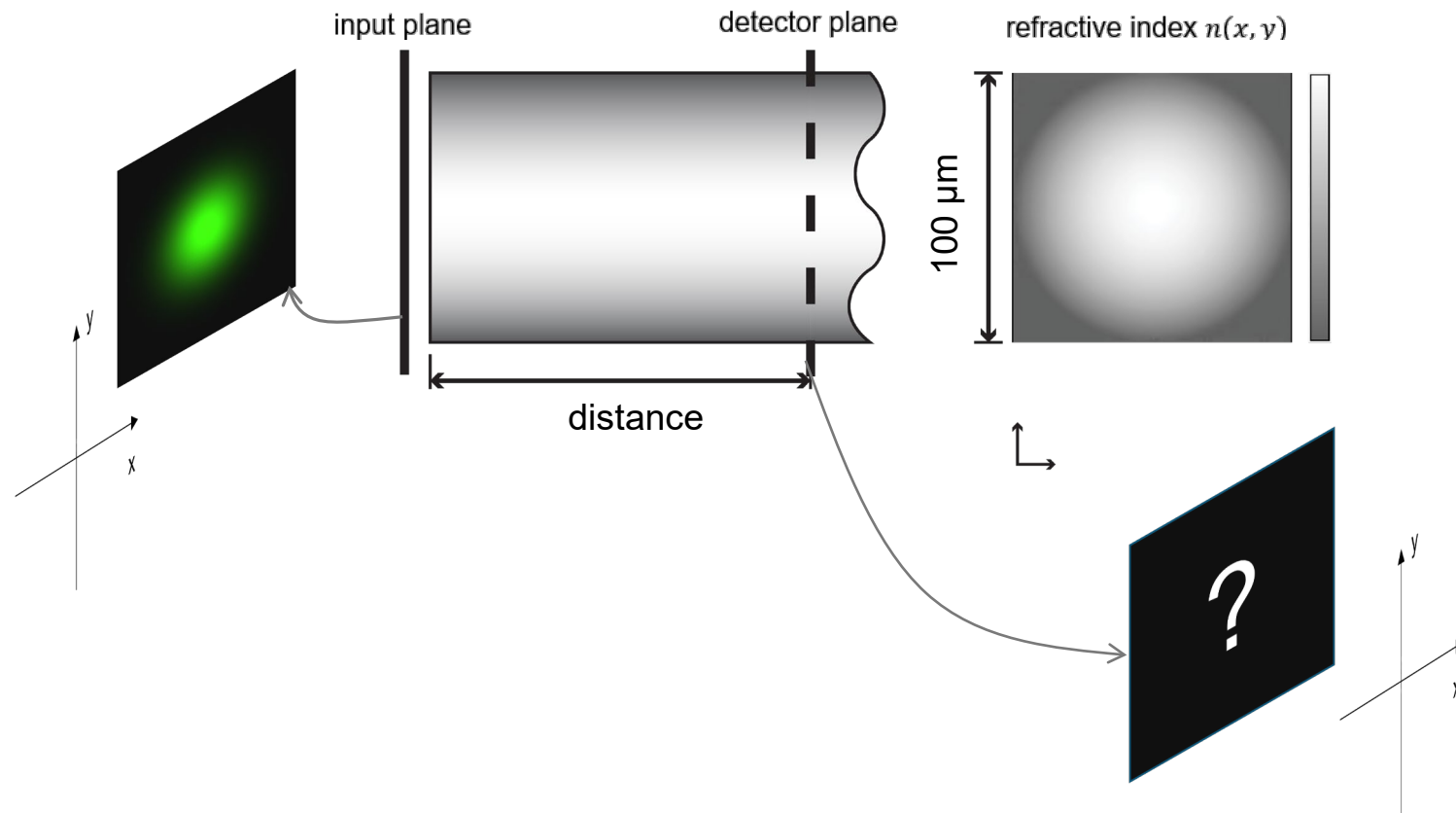
A K-Domain Method for Fast Calculation of Electromagnetic Fields through Graded-Index Media

Regional Field Solver for Graded-Index Medium: Fiber

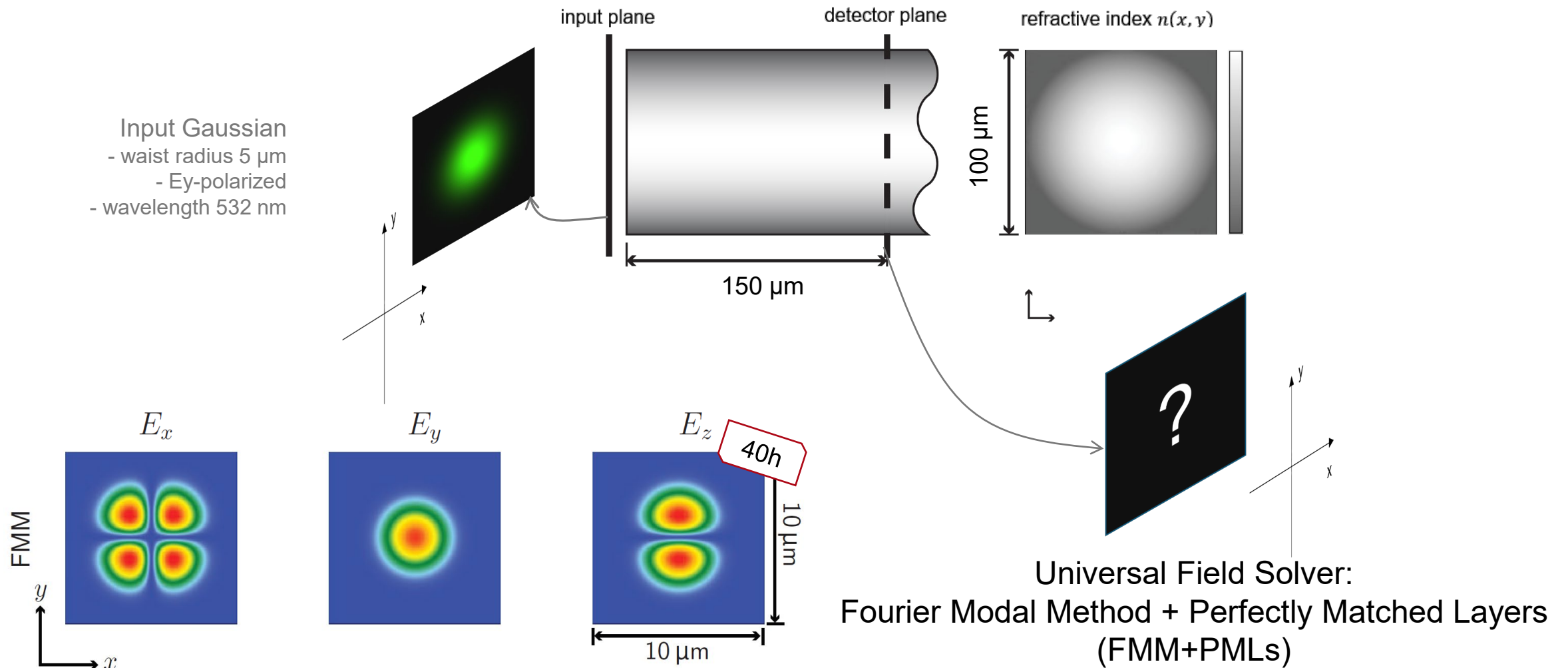


Example: Fiber

Input Gaussian
- waist radius $5\ \mu\text{m}$
- E_y -polarized
- wavelength $532\ \text{nm}$

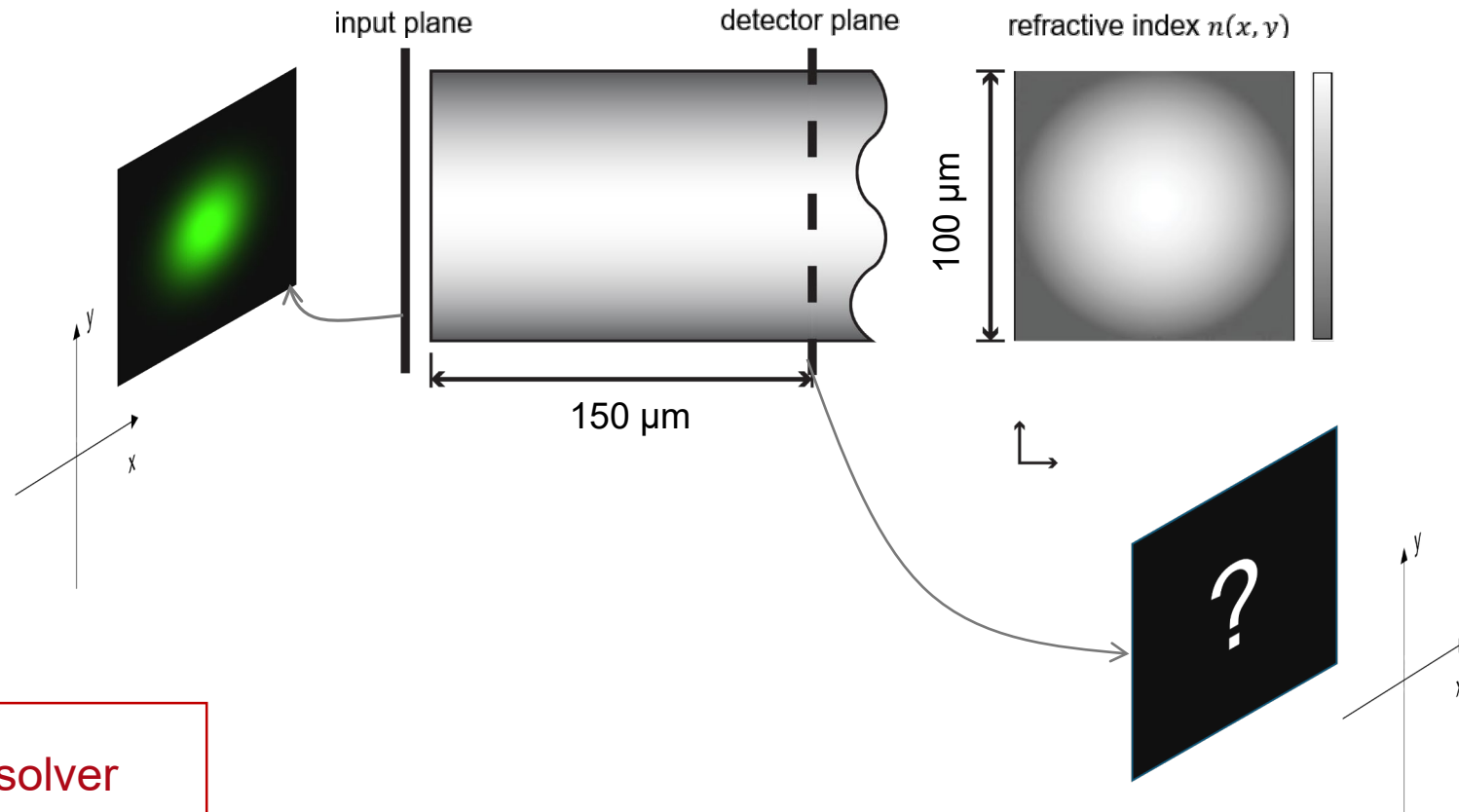


Fiber: Universal Field Solver



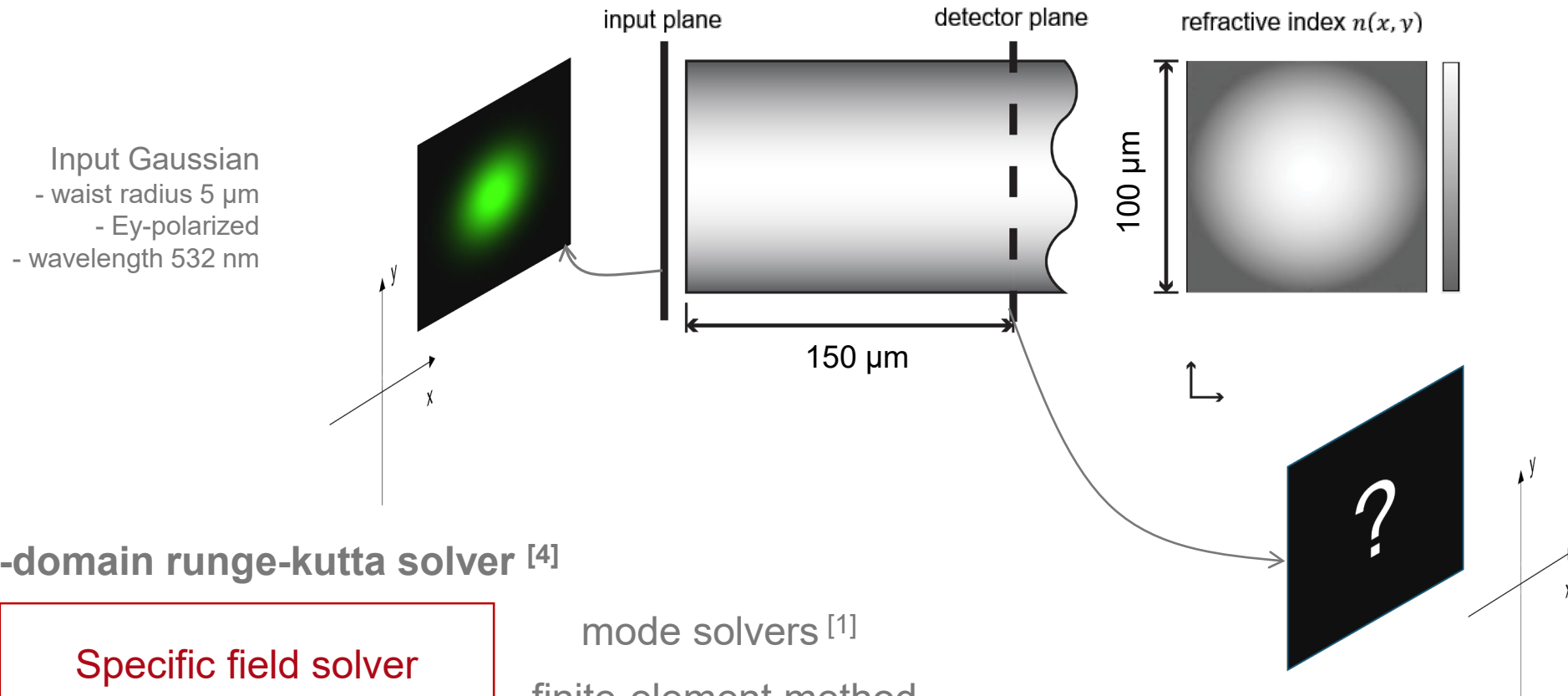
Fiber: Specific Field Solver

Input Gaussian
- waist radius $5\ \mu\text{m}$
- Ey-polarized
- wavelength $532\ \text{nm}$



Specific field solver

Fiber: Specific Field Solver



x-domain runge-kutta solver [4]

Specific field solver

wave propagation method [3]

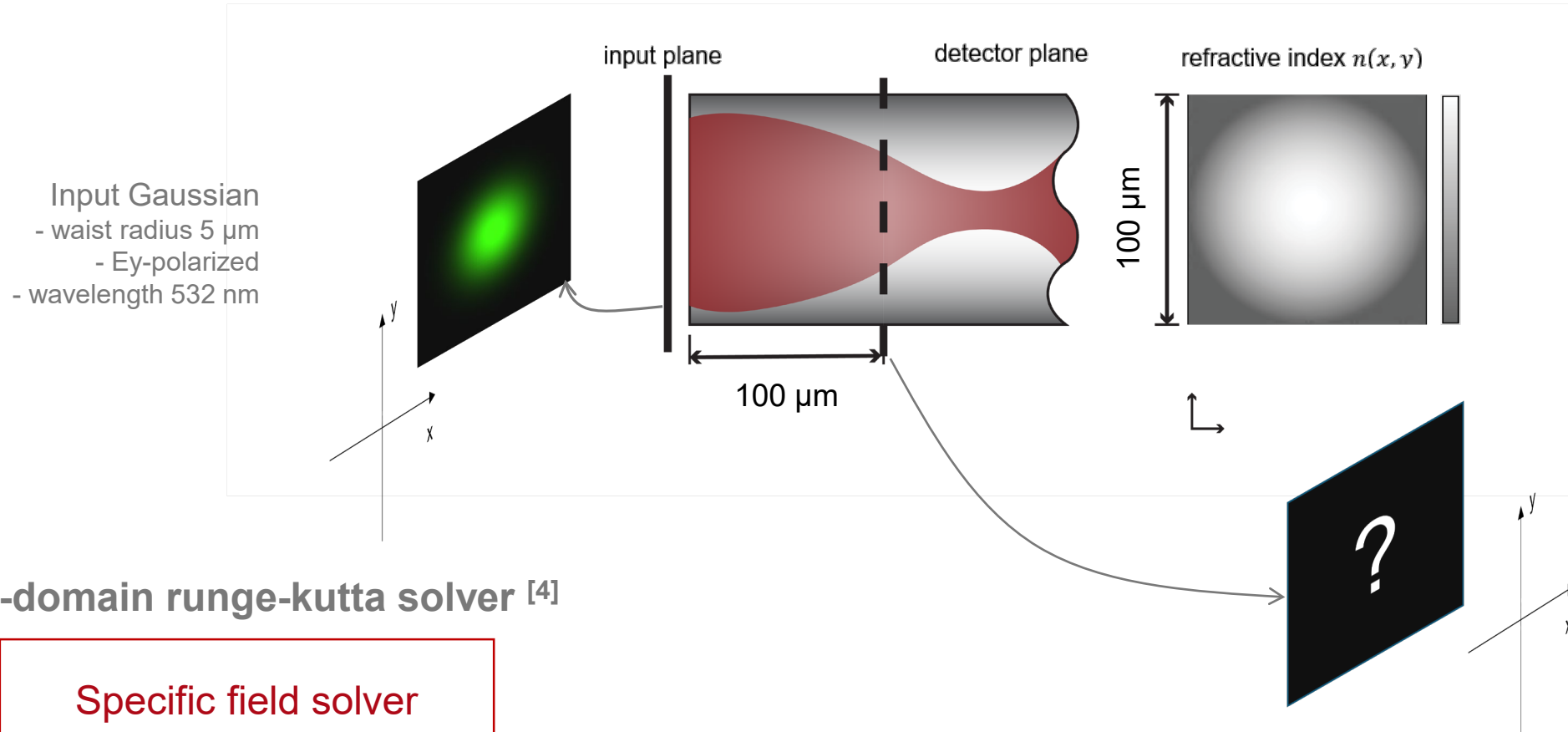
split-step methods [2]

mode solvers [1]

finite-element method
in cylindrical CS (JCM Wave)

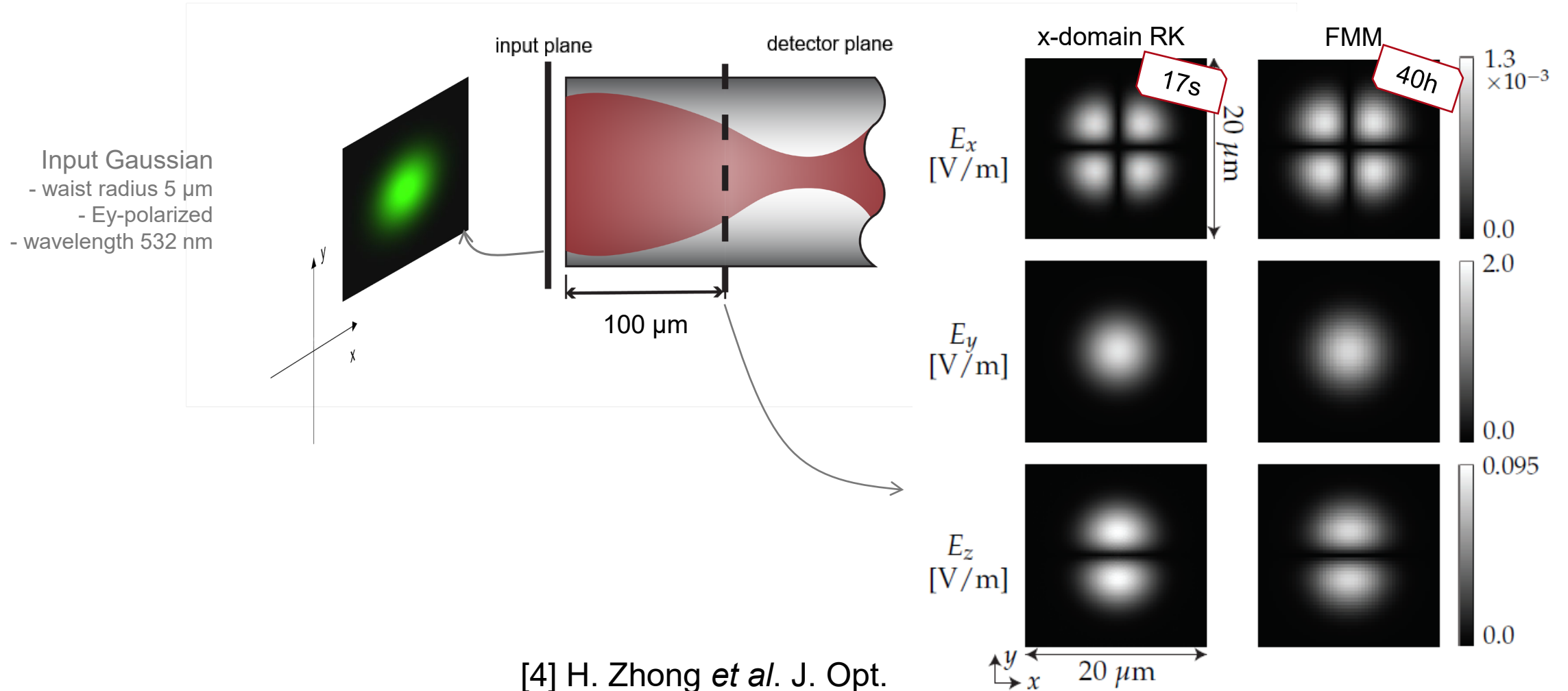
- [1] Kawano et al. Wiley (2004)
- [2] M.D. Feit et al. Appl. Opt. (1978)
- [3] Brenner et al. Appl. Opt. (1993)
- [4] H. Zhong et al. J. Opt. Soc. AM. A (2018)

Fiber: Specific Field Solver



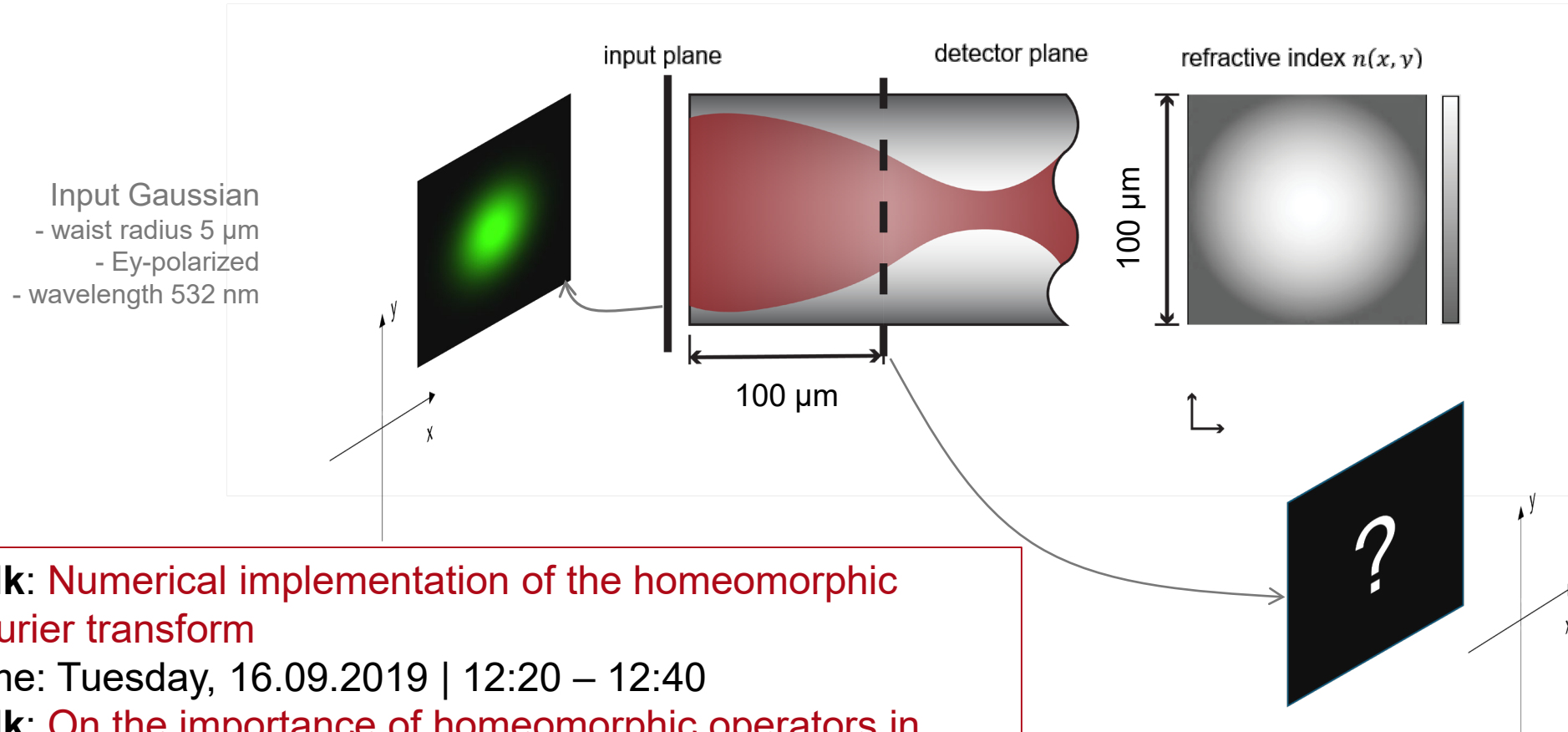
[4] H. Zhong *et al.* J. Opt. Soc. AM. A (2018)

Fiber: Specific Field Solver



[4] H. Zhong *et al.* J. Opt. Soc. AM. A (2018)

Fiber: Specific Field Solver



Talk: Numerical implementation of the homeomorphic Fourier transform

Time: Tuesday, 16.09.2019 | 12:20 – 12:40

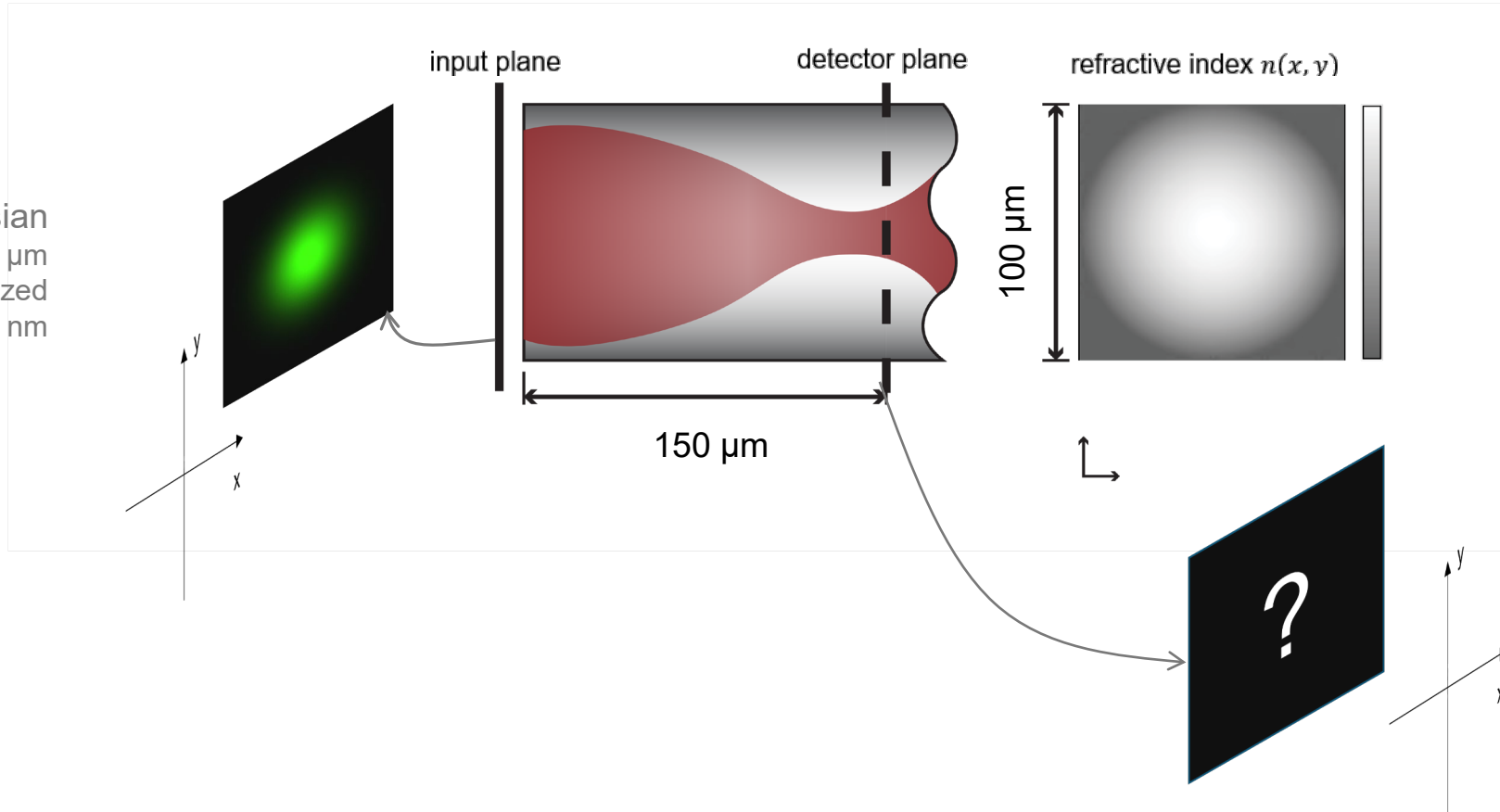
Talk: On the importance of homeomorphic operators in physical and geometrical optics

Time: Tuesday, 16.09.2019 | 14:30 – 14:50

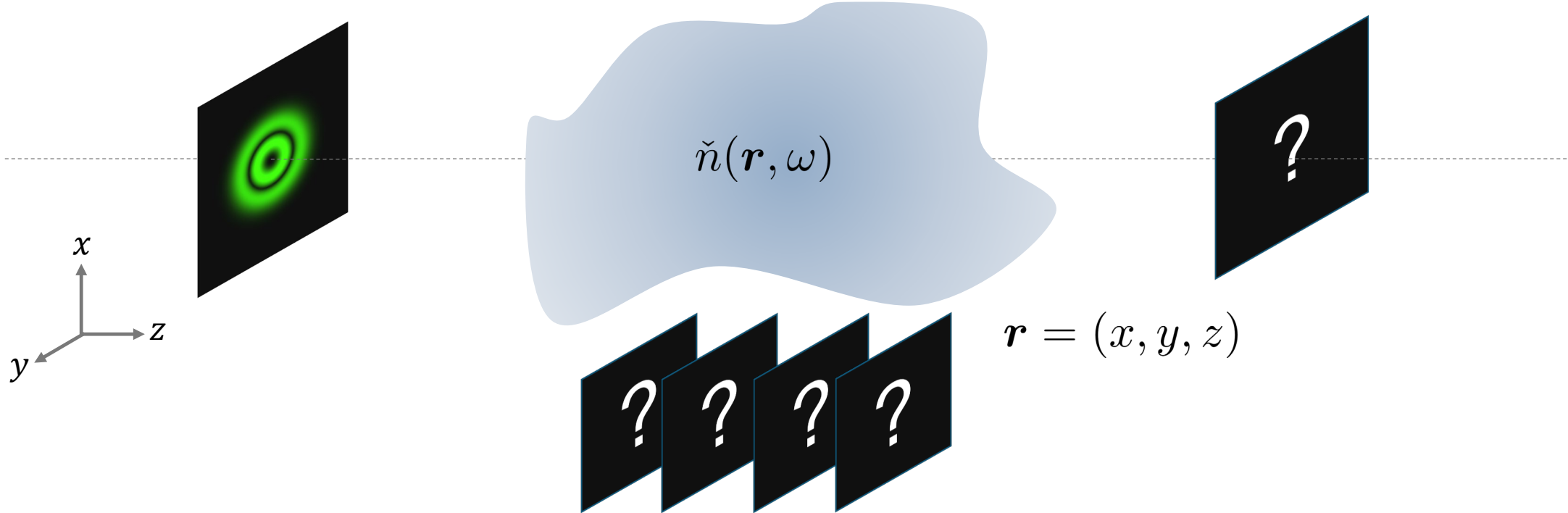
[4] H. Zhong *et al.* J. Opt. Soc. AM. A (2018)

Other Field Solver?

Input Gaussian
- waist radius $5\ \mu\text{m}$
- E_y -polarized
- wavelength $532\ \text{nm}$



Task Description



How to calculate an electromagnetic field propagation through graded-index media?

A K-Domain Method for Fast Propagation of Electromagnetic Fields through Graded-Index Media

Theory: Maxwell's Equations

$$\nabla \times \mathbf{E}(\mathbf{r}, \omega) = i\omega\mu_0\mathbf{H}(\mathbf{r}, \omega) \quad (1)$$

$$\nabla \times \mathbf{H}(\mathbf{r}, \omega) = -i\omega\epsilon(\mathbf{r}, \omega)\mathbf{E}(\mathbf{r}, \omega) \quad (2)$$

$$\epsilon(\mathbf{r}, \omega) = \tilde{n}^2(\mathbf{r}, \omega)$$

Now we define $\mathbf{V}(\mathbf{r}, \omega) = \{E_x, E_y, E_z, \sqrt{\frac{\mu_0}{\epsilon_0}}H_x, \sqrt{\frac{\mu_0}{\epsilon_0}}H_y, \sqrt{\frac{\mu_0}{\epsilon_0}}H_z\}^T(\mathbf{r}, \omega)$. Then Eqn. (1) and (2) can be rewritten as

$$\begin{pmatrix} \partial_y V_3(\mathbf{r}) - \partial_z V_2(\mathbf{r}) \\ \partial_z V_1(\mathbf{r}) - \partial_x V_3(\mathbf{r}) \\ \partial_x V_2(\mathbf{r}) - \partial_y V_1(\mathbf{r}) \end{pmatrix} = ik_0 \begin{pmatrix} V_4(\mathbf{r}) \\ V_5(\mathbf{r}) \\ V_6(\mathbf{r}) \end{pmatrix} \quad (3)$$

ω is skipped in notation.

$$\begin{pmatrix} \partial_y V_6(\mathbf{r}) - \partial_z V_5(\mathbf{r}) \\ \partial_z V_4(\mathbf{r}) - \partial_x V_6(\mathbf{r}) \\ \partial_x V_5(\mathbf{r}) - \partial_y V_4(\mathbf{r}) \end{pmatrix} = -ik_0\epsilon(\mathbf{r}) \begin{pmatrix} V_1(\mathbf{r}) \\ V_2(\mathbf{r}) \\ V_3(\mathbf{r}) \end{pmatrix} \quad (4)$$

Theory: Fourier Transform

$$\begin{pmatrix} \partial_y V_3(\mathbf{r}) - \partial_z V_2(\mathbf{r}) \\ \partial_z V_1(\mathbf{r}) - \partial_x V_3(\mathbf{r}) \\ \partial_x V_2(\mathbf{r}) - \partial_y V_1(\mathbf{r}) \end{pmatrix} = ik_0 \begin{pmatrix} V_4(\mathbf{r}) \\ V_5(\mathbf{r}) \\ V_6(\mathbf{r}) \end{pmatrix} \quad \begin{pmatrix} \partial_y V_6(\mathbf{r}) - \partial_z V_5(\mathbf{r}) \\ \partial_z V_4(\mathbf{r}) - \partial_x V_6(\mathbf{r}) \\ \partial_x V_5(\mathbf{r}) - \partial_y V_4(\mathbf{r}) \end{pmatrix} = -ik_0 \epsilon(\mathbf{r}) \begin{pmatrix} V_1(\mathbf{r}) \\ V_2(\mathbf{r}) \\ V_3(\mathbf{r}) \end{pmatrix} \quad (3-4)$$

In the plane z , we represent $V_\ell(\boldsymbol{\rho}, z)$ by inverse Fourier transform $\boldsymbol{\rho} = (x, y)$

$$V_\ell(\boldsymbol{\rho}, z) = \mathcal{F}_k^{-1} \tilde{V}_\ell(\boldsymbol{\kappa}, z) = \frac{1}{2\pi} \iint_{-\infty}^{+\infty} dk_x dk_y \tilde{V}_\ell(\boldsymbol{\kappa}, z) \exp(i\boldsymbol{\kappa} \cdot \boldsymbol{\rho}). \quad (5)$$

And substitute into Eqn. (3) and (4), i.e.,

$$\partial_x V_\ell(\boldsymbol{\rho}, z) = \frac{1}{2\pi} \iint_{-\infty}^{+\infty} dk_x dk_y i\kappa_x \tilde{V}_\ell(\boldsymbol{\kappa}, z) \exp(i\boldsymbol{\kappa} \cdot \boldsymbol{\rho})$$

and

$$\partial_y V_\ell(\boldsymbol{\rho}, z) = \frac{1}{2\pi} \iint_{-\infty}^{+\infty} dk_x dk_y i\kappa_y \tilde{V}_\ell(\boldsymbol{\kappa}, z) \exp(i\boldsymbol{\kappa} \cdot \boldsymbol{\rho})$$

Theory: K-Domain Formulation

$$\begin{pmatrix} \partial_y V_3(\mathbf{r}) - \partial_z V_2(\mathbf{r}) \\ \partial_z V_1(\mathbf{r}) - \partial_x V_3(\mathbf{r}) \\ \partial_x V_2(\mathbf{r}) - \partial_y V_1(\mathbf{r}) \end{pmatrix} = ik_0 \begin{pmatrix} V_4(\mathbf{r}) \\ V_5(\mathbf{r}) \\ V_6(\mathbf{r}) \end{pmatrix} \quad \begin{pmatrix} \partial_y V_6(\mathbf{r}) - \partial_z V_5(\mathbf{r}) \\ \partial_z V_4(\mathbf{r}) - \partial_x V_6(\mathbf{r}) \\ \partial_x V_5(\mathbf{r}) - \partial_y V_4(\mathbf{r}) \end{pmatrix} = -ik_0 \epsilon(\mathbf{r}) \begin{pmatrix} V_1(\mathbf{r}) \\ V_2(\mathbf{r}) \\ V_3(\mathbf{r}) \end{pmatrix} \quad (3-4)$$

Eqn. (3) and (4) become

$$\begin{pmatrix} i\kappa_y \tilde{V}_3(\boldsymbol{\kappa}, z) - \partial_z \tilde{V}_2(\boldsymbol{\kappa}, z) \\ \partial_z \tilde{V}_1(\boldsymbol{\kappa}, z) - i\kappa_x \tilde{V}_3(\boldsymbol{\kappa}, z) \\ i\kappa_x \tilde{V}_2(\boldsymbol{\kappa}, z) - i\kappa_y \tilde{V}_1(\boldsymbol{\kappa}, z) \end{pmatrix} = ik_0 \begin{pmatrix} \tilde{V}_4(\boldsymbol{\kappa}, z) \\ \tilde{V}_5(\boldsymbol{\kappa}, z) \\ \tilde{V}_6(\boldsymbol{\kappa}, z) \end{pmatrix}$$

and

$$\begin{pmatrix} i\kappa_y \tilde{V}_6(\boldsymbol{\kappa}, z) - \partial_z \tilde{V}_5(\boldsymbol{\kappa}, z) \\ \partial_z \tilde{V}_4(\boldsymbol{\kappa}, z) - i\kappa_x \tilde{V}_6(\boldsymbol{\kappa}, z) \\ i\kappa_x \tilde{V}_5(\boldsymbol{\kappa}, z) - i\kappa_y \tilde{V}_4(\boldsymbol{\kappa}, z) \end{pmatrix} = -ik_0 \tilde{\epsilon}(\boldsymbol{\kappa}, z) * \begin{pmatrix} \tilde{V}_1(\boldsymbol{\kappa}, z) \\ \tilde{V}_2(\boldsymbol{\kappa}, z) \\ \tilde{V}_3(\boldsymbol{\kappa}, z) \end{pmatrix}$$

$$\partial_z \Rightarrow \frac{d}{dz}$$

Theory: K-Domain Formulation

$$\begin{pmatrix} \partial_y V_3(\mathbf{r}) - \partial_z V_2(\mathbf{r}) \\ \partial_z V_1(\mathbf{r}) - \partial_x V_3(\mathbf{r}) \\ \partial_x V_2(\mathbf{r}) - \partial_y V_1(\mathbf{r}) \end{pmatrix} = ik_0 \begin{pmatrix} V_4(\mathbf{r}) \\ V_5(\mathbf{r}) \\ V_6(\mathbf{r}) \end{pmatrix} \quad \begin{pmatrix} \partial_y V_6(\mathbf{r}) - \partial_z V_5(\mathbf{r}) \\ \partial_z V_4(\mathbf{r}) - \partial_x V_6(\mathbf{r}) \\ \partial_x V_5(\mathbf{r}) - \partial_y V_4(\mathbf{r}) \end{pmatrix} = -ik_0 \epsilon(\mathbf{r}) \begin{pmatrix} V_1(\mathbf{r}) \\ V_2(\mathbf{r}) \\ V_3(\mathbf{r}) \end{pmatrix} \quad (3-4)$$

Eqn. (3) and (4) become

$$\begin{pmatrix} i\kappa_y \tilde{V}_3(\boldsymbol{\kappa}, z) - \frac{d\tilde{V}_2}{dz}(\boldsymbol{\kappa}, z) \\ \frac{d\tilde{V}_1}{dz}(\boldsymbol{\kappa}, z) - i\kappa_x \tilde{V}_3(\boldsymbol{\kappa}, z) \\ i\kappa_x \tilde{V}_2(\boldsymbol{\kappa}, z) - i\kappa_y \tilde{V}_1(\boldsymbol{\kappa}, z) \end{pmatrix} = ik_0 \begin{pmatrix} \tilde{V}_4(\boldsymbol{\kappa}, z) \\ \tilde{V}_5(\boldsymbol{\kappa}, z) \\ \tilde{V}_6(\boldsymbol{\kappa}, z) \end{pmatrix} \quad (5)$$

and

$$\begin{pmatrix} i\kappa_y \tilde{V}_6(\boldsymbol{\kappa}, z) - \frac{d\tilde{V}_5}{dz}(\boldsymbol{\kappa}, z) \\ \frac{d\tilde{V}_4}{dz}(\boldsymbol{\kappa}, z) - i\kappa_x \tilde{V}_6(\boldsymbol{\kappa}, z) \\ i\kappa_x \tilde{V}_5(\boldsymbol{\kappa}, z) - i\kappa_y \tilde{V}_4(\boldsymbol{\kappa}, z) \end{pmatrix} = -ik_0 \tilde{\epsilon}(\boldsymbol{\kappa}, z) * \begin{pmatrix} \tilde{V}_1(\boldsymbol{\kappa}, z) \\ \tilde{V}_2(\boldsymbol{\kappa}, z) \\ \tilde{V}_3(\boldsymbol{\kappa}, z) \end{pmatrix} \quad (6)$$

Theory: ODE in K-Domain

$$\frac{d}{dz} \tilde{\mathbf{V}}_{\perp} = \mathbf{f}(z, \tilde{\mathbf{V}}_{\perp})$$

$$\frac{d}{dz} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z) = ik_0 \begin{bmatrix} 0 & 0 & \frac{k_x}{k_0} \tilde{\underline{\epsilon}}^{-1} \frac{k_y}{k_0} & 1 - \frac{k_x}{k_0} \tilde{\underline{\epsilon}}^{-1} \frac{k_x}{k_0} \\ 0 & 0 & \frac{k_y}{k_0} \tilde{\underline{\epsilon}}^{-1} \frac{k_y}{k_0} - 1 & -\frac{k_y}{k_0} \tilde{\underline{\epsilon}}^{-1} \frac{k_x}{k_0} \\ -\frac{k_x k_y}{k_0^2} & \frac{k_x^2}{k_0^2} - \tilde{\underline{\epsilon}} & 0 & 0 \\ \tilde{\underline{\epsilon}} - \frac{k_y^2}{k_0^2} & \frac{k_y k_x}{k_0^2} & 0 & 0 \end{bmatrix} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z) \quad (7)$$

$\tilde{\underline{\epsilon}}$ and $\tilde{\underline{\epsilon}}^{-1}$ are the convolution operator. More specifically, $\tilde{\underline{\epsilon}} = \tilde{\epsilon}*$ and $\tilde{\underline{\epsilon}}^{-1} = \epsilon^{-1}*$

Mathematical task:

Solving the ordinary differential equation (ODE) (7), field propagation through media with $\tilde{n}(\mathbf{r})$ is calculated!

[5] Popov et al. J. Opt. Soc. Am. A(2001)

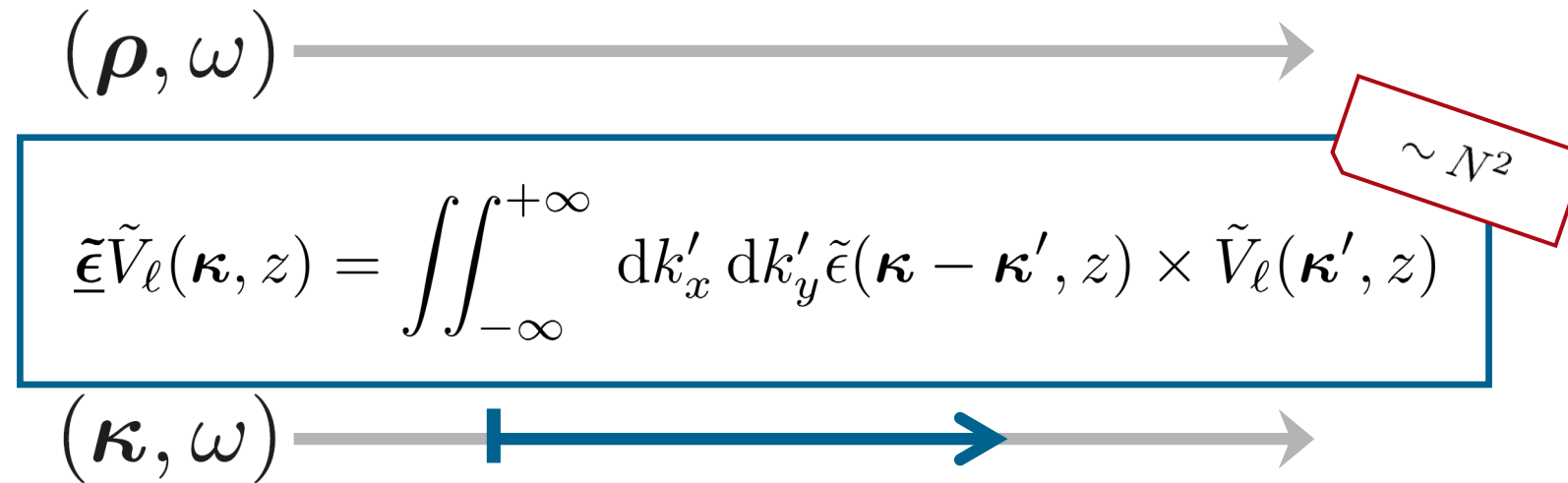
Theory: Solve the ODE

$$\frac{d}{dz} \tilde{\mathbf{V}}_{\perp} = \mathbf{f}(z, \tilde{\mathbf{V}}_{\perp})$$

$$\frac{d}{dz} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z) = ik_0 \begin{bmatrix} 0 & 0 & \frac{k_x}{k_0} \tilde{\underline{\epsilon}}^{-1} \frac{k_y}{k_0} & 1 - \frac{k_x}{k_0} \tilde{\underline{\epsilon}}^{-1} \frac{k_x}{k_0} \\ 0 & 0 & \frac{k_y}{k_0} \tilde{\underline{\epsilon}}^{-1} \frac{k_y}{k_0} & -1 - \frac{k_y}{k_0} \tilde{\underline{\epsilon}}^{-1} \frac{k_x}{k_0} \\ -\frac{k_x k_y}{k_0^2} & \frac{k_x^2}{k_0^2} - \tilde{\underline{\epsilon}} & 0 & 0 \\ \tilde{\underline{\epsilon}} - \frac{k_y^2}{k_0^2} & \frac{k_y k_x}{k_0^2} & 0 & 0 \end{bmatrix} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z)$$

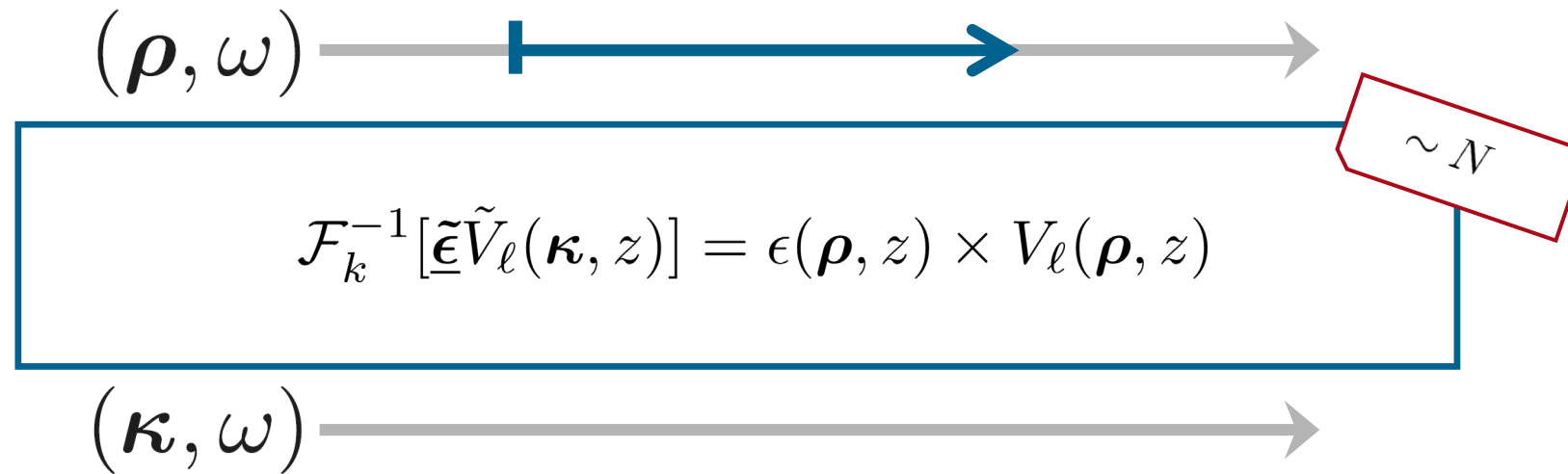
How to deal with operator $\tilde{\underline{\epsilon}}$ and $\tilde{\underline{\epsilon}}^{-1}$?

Convolution Operator: Domain Diagram

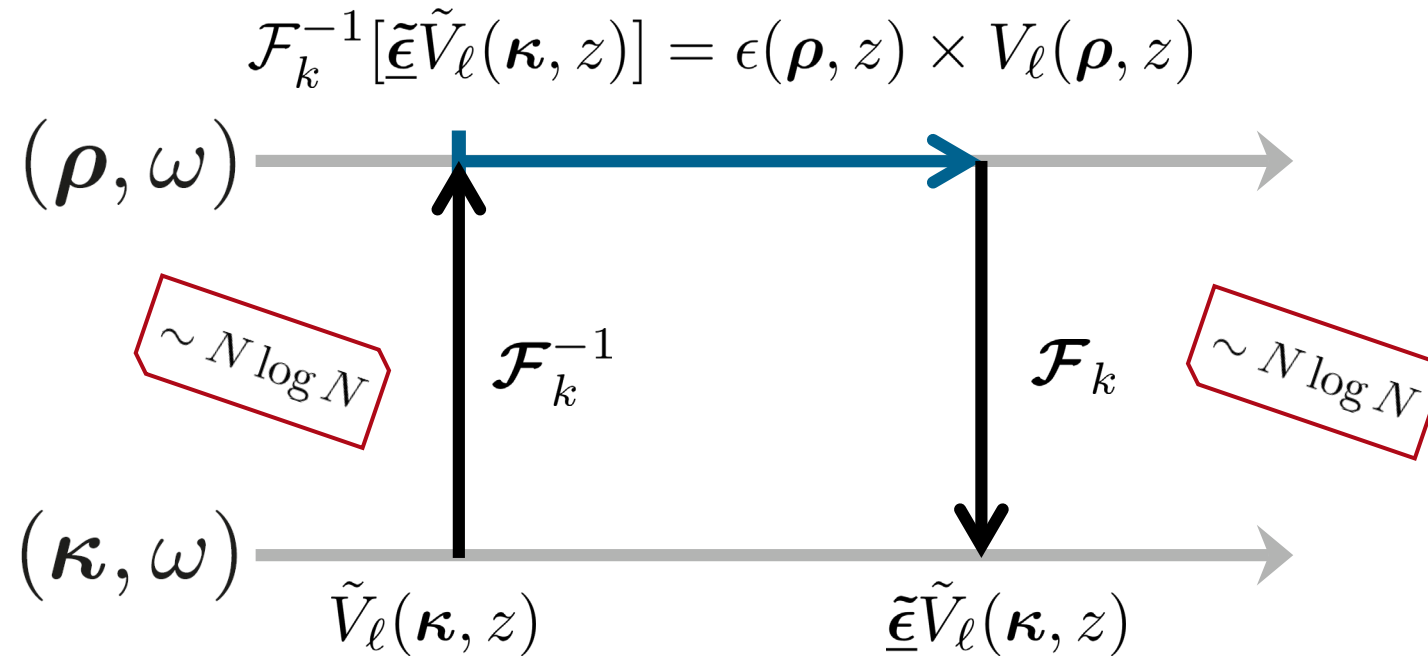


N is number of
sampling points

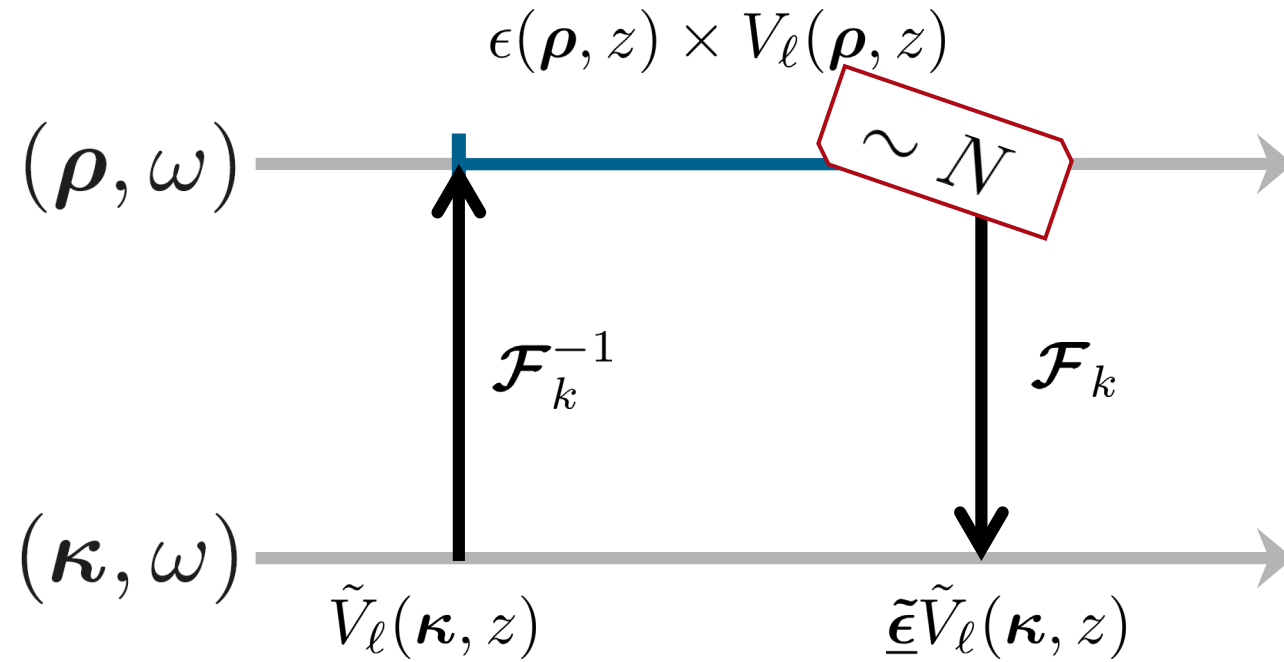
Convolution Operator: Convolution Theorem



Convolution Operator: Domain Diagram



Convolution Operator: Domain Diagram

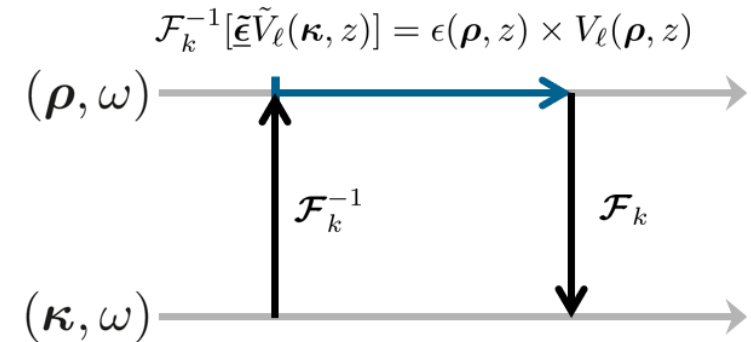


Theory: Convolution Operator

$$\frac{d}{dz} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z) = ik_0 \begin{bmatrix} 0 & 0 & \frac{k_x}{k_0} \tilde{\underline{\epsilon}}^{-1} \frac{k_y}{k_0} & 1 - \frac{k_x}{k_0} \tilde{\underline{\epsilon}}^{-1} \frac{k_x}{k_0} \\ 0 & 0 & \frac{k_y}{k_0} \tilde{\underline{\epsilon}}^{-1} \frac{k_y}{k_0} & -1 - \frac{k_y}{k_0} \tilde{\underline{\epsilon}}^{-1} \frac{k_x}{k_0} \\ -\frac{k_x k_y}{k_0^2} & \frac{k_x^2}{k_0^2} - \tilde{\underline{\epsilon}} & 0 & 0 \\ \tilde{\underline{\epsilon}} - \frac{k_y^2}{k_0^2} & \frac{k_y k_x}{k_0^2} & 0 & 0 \end{bmatrix} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z)$$

$$\tilde{\underline{\epsilon}} \tilde{V}_\ell(\boldsymbol{\kappa}, z) = \mathcal{F}_k \left\{ \epsilon(\boldsymbol{\rho}, z) \times \mathcal{F}_k^{-1} \left[\tilde{V}_\ell(\boldsymbol{\kappa}, z) \right] \right\}$$

$$\tilde{\underline{\epsilon}}^{-1} \kappa_j \tilde{V}_\ell(\boldsymbol{\kappa}, z) = \mathcal{F}_k \left\{ \epsilon^{-1}(\boldsymbol{\rho}, z) \times \mathcal{F}_k^{-1} \left[\kappa_j \tilde{V}_\ell(\boldsymbol{\kappa}, z) \right] \right\}$$



[2] S. Sheng *et al.* Phys. Rev. A (1980)

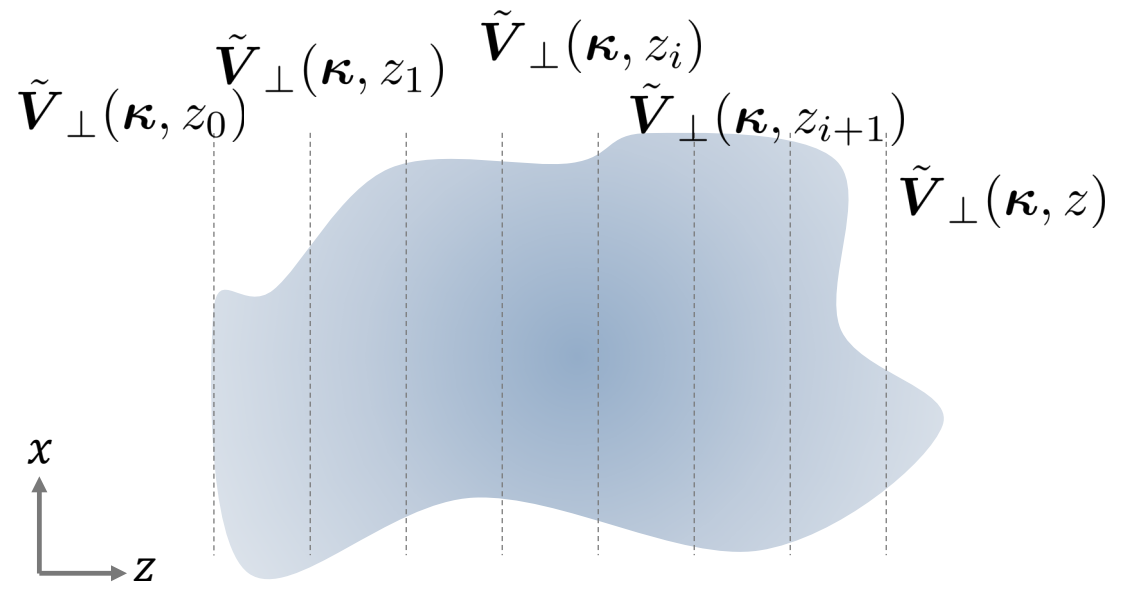
Theory: Solve the ODE

$$\frac{d}{dz} \tilde{\mathbf{V}}_{\perp} = \mathbf{f}(z, \tilde{\mathbf{V}}_{\perp})$$

$$\frac{d}{dz} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z) = ik_0 \begin{bmatrix} 0 & 0 & \frac{k_x}{k_0} \tilde{\epsilon}^{-1} \frac{k_y}{k_0} & 1 - \frac{k_x}{k_0} \tilde{\epsilon}^{-1} \frac{k_x}{k_0} \\ 0 & 0 & \frac{k_y}{k_0} \tilde{\epsilon}^{-1} \frac{k_y}{k_0} & -1 - \frac{k_y}{k_0} \tilde{\epsilon}^{-1} \frac{k_x}{k_0} \\ -\frac{k_x k_y}{k_0^2} & \frac{k_x^2}{k_0^2} - \tilde{\epsilon} & 0 & 0 \\ \tilde{\epsilon} - \frac{k_y^2}{k_0^2} & \frac{k_y k_x}{k_0^2} & 0 & 0 \end{bmatrix} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z)$$

ODE solver (initial value problem)

- Euler method
- Taylor series methods
- Runge-Kutta methods
- ...



Initial Value: Approximation

$$\frac{d}{dz} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z) = ik_0 \begin{bmatrix} 0 & 0 & \frac{k_x}{k_0} \tilde{\epsilon}^{-1} \frac{k_y}{k_0} & 1 - \frac{k_x}{k_0} \tilde{\epsilon}^{-1} \frac{k_x}{k_0} \\ 0 & 0 & \frac{k_y}{k_0} \tilde{\epsilon}^{-1} \frac{k_y}{k_0} & -1 - \frac{k_y}{k_0} \tilde{\epsilon}^{-1} \frac{k_x}{k_0} \\ -\frac{k_x k_y}{k_0^2} & \frac{k_x^2}{k_0^2} - \tilde{\epsilon} & 0 & 0 \\ \tilde{\epsilon} - \frac{k_y^2}{k_0^2} & \frac{k_y k_x}{k_0^2} & 0 & 0 \end{bmatrix} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z)$$

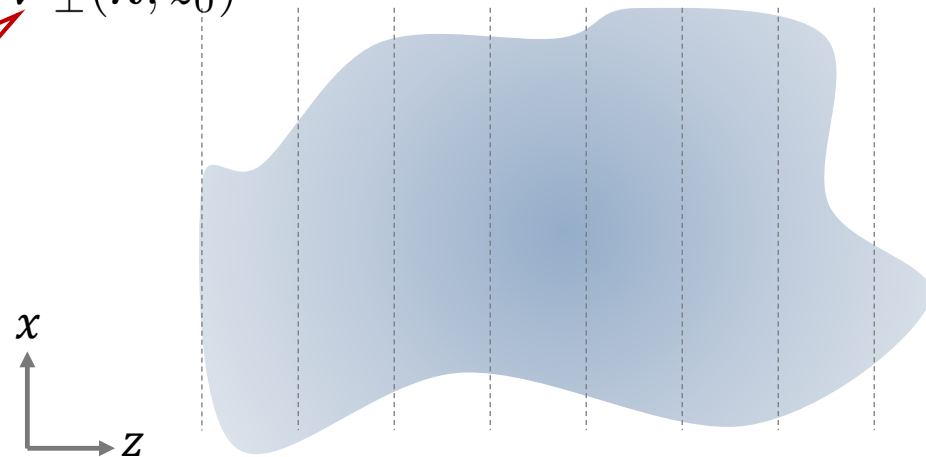
ODE solver (initial value problem)

Approximation:

Our initial field just contains forward propagation part

→ reflected field is not predicted

$\tilde{V}_\perp(\boldsymbol{\kappa}, z_0)$



Theory: Solve the ODE

$$\frac{d}{dz} \tilde{\mathbf{V}}_{\perp}^{\text{EM}} = \mathbf{f}(z, \tilde{\mathbf{V}}_{\perp}^{\text{EM}})$$

$$\frac{d}{dz} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z) = ik_0 \begin{bmatrix} 0 & 0 & \frac{k_x}{k_0} \tilde{\epsilon}^{-1} \frac{k_y}{k_0} & 1 - \frac{k_x}{k_0} \tilde{\epsilon}^{-1} \frac{k_x}{k_0} \\ 0 & 0 & \frac{k_y}{k_0} \tilde{\epsilon}^{-1} \frac{k_y}{k_0} & -1 - \frac{k_y}{k_0} \tilde{\epsilon}^{-1} \frac{k_x}{k_0} \\ -\frac{k_x k_y}{k_0^2} & \frac{k_x^2}{k_0^2} - \tilde{\epsilon} & 0 & 0 \\ \tilde{\epsilon} - \frac{k_y^2}{k_0^2} & \frac{k_y k_x}{k_0^2} & 0 & 0 \end{bmatrix} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z)$$

Calculate $\tilde{\mathbf{V}}_{\perp}(\boldsymbol{\kappa}, z_{i+1})$ from $\tilde{\mathbf{V}}_{\perp}(\boldsymbol{\kappa}, z_i)$

ODE solver (initial value problem)

- Euler method
- Taylor series methods
- Runge-Kutta methods
- ...

$$\begin{aligned} \mathbf{k}_1 &= \Delta z_i \mathbf{f}(z_i, \tilde{\mathbf{V}}_{\perp}(\boldsymbol{\kappa}, z_i)) \\ \mathbf{k}_2 &= \Delta z_i \mathbf{f}\left(z_i + \frac{1}{2} \Delta z_i, \tilde{\mathbf{V}}_{\perp}(\boldsymbol{\kappa}, z_i) + \frac{1}{2} \mathbf{k}_1\right) \\ \mathbf{k}_3 &= \Delta z_i \mathbf{f}\left(z_i + \frac{1}{2} \Delta z_i, \tilde{\mathbf{V}}_{\perp}(\boldsymbol{\kappa}, z_i) + \frac{1}{2} \mathbf{k}_2\right) \\ \mathbf{k}_4 &= \Delta z_i \mathbf{f}\left(z_{i+1}, \tilde{\mathbf{V}}_{\perp}(\boldsymbol{\kappa}, z_i) + \frac{1}{2} \mathbf{k}_3\right) \\ \tilde{\mathbf{V}}_{\perp}(\boldsymbol{\kappa}, z_{i+1}) &= \tilde{\mathbf{V}}_{\perp}(\boldsymbol{\kappa}, z_i) + \frac{1}{6} (\mathbf{k}_1 + 2\mathbf{k}_2 + 2\mathbf{k}_3 + \mathbf{k}_4) \end{aligned}$$

Theory: Solve the ODE

$$\frac{d}{dz} \tilde{\mathbf{V}}_{\perp}^{\text{EM}} = \mathbf{f}(z, \tilde{\mathbf{V}}_{\perp}^{\text{EM}})$$

$$\frac{d}{dz} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z) = ik_0 \begin{bmatrix} 0 & 0 & \frac{k_x}{k_0} \tilde{\epsilon}^{-1} \frac{k_y}{k_0} & 1 - \frac{k_x}{k_0} \tilde{\epsilon}^{-1} \frac{k_x}{k_0} \\ 0 & 0 & \frac{k_y}{k_0} \tilde{\epsilon}^{-1} \frac{k_y}{k_0} & -1 - \frac{k_y}{k_0} \tilde{\epsilon}^{-1} \frac{k_x}{k_0} \\ -\frac{k_x k_y}{k_0^2} & \frac{k_x^2}{k_0^2} - \tilde{\epsilon} & 0 & 0 \\ \tilde{\epsilon} - \frac{k_y^2}{k_0^2} & \frac{k_y k_x}{k_0^2} & 0 & 0 \end{bmatrix} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z)$$

Calculate $\tilde{\mathbf{V}}_{\perp}(\boldsymbol{\kappa}, z_{i+1})$ from $\tilde{\mathbf{V}}_{\perp}(\boldsymbol{\kappa}, z_i)$

ODE solver (initial value problem)

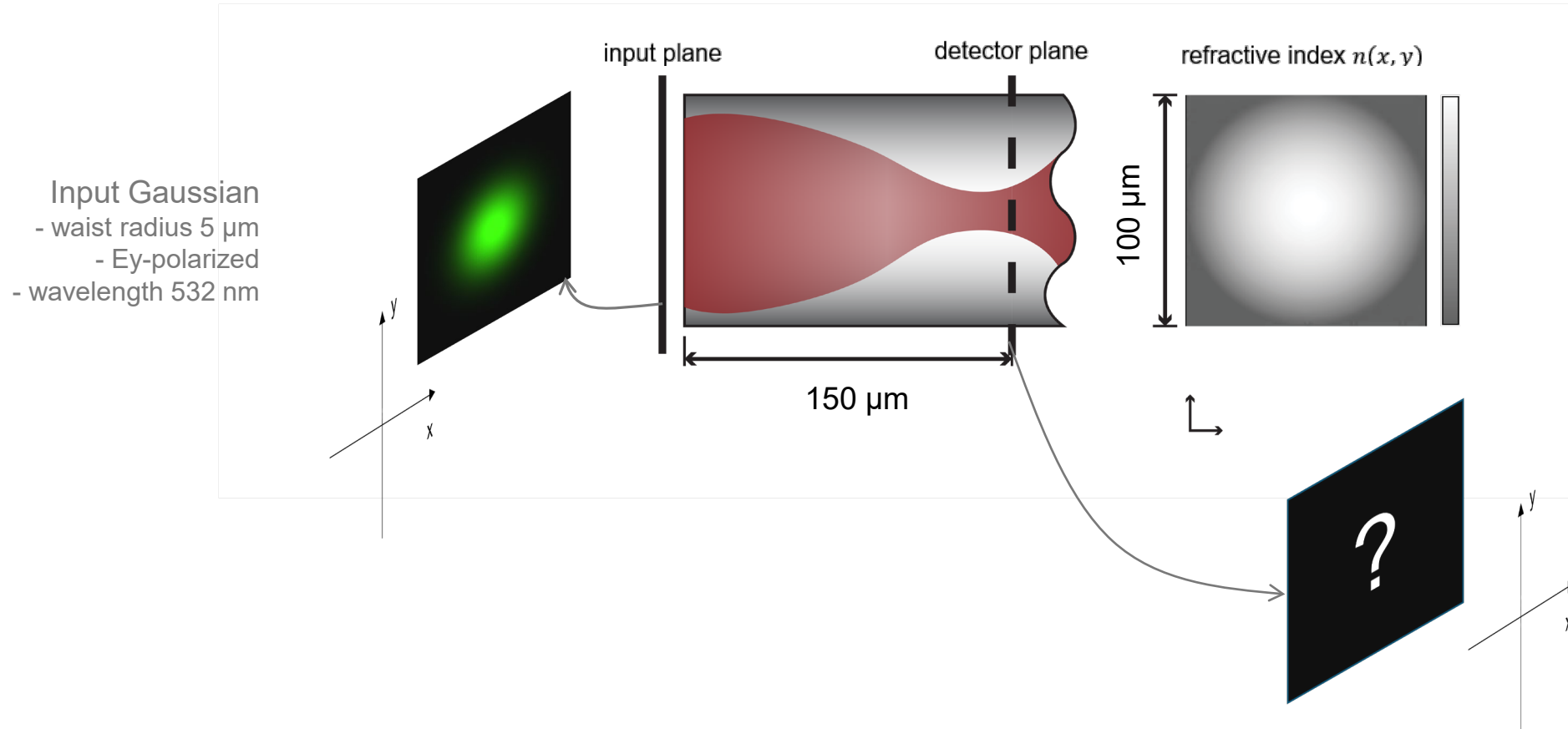
- Euler method
- Taylor series methods
- Runge-Kutta methods
- ...

$$\mathbf{k}_1 = \Delta z_i \mathbf{f}(z_i, \tilde{\mathbf{V}}_{\perp}(\boldsymbol{\kappa}, z_i))$$

$$\mathbf{k}_2 = \Delta z_i \mathbf{f}\left(z_i + \frac{1}{2} \Delta z_i, \tilde{\mathbf{V}}_{\perp}(\boldsymbol{\kappa}, z_i) + \frac{1}{2} \mathbf{k}_1\right)$$

We name the k -domain method as Runge-Kutta k -domain algorithm.

Example: Fiber

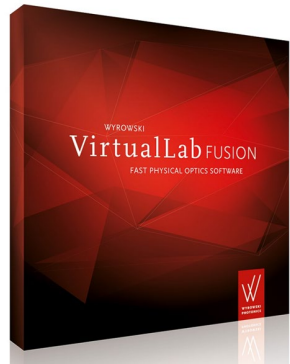
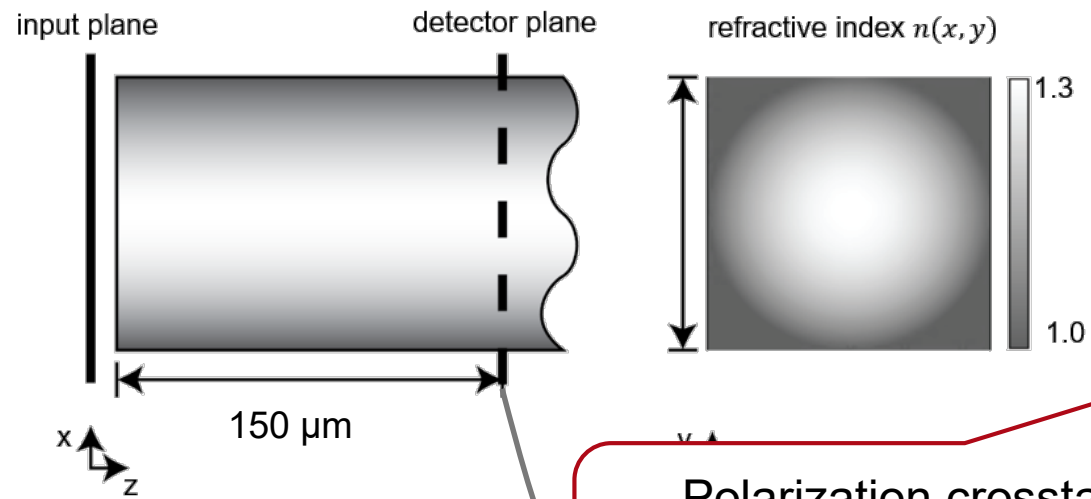


calculate the result fields by Fourier modal method and Runge-Kutta based k-domain algorithm.

Result: Amplitude [V/m] of Output Field

$\sim N \times N_z$

$\sim N^3$



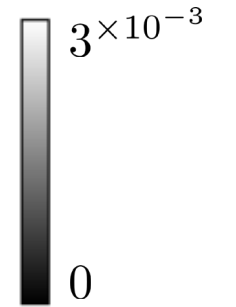
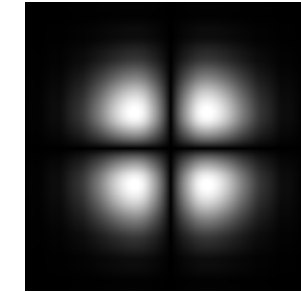
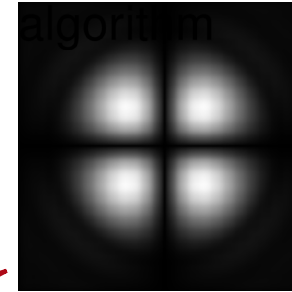
Implemented by using
programmable plug-in component in
VirtualLab Fusion

Polarization crosstalk
between field components is
included

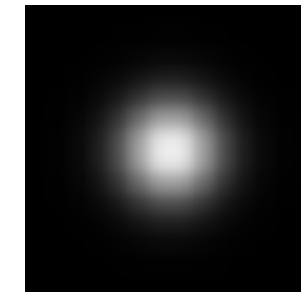
RK k -domain
algorithm

FMM

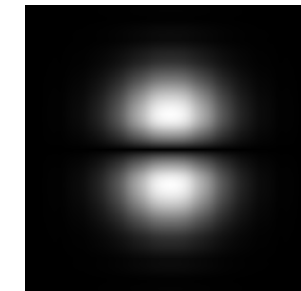
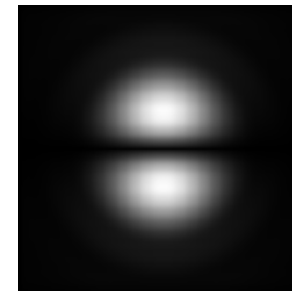
E_x



E_y



E_z

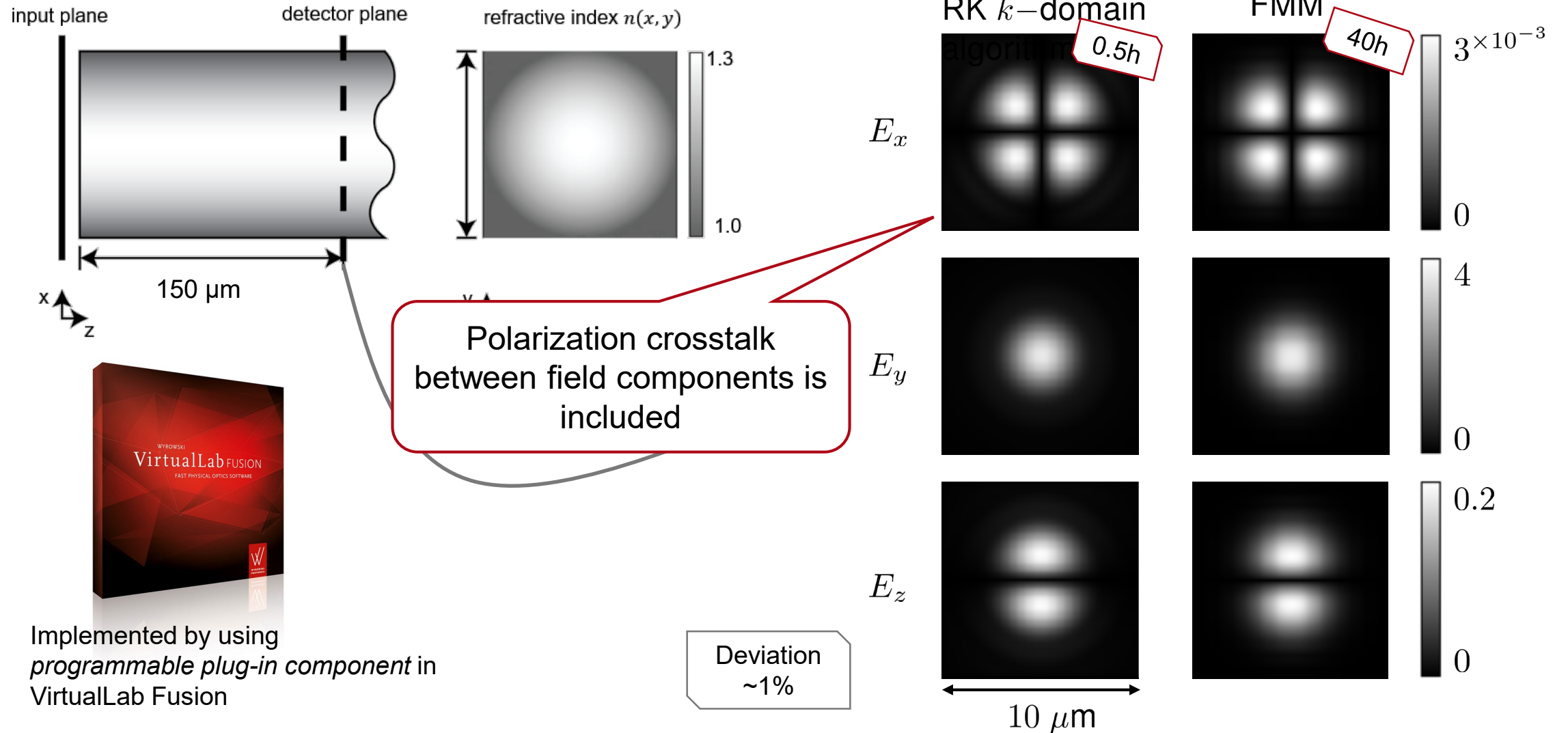


10 μm

Result: Amplitude [V/m] of Output Field

$\sim N \times N_z$

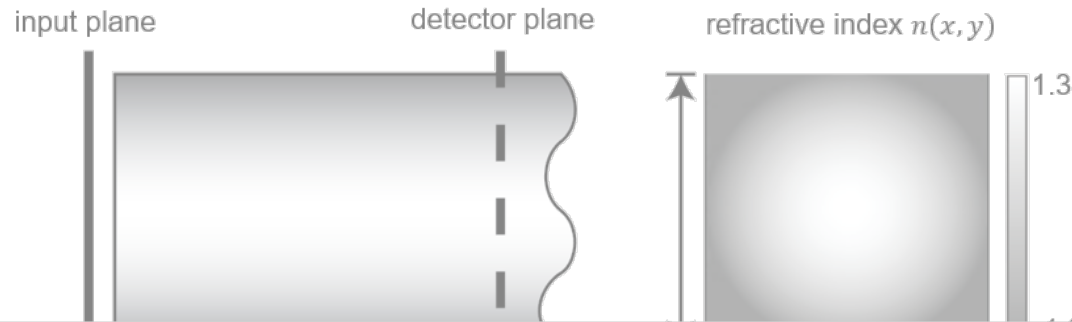
$\sim N^3$



Result: Amplitude [V/m] of Output Field

$\sim N \times N_z$

$\sim N^3$



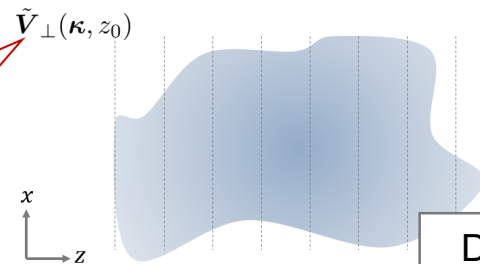
Initial Value: Approximation

$$\frac{d}{dz} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z) = ik_0 \begin{bmatrix} 0 & 0 & \frac{k_x}{k_0} \tilde{\epsilon}^{-1} \frac{k_y}{k_0} & 1 - \frac{k_x}{k_0} \tilde{\epsilon}^{-1} \frac{k_x}{k_0} \\ 0 & 0 & \frac{k_y}{k_0} \tilde{\epsilon}^{-1} \frac{k_y}{k_0} - 1 & -\frac{k_y}{k_0} \tilde{\epsilon}^{-1} \frac{k_x}{k_0} \\ -\frac{k_x k_y}{k_0^2} & \frac{k_x^2}{k_0^2} - \tilde{\epsilon} & 0 & 0 \\ \tilde{\epsilon} - \frac{k_y^2}{k_0^2} & \frac{k_y k_x}{k_0^2} & 0 & 0 \end{bmatrix} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z)$$

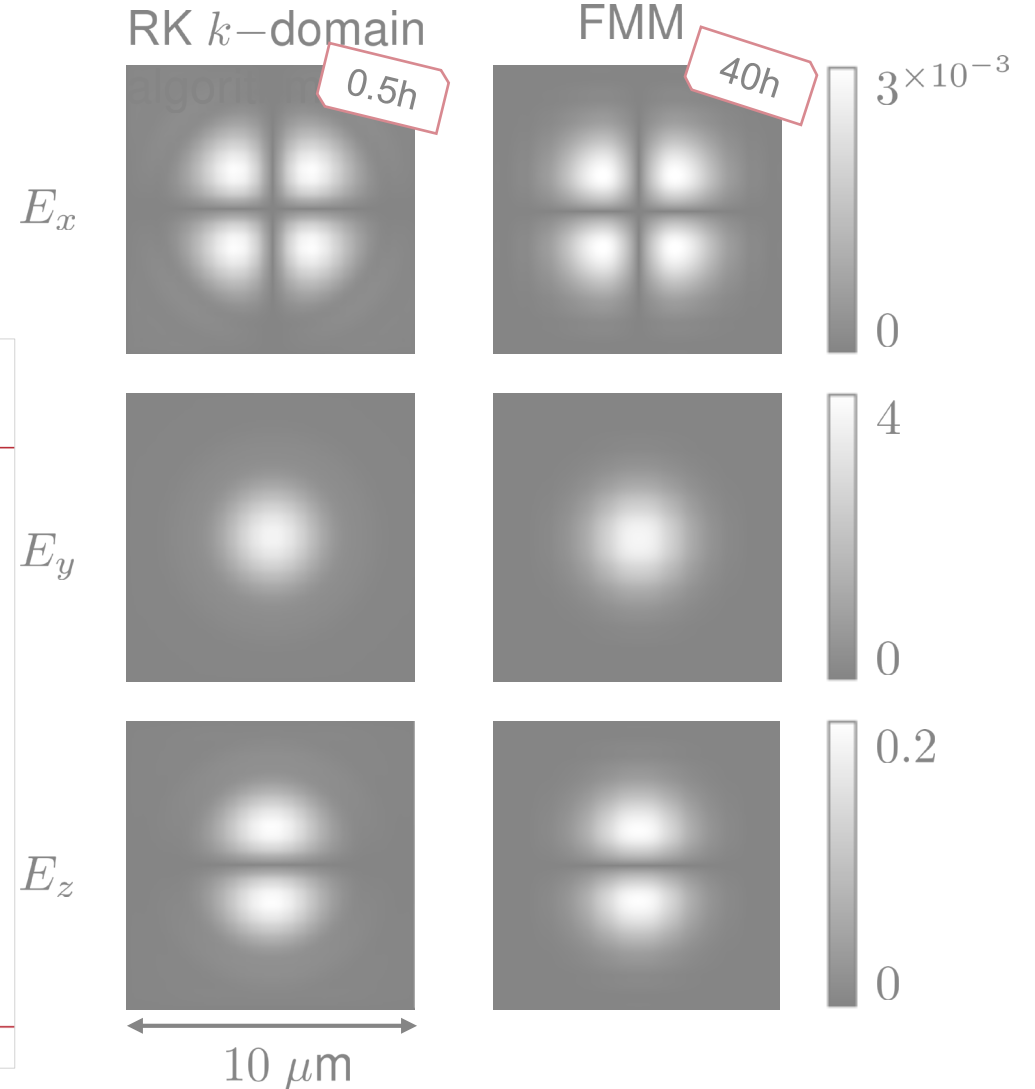
ODE solver (initial value problem)

Approximation:

Our initial field just contains forward propagation part
 → reflected field is not predicted



Deviation
 $\sim 1\%$



Two-Dimensional Case

Theory: ODE for y – Invariant Condition

$$\partial_y = 0$$

$$\frac{d}{dz} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z) = ik_0 \begin{bmatrix} 0 & 0 & 0 & 1 - \frac{k_x}{k_0} \tilde{\boldsymbol{\epsilon}}^{-1} \frac{k_x}{k_0} \\ 0 & 0 & -1 & 0 \\ 0 & \frac{k_x^2}{k_0^2} - \tilde{\boldsymbol{\epsilon}} & 0 & 0 \\ \tilde{\boldsymbol{\epsilon}} & 0 & 0 & 0 \end{bmatrix} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z) \quad (8)$$

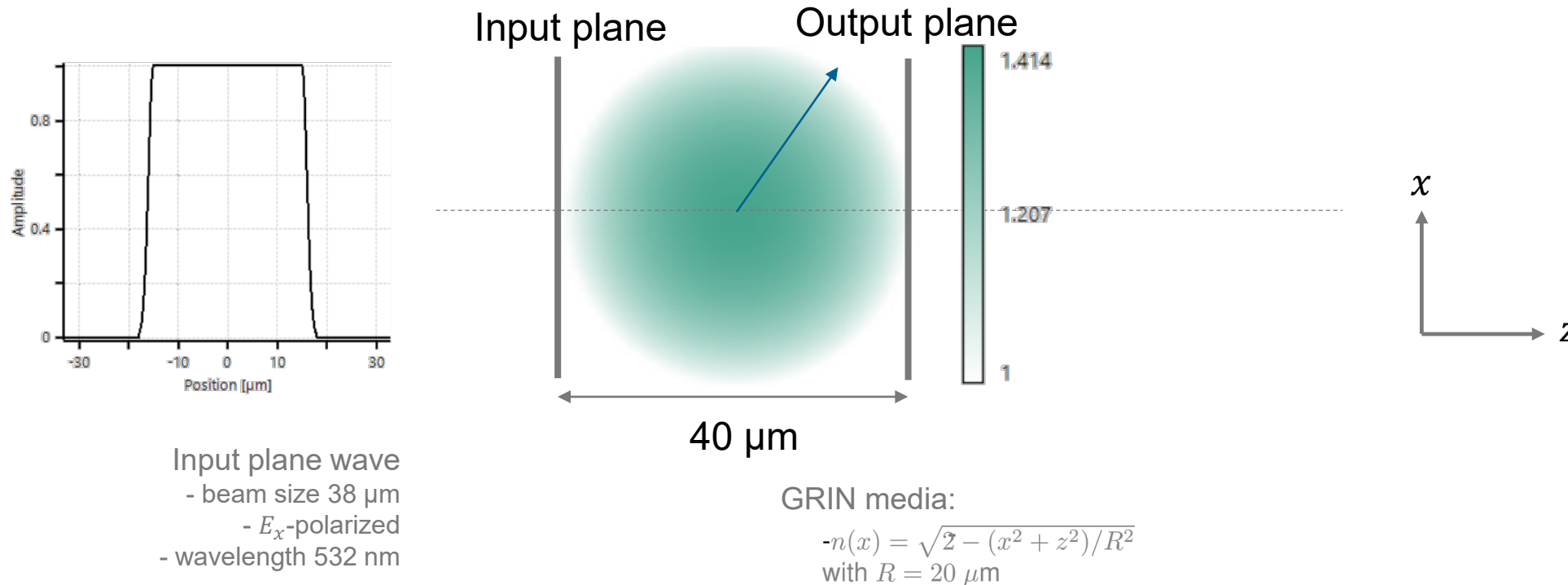
TE

$$\frac{d}{dz} \begin{pmatrix} \tilde{V}_2 \\ \tilde{V}_4 \end{pmatrix} (\boldsymbol{\kappa}, z) = ik_0 \begin{bmatrix} 0 & -1 \\ \frac{k_x^2}{k_0^2} - \tilde{\boldsymbol{\epsilon}} & 0 \end{bmatrix} \begin{pmatrix} \tilde{V}_2 \\ \tilde{V}_4 \end{pmatrix} (\boldsymbol{\kappa}, z) \quad (9)$$

TM

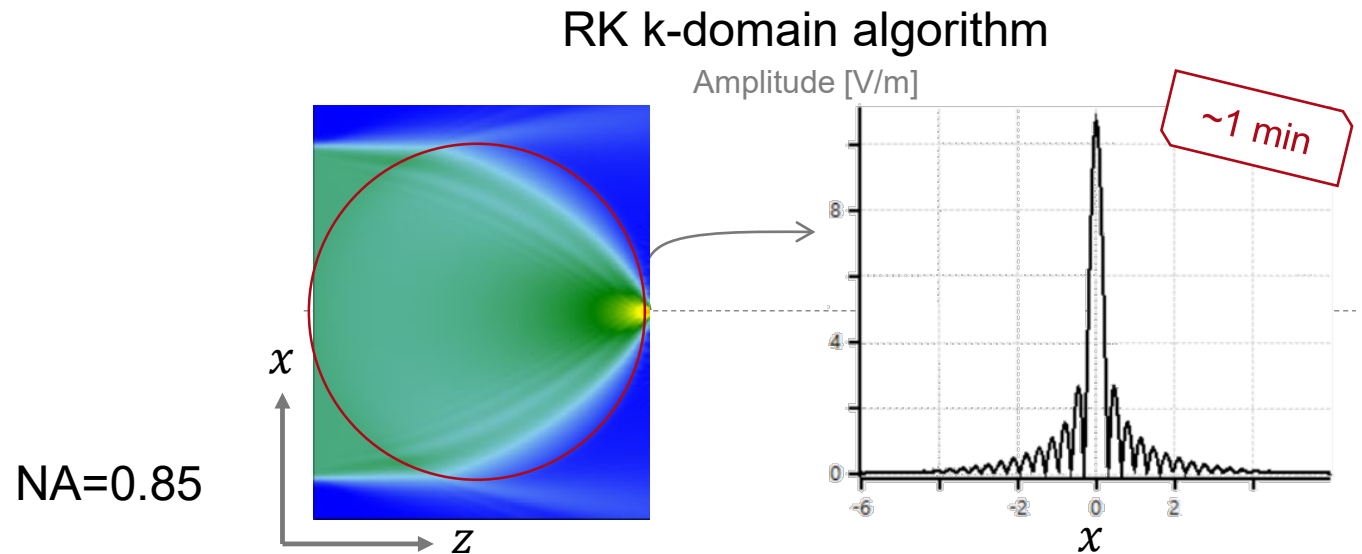
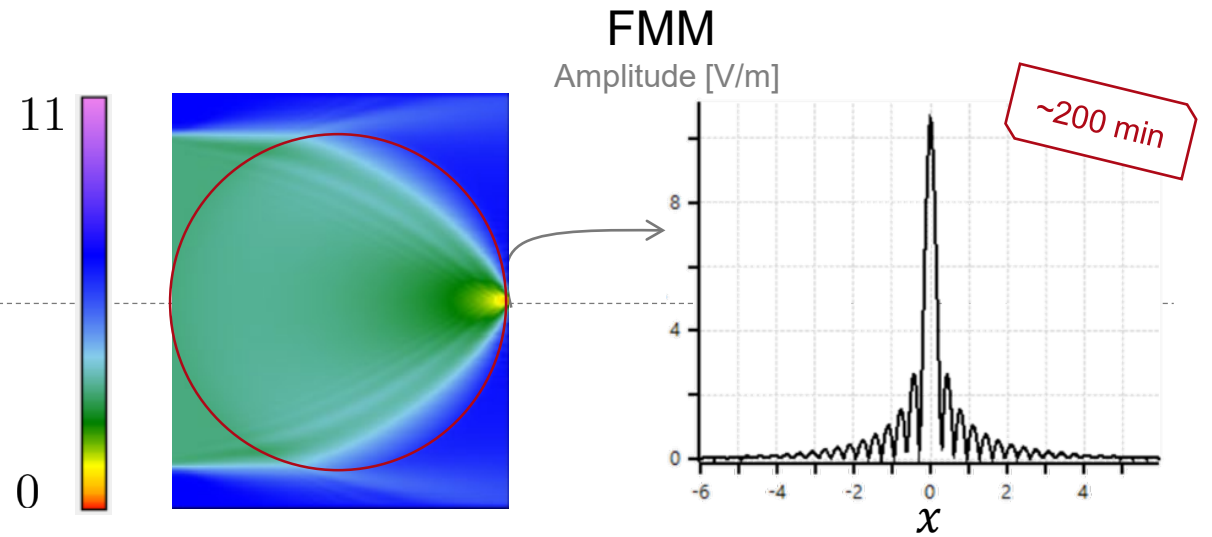
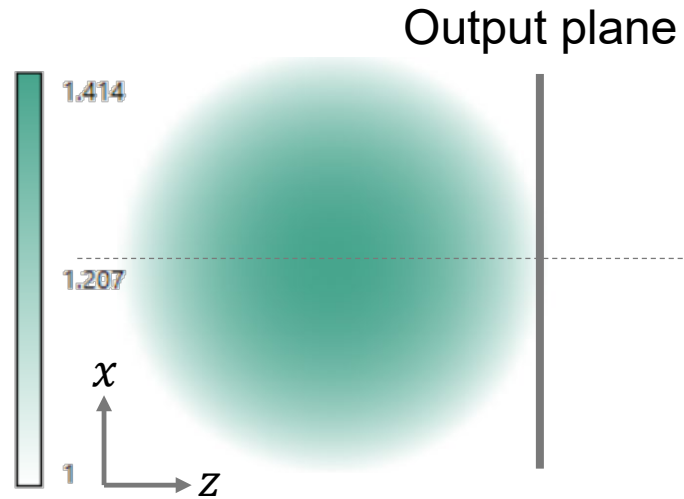
$$\frac{d}{dz} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z) = ik_0 \begin{bmatrix} 0 & 1 - \frac{k_x}{k_0} \tilde{\boldsymbol{\epsilon}}^{-1} \frac{k_x}{k_0} \\ \tilde{\boldsymbol{\epsilon}} & 0 \end{bmatrix} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z) \quad (10)$$

Y-Invariant GRIN Media: Luneburg Cylinder Lens

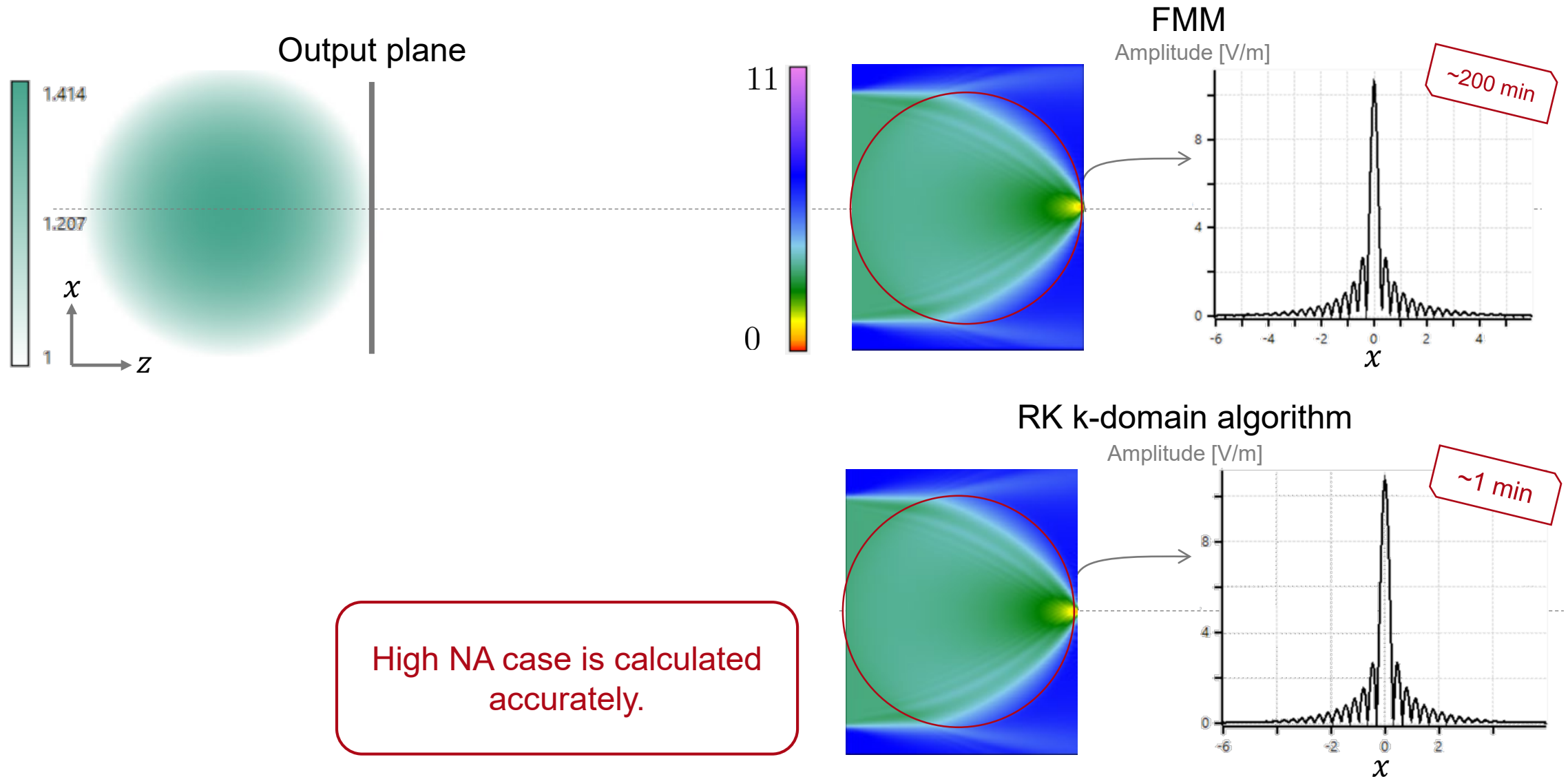


- Task: By using FMM (rigorous) and the RK k-domain algorithm
- calculate field propagation in GRIN media xz –plane
 - calculate field in the output plane

Result: Amplitude of E_x –Field



Result: Amplitude of E_x –Field

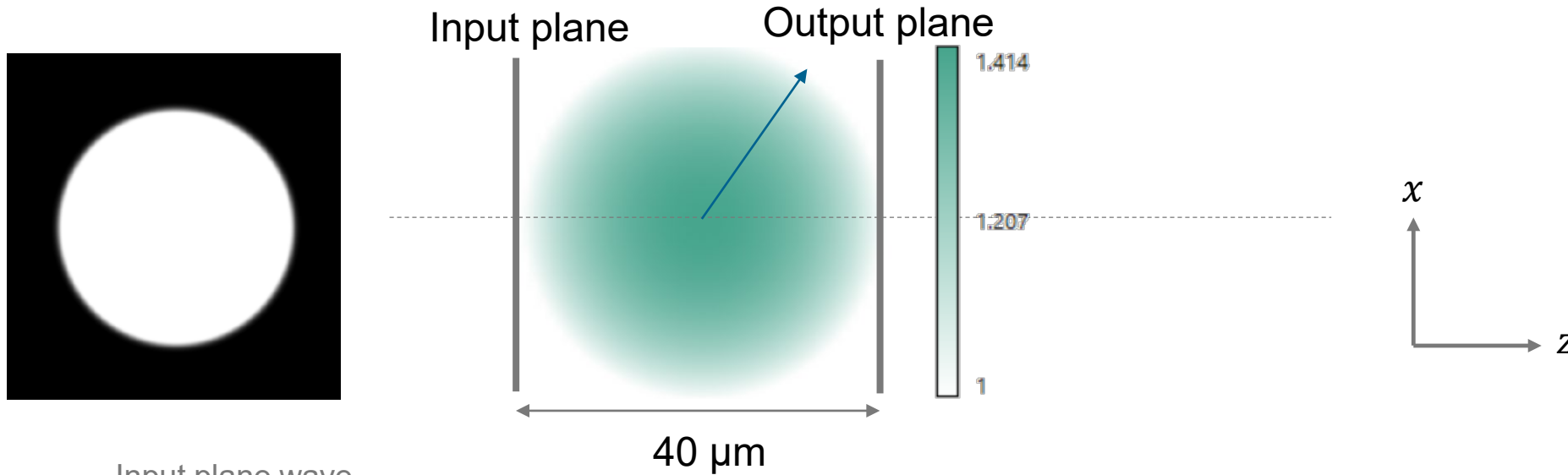


Three-Dimensional Case

3D Case

$$\frac{d}{dz} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z) = ik_0 \begin{bmatrix} 0 & 0 & \frac{k_x}{k_0} \tilde{\boldsymbol{\epsilon}}^{-1} \frac{k_y}{k_0} & 1 - \frac{k_x}{k_0} \tilde{\boldsymbol{\epsilon}}^{-1} \frac{k_x}{k_0} \\ 0 & 0 & \frac{k_y}{k_0} \tilde{\boldsymbol{\epsilon}}^{-1} \frac{k_y}{k_0} - 1 & -\frac{k_y}{k_0} \tilde{\boldsymbol{\epsilon}}^{-1} \frac{k_x}{k_0} \\ -\frac{k_x k_y}{k_0^2} & \frac{k_x^2}{k_0^2} - \tilde{\boldsymbol{\epsilon}} & 0 & 0 \\ \tilde{\boldsymbol{\epsilon}} - \frac{k_y^2}{k_0^2} & \frac{k_y k_x}{k_0^2} & 0 & 0 \end{bmatrix} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z)$$

3D Case: Luneburg Lens



Input plane wave
- beam size $38 \mu\text{m}$
- E_x -polarized
- wavelength 532 nm

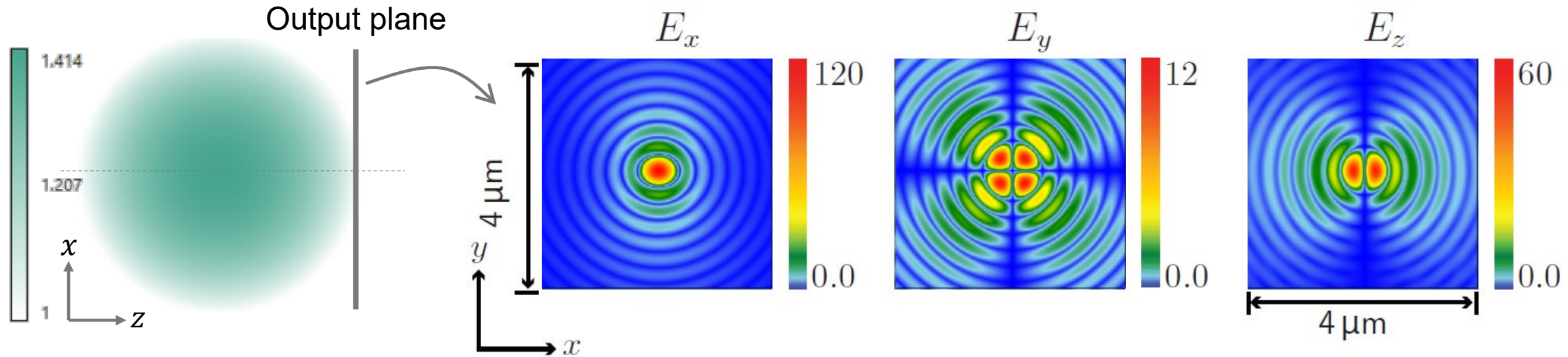
GRIN media:

$$-n(x) = \sqrt{2 - (x^2 + y^2 + z^2)/R^2}$$

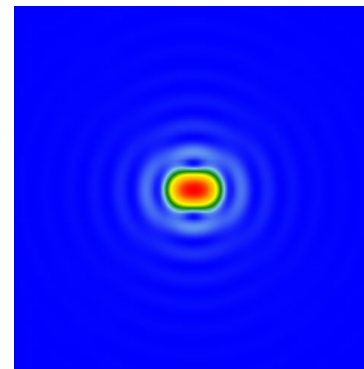
with $R = 20 \mu\text{m}$

Task: RK k-domain algorithm
- calculate field in the output plane

Result: Amplitude and Energy Density of Electric Fields



energy density



Too much numerical effort
for FMM.

$$\sim |E_x|^2 + |E_y|^2 + |E_z|^2$$

Conclusion

- Develop a fast k-domain algorithm to calculate field propagation through graded-index media

- Maxwell's equations to derive ODE

$$\frac{d}{dz} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z) = ik_0 \begin{bmatrix} 0 & 0 & \frac{k_x}{k_0} \tilde{\epsilon}^{-1} \frac{k_y}{k_0} & 1 - \frac{k_x}{k_0} \tilde{\epsilon}^{-1} \frac{k_x}{k_0} \\ 0 & 0 & \frac{k_y}{k_0} \tilde{\epsilon}^{-1} \frac{k_y}{k_0} - 1 & -\frac{k_y}{k_0} \tilde{\epsilon}^{-1} \frac{k_x}{k_0} \\ -\frac{k_x k_y}{k_0^2} & \frac{k_x^2}{k_0^2} - \tilde{\epsilon} & 0 & 0 \\ \tilde{\epsilon} - \frac{k_y^2}{k_0^2} & \frac{k_y k_x}{k_0^2} & 0 & 0 \end{bmatrix} \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \\ \tilde{V}_4 \\ \tilde{V}_5 \end{pmatrix} (\boldsymbol{\kappa}, z)$$

- Solving this ODE by Runge-Kutta method (4th order) slice by slice along z –axis
- By using convolution theorem, convolution in k-domain is realized by multiplication in spatial domain. So numerical effort of this algorithm $\sim N \times N_z$, with N is sampling points of field and N_z denoting slice number
- Still missing: reflection

Outlook: Further Tricks of Solver

- We rewrite $\tilde{\mathbf{V}}_{\perp} = \tilde{\mathbf{U}}_{\perp} \exp(ik_0 \bar{n} z)$, which abstract the fast changing term of field, ODE becomes

$$\frac{d}{dz} \begin{pmatrix} \tilde{U}_1 \\ \tilde{U}_2 \\ \tilde{U}_4 \\ \tilde{U}_5 \end{pmatrix} (\boldsymbol{\kappa}, z) = ik_0 \begin{bmatrix} -\bar{n} & 0 & \frac{k_x}{k_0} \tilde{\epsilon}^{-1} \frac{k_y}{k_0} & 1 - \frac{k_x}{k_0} \tilde{\epsilon}^{-1} \frac{k_x}{k_0} \\ 0 & -\bar{n} & \frac{k_y}{k_0} \tilde{\epsilon}^{-1} \frac{k_y}{k_0} - 1 & -\frac{k_y}{k_0} \tilde{\epsilon}^{-1} \frac{k_x}{k_0} \\ -\frac{k_x k_y}{k_0^2} & \frac{k_x^2}{k_0^2} - \tilde{\epsilon} & -\bar{n} & 0 \\ \tilde{\epsilon} - \frac{k_y^2}{k_0^2} & \frac{k_y k_x}{k_0^2} & 0 & -\bar{n} \end{bmatrix} \begin{pmatrix} \tilde{U}_1 \\ \tilde{U}_2 \\ \tilde{U}_4 \\ \tilde{U}_5 \end{pmatrix} (\boldsymbol{\kappa}, z)$$

Slow varying term \mathbf{U}_{\perp} is calculated, so N_z can be reduced

- In general case, $\tilde{\mathbf{V}}_{\perp} = \tilde{\mathbf{U}}_{\perp} \exp(i\tilde{\phi})$ or $\mathbf{V}_{\perp} = \mathbf{U}_{\perp} \exp(i\psi)$. We need to explore how to predict $\tilde{\psi}$ or ψ and how to perform Fourier transform fast! N reduced.

Thank you!

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